Burkhard Vogel



How to Gain



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A Reference Book on Triodes in Audio Pre-Amps



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To all valve enthusiasts

"A valve and a piece of wire - and the whole stuff will play!"

My friend Otto, 1971 after a valve amp crash

"Math is for solid-state; poetry is for tube audio"1

Tube Cad Journal, Nov. 2004

"God doesn't play at dice"

Albert Einstein

1

Worth reading: "Science versus subjectivism in audio engineering", Douglas Self, Electronics & Wireless World, July 1988, p. 692 ff

Preface

The today's (2008) audio (or low-frequency) amplifier world is nearly 100% "contaminated" by silicon solid-state components that ensure proper amplification for any signal from any source (CD, DVD, Vinyl, MP3, Radio, TV, etc.) to ones ears. A broad range of design supporting literature² and other information sources and tools like eg. the internet or component producer's applications help design engineers world-wide to come up with the right products at the right time on the right markets - hopefully.

The percentage difference between 100% and nearly 100% is filled with gain making elements that are far away from silicon: vacuum valves and audio transformers. It's an interesting fact that still many CD and/or DVD producing studios work with valve and transformer driven equipment like eg. the compressor types Teletronik LA-2A or UREI 1176LN or they bring into action valve driven microphones (eg. Neumann U47 or Rode Classic II) and mixers at the frontend of the recording chain. Not to forget all the valve powered measurement equipment (from eg. Brüel & Kjær, Tektronics, etc.) still in use.

Because of their outstanding sound quality (eventually mainly caused by an even harmonics distortion effect) most of the involved valves in pre-amp stages are triodes or pentodes configured as triodes. I won't debate whether silicon or vacuum sounds better - this would be purely subjective. But the world-wide growing sales revenues for vacuum based sound and reproduction equipment is an astonishing thing for me and gives a sound related answer by purse or credit card. And another thing surprises me as well: despite the totally different analogue world there are enough young engineers (and senior ones - of course) of our totally digital era that are willing to struggle with such an old fashioned technology by creating superb sounding electronic instruments.

Although it might look as if - but it has nothing to do with Black Art! It's simply the transfer of a specific know-how into life by enthusiasts. A know-how that seems to be no longer part of training courses of universities and colleges, that is threatened to get lost if we don't work hard to stop this evolution by bringing out ready and easy to use modern literature and software tools.

Therefore, the following chapters offer formulae to calculate certain building blocks of valve amplifiers - but for pre-amp purposes only. In nearly all cases detailed derivations are also given. All what's needed are the data sheet figures of the triode's (t) mutual conductance $g_{m,t}$, the gain factor μ_t and the internal plate resistance $r_{a,t}$. To calculate frequency and phase responses of gain stages the different data sheet presented input and output capacitances have to be taken into account as well.

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Inter alia: "Electronic Circuits", U. Tietze, C. Schenk, 2nd edition, Springer 2008, ISBN 978-3-540-00429-5

It must be pointed out that all formulae are based on certain assumptions. The most important one is the one that defines the DC biasing conditions of these active devices. The conditions were assumed to be those of the A-class operating point settings: the plate DC current never switches off for positive and negative parts of the input signal. In other words: the A-class operating point is located in the (~middle of the) most linear part of the V_g/I_a versus plate voltage V_a diagram of the respective valve. This is the only way to guarantee that the triode's data sheet figures for mutual conductance g_{mt} , gain μ_t and internal plate resistance $r_{a,t}$ can be taken as so-called constants (always valid: $\mu_t = g_{m,t} \times r_{a,t}$) and can be used for our calculation purposes.

Other biasing classes (B = total plate/cathode current switch-off for negative signal parts or AB = a tiny quiescent current is allowed to flow through plate and cathode for negative signal parts) or the use of other operating points on the V_g/I_a versus plate voltage V_a characteristic plot need certain additional measurements or graphical approaches to get the right values for the above shown valve constants. Having gone through these processes the newly generated $g_{m.t.new}$, $\mu_{t.new}$ ³ and $r_{a.t.new}$ figures should be used for further calculation purposes. The given formulae won't change and will look the same.

I do not dive into the valve's DC biasing mechanics because they can easily be studied with the help of a broad range of literature⁴. But in that range of books and magazines⁵ I miss a summary of all the gain producing possibilities of triodes on one spot. That will be the only matter of the following pages. The respective formulae were derived from equivalent circuits by application of Ohm's⁶ and Kirchhof's⁷ laws. It will be demonstrated in detail in Chapters 1... 4. These approaches lead to certain amp building blocks around one valve. The formulae for gain stages that incorporate more than one valve (eg. SRPP or cascoded gain stages, etc.) will mostly be derived from these building blocks.

In addition, MathCad⁸ (MCD) worksheets as a part of each chapter allow easy follow-up and application of the respective formulae for any kind of triode. The calculations show results with 3 digits after the decimal point. The only reason for that is to demonstrate - from time to time - (tiny) differences with other calculation results. In reality, even a calculation result of one digit after the decimal point wouldn't present the whole truth because the tolerances of valves are a magnitude away from precision. But this fact didn't - nor doesn't it today - prevent engineers from designing extremely precise working analogue amps and other electronic valve driven devices. That's why, on the other hand, the calculation approaches offered are not far away from reality. For fast estimations many rules of thumbs are offered too.

I'm sure I only did treat a limited selection of possible building blocks for triode driven amps. That's why all readers are invited to not hesitate to send to the editors their know-how on additional triode amp stage solutions - including the mathematical derivations that are needed to understand how they work (à la the presented MathCad worksheets). This book should become the collection of everything what's of interest on this specific design field. The next edition will come out with these additional designs.

³ in contrast to respective "on dit(s)" a change of the bias point also means a change of μ_i; it is not a constant at all (see also Chapter 16 plots!)

⁴ Inter alia: "Valve amplifiers", Morgan Jones, Newnes, ISBN 0-7506-2337-3

⁵ Inter alia: "Tube Cad Journal"

⁶ a) $1\Omega * 1A = 1V$ or - generally spoken - R*I = V

⁷ a) The sum of all currents in a circuit's node equals zero;

b) The sum of all voltages (= potential differences) in a circuit's closed loop equals zero.
 MathCad is a registered trademark of MathSoft Engineering & Education Inc., since 2006 part of Parametrics Technology Corporation (PTC), Ma., USA

To sum-up the aims of this book:

- building up a collection of triode amp stage alternatives with satisfactory mathematical demonstration on how they work via derivations and transfer functions,
- to make things less complex the transfer functions are derived from rather simplified equivalent circuits, thus, saving a lot of energy by paying for it with tiny frequency and phase response errors, especially at the ends of the audio band,
- it's always better to calculate first and spent money for expensive components later instead of playing around with dice-type trial and error.

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1.1 Circuit diagram



Figure 1.1 Basic design of the Common Cathode Gain Stage (CCS)

1.2 Basic formulae (excl. stage load (R_L)-effect)

1.2.1 gain G_t:

$$G_t = -\frac{v_0}{v_i} \tag{1.1}$$

in terms of $g_{m,t}$ and $\mu_t G_t$ becomes:

$$G_{t} = -g_{m.t} \frac{r_{a.t}R_{a}}{r_{a.t} + R_{a} + R_{c}(1 + g_{m.t}r_{a.t})}$$

$$= -\mu_{t} \frac{R_{a}}{r_{a.t} + R_{a} + R_{c}(1 + \mu_{t})}$$
(1.2)

rule of thumb (rot):

with

$$\mu_t R_c \gg r_{a.t} + R_a \tag{1.3}$$

G_{t.rot} becomes:

$$G_{t.rot} = -\frac{R_a}{R_c}$$
(1.4)

1.2.2 grid input resistance R_g , input capacitance $C_{i.tot}$ and input impedance $Z_{i.g}(f)$:

$$Z_{i,g}(f) = R_g \parallel C_{i,tot}$$
(1.5)

$$C_{i.tot} = \left(1 + \left|G_{t}\right|\right) C_{M} + C_{g.c} + C_{stray}$$
(1.6)

1.2.3 plate output resistance $R_{o.a}$ and output impedance $Z_{o.a}(f)$ (by ignoring tiny R_c -effects):

$$\mathbf{R}_{\mathbf{0},\mathbf{a}} = \mathbf{R}_{\mathbf{a}} \parallel \mathbf{r}_{\mathbf{0},\mathbf{a},\mathbf{t}} \tag{1.7}$$

$$\mathbf{r}_{o.a.t} = \mathbf{r}_{a.t} + (1 + \mu_t) \mathbf{R}_c \tag{1.8}$$

$$Z_{o.a}(f) = R_{o.a} \| C_{o.tot}$$
 (1.9)

1.2.4 cathode output resistance Ro.c:

$$\mathbf{R}_{\mathbf{0},\mathbf{c}} = \mathbf{r}_{\mathbf{c},\mathbf{t}} \| \mathbf{R}_{\mathbf{c}} \tag{1.10}$$

$$\mathbf{r}_{c.t} = \frac{\mathbf{R}_a + \mathbf{r}_{a.t}}{\mu_t + 1} \tag{1.11}$$

1.3 Derivations

1.3.1 Equivalent circuit for derivation purposes



Figure 1.2 Equivalent circuit of Figure 1.1

1.3.2 Derivation

1.3.2.1 gain G_t:

sum of currents at node A:

$$i_0 = i_1 + i_2 + i_3$$
 (1.12)

without R_L we can set $i_0 = 0$, hence

$$-i_1 = i_2 + i_3$$
 (1.13)

$$i_1 = \frac{V_0}{R_a} \tag{1.14}$$

$$i_2 = \frac{v_{a.c}}{r_{a.t}} = \frac{v_o - v_{R.c}}{r_{a.t}}$$
(1.15)

$$i_3 = g_{m.t} v_{g.c} = g_{m.t} (v_i - v_{R.c})$$
 (1.16)

sum of currents at node C:

$$i_4 = i_2 + i_3 + i_5$$
 (1.17)

 $r_{g,t}$ can be assumed as infinite, hence we can set $i_5 = 0$, thus

$$i_{4} = \frac{v_{R.c}}{R_{c}} = \frac{v_{0} - v_{R.c}}{r_{a.t}} + g_{m.t} \left(v_{i} - v_{R.c} \right)$$
(1.18)

rearrangement leads to:

$$i_4 = -i_1$$
 (1.19)

$$G_t = -\frac{v_o}{v_i} \tag{1.20}$$

$$g_{m.t}\left(v_{i}+v_{o}\frac{R_{c}}{R_{a}}\right)+\frac{v_{o}+v_{o}\frac{R_{c}}{R_{a}}}{r_{a.t}}=-\frac{v_{o}}{R_{a}}$$
 (1.21)

$$g_{m.t}v_{i} = -v_{o}\left(\frac{1}{R_{a}} + g_{m.t}\frac{R_{c}}{R_{a}} + \frac{1 + \frac{R_{c}}{R_{a}}}{r_{a.t}}\right)$$
(1.22)

$$\Rightarrow G_{t} = -g_{m.t} \frac{r_{a.t} R_{a}}{r_{a.t} + R_{a} + R_{c} (1 + g_{m.t} r_{a.t})}$$
(1.23)

with the general triode equation G_t in terms of μ_t becomes:

$$g_{m,t} r_{a,t} = \mu_t \tag{1.24}$$

$$\Rightarrow G_t = -\mu_t \frac{R_a}{r_{a,t} + R_a + R_c \left(1 + \mu_t\right)}$$
(1.25)

$R_{a,\text{eff}}$ replaces R_a in all calculations that include R_L as gain stage output load!

$$\mathbf{R}_{a.eff} = \mathbf{R}_a \parallel \mathbf{R}_L \tag{1.26}$$

$$G_{t.eff} = -g_{m.t} \frac{r_{a.t} R_{a.eff}}{r_{a.t} + R_{a.eff} + R_{c} (1 + g_{m.t} r_{a.t})}$$
(1.27)

$$G_{t.eff} = -\mu_t \frac{R_{a.eff}}{r_{a.t} + R_{a.eff} + R_c \left(1 + \mu_t\right)}$$
(1.28)

1.3.2.2 the grid input impedance $Z_{i.g}(f)$ becomes:

$$Z_{i.g}(f) = r_{g.t} || R_g || C_{i.tot}$$
 (1.29)

$$i_{5} = 0$$

$$\Rightarrow \quad r_{g,t} = \infty \qquad (1.30)$$

$$\Rightarrow \quad Z_{i,g}(f) = R_{g} \parallel C_{i,tot}$$

1.3.2.3 the effective plate output resistance $R_{o.a.eff}$ and impedance $Z_{o.a.eff}(f)$ become:

$$i_{4} = i_{2} + i_{3} = g_{m.t} v_{g.c} + \frac{v_{a.c}}{r_{a.t}}$$

$$i_{4} = g_{m.t} (v_{i} - v_{R.c}) + \frac{v_{o} - v_{R.c}}{r_{a.t}}$$
(1.31)

setting $v_i = 0$ leads to:

$$r_{a.t} i_{4} = v_{o} - (1 + \mu_{t}) v_{R,c}$$

$$r_{a.t} = \frac{v_{o}}{i_{4}} - (1 + \mu_{t}) R_{c}$$

$$r_{o.a.t} = \frac{v_{o}}{i_{4}}$$

$$= r_{a.t} + (1 + \mu_{t}) R_{c}$$
(1.32)

$$R_{o.a} = r_{o.a.t} || R_a$$

$$\Rightarrow Z_{o.a} (f) = R_{o.a} || C_o$$
(1.33)

$$R_{o.a.eff} = r_{o.a.t} || R_{a.eff}$$

$$\Rightarrow Z_{o.a.eff} (f) = R_{o.a.eff} || C_{o.tot}$$
(1.34)

1.3.2.4 the effective cathode output resistance R_{o.c.eff} looks as follows¹:

$$r_{c.t} = \frac{r_{a.t} + R_a}{1 + \mu_t}$$
(1.35)

$$\mathbf{R}_{o.c} = \mathbf{r}_{c.t} \parallel \mathbf{R}_c \tag{1.36}$$

$$\Rightarrow r_{c.t.eff} = \frac{r_{a.t} + R_{a.eff}}{1 + \mu_t}$$
(1.37)

$$\Rightarrow R_{o.c.eff} = r_{c.t.eff} \parallel R_c$$
(1.38)

1

detailed derivation see Chapter 4 "The common grid stage (CGS)"

1.3.2.5 total input capacitance $C_{i,tot}$, total output capacitance $C_{o,tot}$ and Miller capacitance C_{M} :



Figure 1.3 Valve capacitances

Data sheet figures:

C _{g.c}	=	C between grid and cathode (rather often expanded by
-		additional heater and shield capacitances for the CGS gain
		stage situation - see respective chapter)
$C_{g.a}$	=	C between grid and plate
C _{a.c}	=	C between plate and cathode (rather often expanded by
		additional heater and shield capacitances for the CGS gain
		stage situation - see respective chapter)

Calculation relevant figures:

CM	=	$C_{g,a} = Miller$ capacitance
C _{stray}	=	sum of several different capacitances (to be guessed) ²
Ci.tot	=	total input capacitance
C _{o.tot}	=	total output capacitance

$$\mathbf{C}_{i.tot} = \left(1 + \left|\mathbf{G}_{t}\right|\right) \mathbf{C}_{g.a} \parallel \mathbf{C}_{g.c} \parallel \mathbf{C}_{stray}$$
(1.39)

$$C_{o.tot} = C_{a.c} \parallel C_M \tag{1.40}$$

² Guessed input sum of stray capacitances plus all other existing valve capacitances that were not specifically mentioned in the calculation course, eg. capacitances from grid or plate or cathode to heater or screen or to both or to the equivalent points of a second system of a double triode

1.4 Gain stage frequency and phase response calculations



Figure 1.4 Simplified³ equivalent circuit of Figure 1.1 - including all frequency and phase response relevant components

$$T_i(f) = \frac{v_g}{v_0} \tag{1.41}$$

$$\varphi_{i}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{i}(f)\right]}{\operatorname{Re}\left[T_{i}(f)\right]}\right\}$$
(1.42)

$$T_{i}(f) = \frac{Z2(f)\left(\frac{1}{R_{g}} + \frac{1}{R_{gg} + Z2(f)}\right)^{-1}}{\left(R_{gg} + Z2(f)\right)\left[R_{S} + Z1(f) + \left(\frac{1}{R_{g}} + \frac{1}{R_{gg} + Z2(f)}\right)^{-1}\right]}$$
(1.43)

$$Z1(f) = (2j\pi f C_{in})^{-1}$$

$$Z2(f) = (2j\pi f C_{i.tot})^{-1}$$
(1.44)

1.4.2 gain stage output transfer function $T_o(f)$ and phase $\phi_o(f)$:

3

$$T_{o}(f) = \frac{v_{o}}{v_{a}}$$
(1.45)

$$\varphi_{0}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{0}(f)\right]}{\operatorname{Re}\left[T_{0}(f)\right]}\right\}$$
(1.46)

"Simplified" because of footnote 2 of this chapter and the fact that the insertion of C_o the way I do it "ignores" the existence of R_c . But this makes the calculation less complex and will also lead to results not far away from the audio band reality.

$$T_{o}(f) = \left(\frac{Z3(f) \| (Z4(f) + R_{L})}{R_{o.a} + [Z3(f) \| (Z4(f) + R_{L})]}\right) \left(\frac{R_{L}}{R_{L} + Z4(f)}\right)$$
(1.47)

$$Z3(f) = (2j\pi f C_{o.tot})^{-1}$$

$$Z4(f) = (2j\pi f C_{out})^{-1}$$
(1.48)

1.4.3 fundamental gain stage phase shift $\phi_{G,t}(f)$:

$$\varphi_{G,t}(f) = -180^{\circ} \tag{1.49}$$

1.4.4 gain stage transfer function $T_{tot}\left(f\right)$ and phase $\phi_{tot}\left(f\right)$:

$$T_{tot}(f) = T_i(f)T_o(f)G_t$$
(1.50)

$$\varphi_{\text{tot}}(\mathbf{f}) = \varphi_{i}(\mathbf{f}) + \varphi_{o}(\mathbf{f}) + \varphi_{G,t}(\mathbf{f})$$
(1.51)

MCD Worksheet I: CCS calculations

1.5 Example with ECC83 / 12AX7 (83):



Figure 1.5 CCS example circuitry

1.5.1 Triode bias data:

 $I_{a.83} = 1.2 \cdot 10^{-3} A$ $V_{cc.83} = 370 V$ $V_{a.83} = 250 V$ $V_{g.83} = -2 V$

1.5.2 Triode valve constants:

$g_{m.83} := 1.6 \cdot 10^{-3} \cdot S$	$\mu_{83} := 100$	$r_{a.83} := 62.5 \cdot 10^{3} \Omega$
$C_{g.c.83} := 1.65 \cdot 10^{-12} F$	$C_{g.a.83} := 1.6 \cdot 10^{-12} F$	$C_{a.c.83} := 0.33 \cdot 10^{-12} F$

1.5.3 Circuit variables:

$R_{a.83} \coloneqq 100 \cdot 10^{3} \Omega$	$R_{c.83} \coloneqq 1.6 \cdot 10^{3} \Omega$	$R_{g.83} \coloneqq 1.10^{\circ} \Omega$
$R_{S} := 1 \cdot 10^{3} \Omega$	$R_L := 1 \cdot 10^6 \Omega$	$R_{gg.83} := 2.2 \cdot 10^{3} \Omega$
$C_{stray.83} := 10 \cdot 10^{-12} F$	$C_{in.83} = 100 \cdot 10^{-9} F$	$C_{out.83} := 100 \cdot 10^{-9} F$

1.5.4 Calculation relevant data:

frequency range f for the below shown graphs:

f := 10Hz,20Hz.. 20000 Hz h := 1000 Hz

1.5.5 Gain G_t and effective gain G_{t.eff} :

$$G_{83} \coloneqq -g_{m.83} \frac{R_{a.83} \cdot r_{a.83}}{R_{a.83} + r_{a.83} + (1 + g_{m.83} \cdot r_{a.83}) \cdot R_{c.83}} \qquad G_{83} = -30.855 \times 10^{0}$$

$$G_{83.e} \coloneqq 20 \cdot \log(|G_{83}|) \qquad G_{83.e} = 29.786 \times 10^{0} \text{ [dB]}$$

Page 1

MCD Worksheet I:

 $R_{a.83.eff} := \left(\frac{1}{R_{a.83}} + \frac{1}{R_{I}}\right)^{-1}$ $R_{a,83,eff} = 90.909 \times 10^3 \Omega$ $G_{83.eff} := -\mu_{83} \cdot \frac{R_{a.83.eff}}{R_{a.83.eff} + r_{a.83} + (1 + \mu_{83}) \cdot R_{c.83}}$ $G_{83\,eff} = -28.859 \times 10^0$ $G_{83\,eff\,e} = 29.206 \times 10^0 \, [dB]$ $G_{83.eff.e} := 20 \cdot \log(|G_{83.eff}|)$ 1.5.6 Gain G_{t rot}: $\mu_{83} \cdot R_{c.83} = 160 \times 10^3 \Omega$ $r_{a,83} + R_{a,83} = 162.5 \times 10^3 \Omega$ $G_{83.rot} \coloneqq -\frac{R_{a.83}}{R_{a.82}}$ $G_{83 \text{ rot}} = -62.5 \times 10^0$ this result contradicts equ. (1.3), thus, a gain calculation via G_{t.rot} makes no sense! 1.5.7 Specific resistances: $r_{0.2,83} = 224.1 \times 10^3 \Omega$ $r_{0.a.83} := r_{a.83} + (\mu_{83} + 1) \cdot R_{c.83}$ $R_{0.a.83} := \left[\left(\frac{1}{r_{0.a.83}} + \frac{1}{R_{a.83}} \right)^{-1} \right]$ $R_{0.3,83} = 69.145 \times 10^3 \Omega$ $R_{o.a.83.eff} := \left(\frac{1}{r_{o.a.83}} + \frac{1}{R_{a.83.eff}}\right)^{-1}$ $R_{0.8,83,eff} = 64.673 \times 10^3 \Omega$ $r_{c.83} := \frac{r_{a.83} + R_{a.83}}{1 + \mu_{0.2}}$ $r_{0.83} = 1.609 \times 10^3 \Omega$ $R_{o.c.83} := \left(\frac{1}{r_{c.83}} + \frac{1}{R_{c.83}}\right)^{-1}$ $R_{0,c,83} = 802.222 \times 10^{0} \Omega$ $r_{c.83.eff} := \frac{r_{a.83} + R_{a.83.eff}}{1 + \mu_{83}}$ $r_{c,83,eff} = 1.519 \times 10^{3} \Omega$ $R_{o.c.83.eff} := \left(\frac{1}{r_{c.83.eff}} + \frac{1}{R_{o.82}}\right)^{-1}$ $R_{0.6.83 \text{ eff}} = 779.198 \times 10^{0} \Omega$ 1.5.8 Specific capacitances : $C_{i,tot 83} = 62.617 \times 10^{-12} F_{i}$ $\mathbf{C_{i.tot.83}} \coloneqq \left(1 + \left|\mathbf{G_{83}}\right|\right) \cdot \mathbf{C_{g.a.83}} + \mathbf{C_{g.c.83}} + \mathbf{C_{stray.83}}$ $C_{o.tot.83} = 1.93 \times 10^{-12} F$ $C_{o.tot.83} := C_{a.c.83} + C_{g.a.83}$

MCD Worksheet I: CCS calculations



Page 3

MCD Worksheet I:



degrees







 $T_{tot,83}(f) := T_i(f) \cdot T_o(f) \cdot G_{83}$

 $T_{tot, 83, e}(f) := 20 \cdot log(|T_{tot, 83}(f)|)$



Figure 1.10 Phase of o/p network

 $\phi_{G.83}(f) := -180 \deg$

 $\phi_{tot.83}(f) \coloneqq \phi_i(f) + \phi_o(f) + \phi_{G.83}(f)$









1.6 With changed circuitry components and valve constants the same calculation course as above leads to an overall gain improvement of appr. 1.5dB (n = new):

$$\begin{split} I_{a,83,n} &= 0.5 \cdot 10^{-3} A & V_{cc,83,n} = 200 V & V_{a,83,n} = 100 V & V_{g,83,n} = -1 V \\ g_{m,83,n} &\coloneqq 0.9 \cdot 10^{-3} \cdot S & \mu_{83,n} &\coloneqq 95 & r_{a,83,n} &\coloneqq 105 \cdot 10^{3} \Omega \\ R_{a,83,n} &\coloneqq 200 \cdot 10^{3} \Omega & R_{c,83,n} &\coloneqq 2 \cdot 10^{3} \Omega \end{split}$$

1.7 Additional remarks

- 1.7.1 Valve constants change with changing plate DC current I_a and changing platecathode DC voltage V_a. Many data sheets of modern valves offer specific charts⁴ that demonstrates these changes:
 - "constants vs. Ia" for a selection of different Vas
- 1.7.2 Plate currents lower than the one for the A-class biasing point produce higher plate resistances r_{a.t}, thus, valve noise will increase as well and vice verca.
- 1.7.3 The oscillation prevention resistor R_{gg} (mostly to be found fixed between the valve's grid and grid resistance R_g) also plays a negative role when talking about noise, especially in amplifiers for tiny signals, such as signals from cartridges for vinyl records or from microphones.
- 1.7.4 For further information on noise in audio amplifiers in general and specifically a deeper view into the valve noise problems please consult the author's book
 - > "The Sound of Silence" $(= TSOS)^5$.
- 1.7.5 For C_{in} and C_{out} a change from 100nF to 1µF will drastically improve the frequency and phase response of the amp stage.

⁴ see example valve constants charts in Chapter 16

⁵ TSOS see Chapter 17, Section 17.1

2.1 Circuit diagram



Figure 2.1 Basic design of the Common Cathode Gain Stage with grounded Cathode via $C_{\rm c}~({\rm CCS+C_c})$

2.2 Basic formulae (excl. stage load (R_L)-effect)

2.2.1 gain G_t (C_c acts as a complete short-circuit):

$$G_t = -\frac{V_0}{v_i}$$
(2.1)

gain G_t in terms of $g_{m,t}$ and μ_t becomes:

$$G_{t} = -g_{m.t} \frac{r_{a.t} R_{a}}{r_{a.t} + R_{a}}$$

$$= -\mu_{t} \frac{R_{a}}{r_{a.t} + R_{a}}$$
(2.2)

2.2.2 grid input resistance R_g , input capacitance $C_{i,tot}$ and input impedance $Z_{i,g}(f)$:

$$Z_{i,g}(f) = R_g \parallel C_{i,tot}$$
(2.3)

formulae for Ci.tot: see Chapter 1

2.2.3 plate output resistance $R_{o.a}$ and output impedance $Z_{o.a}(f)$:

$$\mathbf{R}_{\mathbf{0.a}} = \mathbf{r}_{\mathbf{a.t}} \parallel \mathbf{R}_{\mathbf{a}} \tag{2.4}$$

$$Z_{o.a}(f) = R_{o.a} \parallel C_{o.tot}$$

$$(2.5)$$

formulae for Co: see Chapter 1

2.2.4 cathode output resistance $R_{o.c}$:

$$R_{o.c} = r_{c.t} || R_c$$

$$r_{c.t} = \frac{r_{a.t} + R_a}{1 + \mu_t}$$
(2.6)

2.2.5 capacitance C_{c} for a specific hp corner frequency $f_{c.opt}\!\!:$

$$C_{c} = \frac{1}{2\pi f_{c.opt} R_{o.c}}$$
(2.7)

2.3 Derivations

2.3.1 Equivalent circuit for derivation purposes:



Figure 2.2 Equivalent circuit of Figure 2.1

2.3.2 Derivations:

With C_c of a size that acts as a short-circuit for $v_{R,c}$ in B_{20k} we can use all the respective formulae of Chapter 1 with $R_c = 0$, hence:

2.3.2.1 the gain G_t and effective gain $G_{t.eff}$ become:

$$\mathbf{G}_{t} = -\mathbf{g}_{m.t} \left(\mathbf{r}_{a.t} \parallel \mathbf{R}_{a} \right) \tag{2.8}$$

$$\mathbf{R}_{a.eff} = \mathbf{R}_{a} \parallel \mathbf{R}_{L} \tag{2.9}$$

$$G_{t.eff} = -g_{m.t} \left(r_{a.t} \parallel R_{a.eff} \right)$$
(2.10)

2.3.2.2 the grid input impedance $Z_{i,g}(f)$ becomes:

$$Z_{i,g}(f) = \frac{R_g}{1 + 2j\pi f R_g C_{i,tot}}$$
(2.11)

2.3.2.3 the effective plate output resistance $R_{o.a.eff}$ and impedance $Z_{o.a.eff}(f)$ become:

$$R_{o.a} = r_{a.t} \parallel R_a$$

$$\Rightarrow Z_{o.a} (f) = R_{o.a} \parallel C_{o.tot}$$
(2.12)

$$R_{o.a.eff} = r_{a.t} || R_{a.eff}$$

$$\Rightarrow Z_{o.a.eff} (f) = R_{o.a.eff} || C_{o.tot}$$
(2.13)

$$Z_{\text{o.a.eff}}(f) = \frac{R_{\text{o.a.eff}}}{1 + 2j\pi f R_{\text{o.a.eff}}C_{\text{o}}}$$
(2.14)

2.3.2.4 cathode resistance $r_{c.t.eff}$ and effective cathode output resistance $R_{o.c.eff}$ become:

$$r_{c.t.eff} = \frac{r_{a.t} + R_{a.eff}}{1 + \mu_t}$$
(2.15)

$$R_{o.c.eff} = r_{c.t.eff} || R_{c}$$

$$= \frac{\frac{r_{a.t} + R_{a.eff}}{1 + \mu_{t}} R_{c}}{\frac{r_{a.t} + R_{a.eff}}{1 + \mu_{t}} + R_{c}}$$
(2.16)

MCD symbolic evaluation "simplify" leads to

$$R_{o.c.eff} = \frac{(r_{a.t} + R_{a.eff})R_{c}}{r_{a.t} + R_{a.eff} + (1 + \mu_{t})R_{c}}$$
(2.17)

2.3.2.5 cathode capacitance C_c for a specific hp corner frequency f_c:

The audio band B_{20k} spreads from 20Hz to 20kHz. To ensure a flat frequency response in $B_{20k}~(\pm0.1dB)$ as well as a phase response deviation of less than 1° at f_c = 20Hz the C_c calculation should be based on a corner frequency $f_{c.opt}$ that is a 100th of f_c .

$$f_c = 20Hz$$

 $f_{c.opt} = \frac{20Hz}{100} = 0.2Hz$ (2.18)

$$C_{c} = \frac{1}{2\pi f_{c.opt} R_{o.c.eff}}$$
(2.19)

2.3.2.6 total input capacitance C_{i.tot} and total output capacitance C_{o.tot}:

see respective equations and footnote² in Chapter 1 - 1.3.2.5

¹ detailed derivation see Chapter 4 "The common grid stage (CGS)"

² see footnote 2 in Chapter 1

2.4 Gain stage frequency and phase response calculations



Figure 2.3 Simplified³ equivalent circuit of Figure 2.1 - including all frequency and phase response relevant components

- 2.4.1 gain stage input transfer function T_i (f) and phase φ_i (f) including source resistance R_s and an oscillation preventing resistor R_{gg}<<R_g:
 - see Chapter 1 1.4.1
- 2.4.2 gain stage output transfer function $T_o(f)$ and phase $\phi_o(f)$:

see Chapter 1 - 1.4.2

2.4.3 gain stage cathode transfer function $T_c(f)$ and phase $\varphi_c(f)$:

$$T_{c}(f) = \left(\frac{R_{o.c.eff}}{R_{o.c.eff} + \frac{1}{2j\pi f C_{c}}}\right)$$
(2.20)

$$\varphi_{c}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{c}(f)\right]}{\operatorname{Re}\left[T_{c}(f)\right]}\right\}$$
(2.21)

2.4.4 fundamental gain stage phase shift $\phi_{G.t}(f)$:

$$\varphi_{\rm G.t}(f) = -180^{\circ}$$
 (2.22)

2.4.5 gain stage transfer function $T_{tot}(f)$ and phase $\phi_{tot}(f)$:

$$T_{tot}(f) = T_i(f) T_o(f) T_c(f) G_t$$
 (2.23)

$$\varphi_{tot}(f) = \varphi_i(f) + \varphi_o(f) + \varphi_c(f) + \varphi_{G,t}(f)$$
 (2.24)

³ "Simplified" because of footnote 2 of Chapter 1. In addition: The simple C_c and $R_{o.c}$ network after the +1 amp V1_c works correct the shown way only in the frequency range of $f_{c.opt}$ minus one octave. In lower frequency ranges than that the gain of the whole gain stage will reach the gain of a CCS gain stage with the same components but without C_c . But this frequency range lies far outside B_{20k} .

MCD Worksheet II CCS+Cc calculations



2.5 Example with ECC83 / 12AX7 (83):



Figure 2.4 CCS+Cc example circuitry

2.5.1 Triode bias data:

$I_{a.83} = 1.2 \cdot 10^{-3} A$ $V_{cc.83} = 3$	$V_{a.83} = 250 V$	$V_{g.83} = -2V$
2.5.2 Triode valve constant	s:	
$g_{m.83} := 1.6 \cdot 10^{-3} \cdot S$	$\mu_{83} := 100$	$r_{a.83} := 62.5 \cdot 10^3 \Omega$
$C_{g.c.83} \coloneqq 1.65 \cdot 10^{-12} F$	$C_{g.a.83} \coloneqq 1.6 \cdot 10^{-12} \mathrm{F}$	$C_{a.c.83} := 0.33 \cdot 10^{-12} F_{a.c.83}$
$C_{o.tot.83} \coloneqq C_{a.c.83} + C_{g.a.83}$	$C_{o.tot.83} = 1.93 \times 10^{-12} F$	
2.5.3 Circuit variables:		
$R_{a.83} := 100 \cdot 10^3 \Omega$	$R_{c.83} := 1.6 \cdot 10^3 \Omega$	$R_{g.83} \coloneqq 1 \cdot 10^6 \Omega$
$R_{S} \coloneqq 1.10^{3} \Omega$	$R_{L} \coloneqq 1.10^{6} \Omega$	$R_{gg.83} := 2.2 \cdot 10^{3} \Omega$
$C_{stray.83} := 10 \cdot 10^{-12} F$	$C_{in.83} := 100 \cdot 10^{-9} F$	$C_{out.83} := 100 \cdot 10^{-9} F$

2.5.4 Calculation relevant data:

frequency range f for the below shown graphs:

f := 10Hz,20Hz.. 20000 Hz h := 1000 Hz

2.5.5 Gain G_t and effective gain $G_{t.eff}$:

$$G_{83} := -g_{m.83} \cdot \frac{R_{a.83} \cdot r_{a.83}}{R_{a.83} + r_{a.83}} \qquad \qquad G_{83} = -61.538 \times 10^0$$

MCD Worksheet II

CCS+Cc calculations

 $G_{82} = 35.783 \times 10^0 \text{ [dB]}$ $G_{83e} := 20 \cdot \log(|G_{83}|)$ $R_{a.83.eff} := \left(\frac{1}{R_{a.83}} + \frac{1}{R_{I}}\right)^{-1}$ $R_{a,83,eff} = 90.909 \times 10^3 \Omega$ $G_{83.eff} := -\mu_{83} \cdot \frac{R_{a.83.eff}}{R_{a.83.eff} + r_{a.83}}$ $G_{83\,eff} = -59.259 \times 10^0$ $G_{82,off,o} = 35.455 \times 10^0 \text{ [dB]}$ $G_{83.eff.e} = 20 \cdot \log(|G_{83.eff}|)$ 2.5.6 Specific resistances: $R_{0.a.83} := \left[\left(\frac{1}{r_{a.83}} + \frac{1}{R_{a.83}} \right)^{-1} \right]$ $R_{0,a,83} = 38.462 \times 10^3 \Omega$ $R_{o.a.83.eff} := \left(\frac{1}{r_{a} R_{3}} + \frac{1}{R_{a} R_{3} eff}\right)^{-1}$ $R_{0.8,83,eff} = 37.037 \times 10^3 \Omega$ $r_{c.83} \coloneqq \frac{r_{a.83} + R_{a.83}}{1 + \mu_{83}}$ $r_{c,83} = 1.609 \times 10^3 \Omega$ $R_{0.c.83} := \left(\frac{1}{r_{c.83}} + \frac{1}{R_{c.83}}\right)^{-1}$ $R_{0,c,83} = 802.222 \times 10^{0} \Omega$ $r_{c.83.eff} := \frac{r_{a.83} + R_{a.83.eff}}{1 + \mu_{22}}$ $r_{c,83,eff} = 1.519 \times 10^3 \Omega$ $R_{o.c.83.eff} := \left(\frac{1}{r_{c.83.eff}} + \frac{1}{R_{c.83}}\right)^{-1}$ $R_{0.6,83,eff} = 779.198 \times 10^{0} \Omega$ 2.5.7 Capacitance C_c: $f_{c \text{ opt}} := \frac{f_c}{100}$ $f_{c opt} = 200 \times 10^{-3} Hz$ $f_c := 20Hz$ $C_{c} \coloneqq \frac{1}{2 \cdot \pi \cdot f_{c} \text{ opt}^{\cdot R_{0}} c 83 \text{ eff}}$ $C_0 = 1.021 \times 10^{-3} F$ 2.5.8 Specific other capacitances: $C_{i \text{ tot } 83} = 111.712 \times 10^{-12} \text{F}$ $C_{i.tot.83} := (1 + |G_{83}|) \cdot C_{g.a.83} + C_{g.c.83} + C_{stray.83}$

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Figure 2.8 Transfer of cathode network





[Hz]

 $T_{tot.83}(f) \coloneqq T_i(f) \cdot T_o(f) \cdot T_c(f) \cdot G_{83}$

$$T_{\text{tot. 83.e}}(f) \coloneqq 20 \cdot \log(|T_{\text{tot. 83}}(f)|)$$

CCS+Cc calculations

$$\frac{\frac{50}{50}}{\frac{9}{50}} \frac{\phi_0(f)}{\frac{10}{600}} = 5$$

$$-5$$

$$10$$

$$10$$

$$10$$

$$1.10^4$$

$$1.10^4$$

$$1.10^6$$

$$\frac{1}{112}$$

Figure 2.9 Phase of cathode network

$$\phi_{\mathbf{c}}(\mathbf{f}) \coloneqq \operatorname{atan}\left(\frac{\operatorname{Im}(T_{\mathbf{c}}(\mathbf{f}))}{\operatorname{Re}(T_{\mathbf{c}}(\mathbf{f}))}\right)$$



Figure 2.11 Phase of o/p network

 $\phi_{G.83}(f) := -180 \deg$

 $\phi_{\text{tot.83}}(f) \coloneqq \phi_i(f) + \phi_o(f) + \phi_c(f) + \phi_{G.83}(f)$

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MCD Worksheet II CCS+Cc calculations







Chapter 3 The Cathode Follower (CF)

3.1 Circuit diagram - simple version CF1



Figure 3.1 Basic design of a Cathode Follower gain stage (CF) with gain $G_{\rm cfl} < 1$

3.2 Basic formulae (excl. stage load (R_L)-effect)

3.2.1 Gain G_{cfl} expressed in terms of $g_{m,t}$ and μ_t :

$$G_{cf1} = \frac{v_0}{v_i}$$
(3.1)

$$G_{cf1} = \frac{g_{m.t} (r_{a.t} || R_c)}{1 + g_{m.t} (r_{a.t} || R_c)}$$
(3.2)

$$\Rightarrow G_{cf1} = \mu_t \frac{R_c}{r_{a,t} + (1 + \mu_t) R_c}$$
(3.3)

3.2.2 Grid input resistance Rg, input capacitance¹ C_{i.tot} and input impedance Z_{i.g}(f):

$$Z_{i,g}(f) = R_g \parallel C_{i,tot}$$
(3.4)

$$C_{i.tot} = C_{g.a} \| C_{stray} \| (1 - G_{cf1}) C_{g.c}$$
(3.5)

3.2.3 Cathode output resistance R_{o.c1}:

$$R_{o.c1} = r_{c.t} \parallel R_c = \frac{r_{c.t} R_c}{r_{c.t} + R_c}$$
(3.6)

$$r_{c.t} = \frac{r_{a.t}}{\mu_t + 1}$$
(3.7)

rot = rule of thumb: with
$$\mu_t >> 1$$
 (3.8)

r_{c.t.rot} becomes:

$$r_{c.t.rot} \approx \frac{1}{g_{m.t}}$$
 (3.9)

Consequently, to get gains close to 1 gmt or Rc must be increased.

 $g_{m,t}$ always has certain limits set by the given values on the market, thus, R_e will be the target to get gains close to 1 (see 3.2: CF - improved version, further down these pages).

¹ see footnote 2 of Chapter 1

3.3 Derivations



Figure 3.2 Equivalent circuit of Figure 3.1

$$\begin{aligned} v_{g,c} &= v_{i} - v_{R,c} \\ v_{R,c} &= v_{o} \\ v_{o} &= -g_{m,t} \left(v_{i} - v_{o} \right) \left(R_{c} \parallel r_{a,t} \right) \\ \frac{v_{o}}{v_{i}} &= g_{m,t} \left(1 - G_{cf1} \right) \left(R_{c} \parallel r_{a,t} \right) \\ G_{cf1} &= g_{m,t} \frac{\left(R_{c} \parallel r_{a,t} \right)}{1 + g_{m,t} \left(R_{c} \parallel r_{a,t} \right)} \\ \mu_{t} &= g_{m,t} r_{a,t} \\ G_{cf1} &= \mu_{t} \frac{R_{c}}{r_{a,t} + (1 + \mu_{t}) R_{c}} \end{aligned}$$
(3.10)
3.4 Gain stage frequency and phase response calculations



Figure 3.3 Simplified² equivalent circuit of Figure 3.1 - including all frequency and phase response relevant components

3.4.1 Gain stage input transfer function $T_{i1}(f)$ and phase $\varphi_{i1}(f)$ - including source resistance R_s and an oscillation preventing resistor $R_{gg} \leq R_{g}$:

from Chapter 1, paragraphs 1.4.1 & 1.4.2 we'll get $T_i(f)$ and $\phi_i(f)^3$:

$$T_{i1}(f) = T_i(f)$$

$$\varphi_{i1}(f) = \varphi_i(f)$$
(3.11)

3.4.2 Gain stage output transfer function $T_{o1}(f)$ and phase $\phi_{o1}(f)$:

$$T_{01}(f) = \frac{v_0}{v_{R,c}} = \frac{R_L}{R_L + R_{0,c1} + Z4(f)}$$
(3.12)

$$Z4(f) = (2j\pi f C_{out})^{-1}$$
(3.13)

$$\varphi_{01}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{01}(f)\right]}{\operatorname{Re}\left[T_{01}(f)\right]}\right\}$$
(3.14)

3.4.3 Fundamental gain stage phase shift $\varphi_{G.cfl.t}(f)$:

$$\varphi_{G,cf1,t}(f) = 0^{\circ} \tag{3.15}$$

3.4.4 Gain stage transfer function $T_{tot,1}$ (f) and phase $\varphi_{tot,1}$ (f):

$$T_{tot.1}(f) = T_{i1}(f) T_{o1}(f) G_{cf1}$$
(3.16)

$$\varphi_{\text{tot},1}(f) = \varphi_{i1}(f) + \varphi_{o1}(f) + \varphi_{G,cf1}(f)$$
 (3.17)

² See footnote 2 of Chapter 1

 $^{^{3}}$ to get C_{i.tot} for the CF1 see equation 3.5 of this Chapter



3.5 Circuit diagram - improved version CF2_b and CF2_u



3.6 Basic formulae (excl. stage load (R_L)-effect)

Assumed that

- for the bypassed version (b) C_{c1} is an AC short-circuit for R_{c1} in B_{20k}
- DC biasing is properly set by R_g, R_{c1}, R_{c2} to the A-class biasing point
- Cout and RL are of a size that does not significantly influence the gain in the audio band B20k

the basic formulae to calculate the gain of the Figure 3.4 CF look similar to the ones of Figure 3.1 and as follows:

3.6.1 Gain $G_{cf2,b}$ of the bypassed version (b) in terms of $g_{m,t}$ and μ_t :

$$G_{cf2.b} = \frac{v_0}{v_i}$$
(3.18)

$$G_{cf2.b} = \frac{g_{m.t} \left(r_{a.t} \parallel R_{c2} \right)}{1 + g_{m.t} \left(r_{a.t} \parallel R_{c2} \right)}$$
(3.19)

$$G_{cf2.b} = \mu_t \frac{R_{c2}}{r_{a.t} + (1 + \mu_t)R_{c2}}$$
(3.20)

3.6.2 Gain $G_{cf2.u}$ in case of absence of C_{c1} (= un-bypassed version u):

$$G_{cf2.u} = \frac{g_{m.t} \left[r_{a.t} \| (R_{c1} + R_{c2}) \right]}{1 + g_{m.t} \left[r_{a.t} \| (R_{c1} + R_{c2}) \right]}$$
(3.21)

$$G_{cf2.u} = \mu_t \frac{R_{c1} + R_{c2}}{r_{a.t} + (1 + \mu_t)(R_{c1} + R_{c2})}$$
(3.22)

3.6.3 Input resistance R_{i.g.2} and input impedance Z_{i.g.2}(f):

$$R_{i.g.2.b} = \frac{R_g}{1 - G_{cf2.b}}$$
(3.23)

$$Z_{i.g.2.b}(f) = R_{i.g.2.b} \| C_{i.tot}$$
(3.24)

$$R_{i.g.2.u} = \frac{R_g}{1 - G_{cf2.u} \frac{R_{c2}}{R_{c1} + R_{c2}}}$$
(3.25)

$$Z_{i.g.2.u}(f) = R_{i.g.2.u} \| C_{i.tot}$$
(3.26)

3.6.4 Cathode output resistances⁴ R_{o.c2.b} & R_{o.c2.u}:

$$r_{c.t} = \frac{r_{a.t}}{\mu_t + 1}$$
(3.27)

$$r_{c.t.rot} \approx \frac{1}{g_{m.t}}$$
 (3.28)

$$R_{o.c2.b} = r_{c.t} \parallel R_{c2} \tag{3.29}$$

$$R_{o.c2.u} = r_{c.t} \| (R_{c1} + R_{c2})$$
(3.30)

3.6.5 Cc1 calculation:

The audio band B_{20k} spreads from 20Hz to 20kHz. To ensure a flat frequency response in B_{20k} (±0.1dB) as well as a phase response deviation of less than 1° at $f_c = 20$ Hz the C_{c1} calculation should be based on a corner frequency $f_{c.opt}$ that is $f_c/100$:

$$C_{c1} = \frac{1}{2\pi f_{c.opt} (r_{c.t} || R_{c1})}$$
(3.31)

$$f_{c.opt} = \frac{f_c}{100}$$
(3.32)

3.6.6 Total input capacitance Ci.tot

calculation relevant valve capacitances:

 $C_{g.c}$ = grid-cathode capacitance

 $C_{g.a}^{5.0}$ = grid-plate capacitance = Miller capacitance

 C_{stray} = sum of several different capacitances (to be guessed)⁵

$$C_{i.tot} = C_{g.a} \| C_{stray} \| (1 - G_{cf}) C_{g.c}$$
 (3.33)

⁵ see footnote 2 of Chapter 1

rule of thumb:

⁴ detailed derivation of r_{ct} see Chapter 4 "The Common Grid Stage (CGS)"

3.7 Derivations



Figure 3.5 Equivalent circuit of Figure 3.4 (without Cc1)

3.7.1 Gain $G_{cf2,b}$ (bypassed version $R_{c1} = 0$ for AC):

$$R_{c1} = 0$$

$$G_{cf2.b} = \frac{v_{o}}{v_{i}}$$

$$v_{o} = g_{m.t} v_{g.c} (r_{a.t} || R_{c2}) \qquad (3.34)$$

$$= v_{R.c2}$$

$$v_{i} = v_{R.g} + v_{R.c2}$$

$$= v_{g.c} + g_{m.t} v_{g.c} (r_{a.t} || R_{2})$$

$$\Rightarrow G_{cf2.b} = \frac{g_{m.t} (r_{a.t} || R_{c2})}{1 + g_{m.t} (r_{a.t} || R_{c2})} \qquad (3.35)$$

3.7.2 Gain $G_{cf2.u}$ (un-bypassed version):

$$G_{cf2.u} = \frac{v_{o}}{v_{i}}$$

$$v_{o} = g_{m.t} v_{g.c} (R_{c1} + R_{c2})$$

$$v_{i} = v_{g.c} + g_{m.t} v_{g.c} (R_{c1} + R_{c2})$$
(3.36)

$$\Rightarrow G_{cf2.u} = \frac{g_{m.t} \left[r_{a.t} \| (R_{c1} + R_{c2}) \right]}{1 + g_{m.t} \left[r_{a.t} \| (R_{c1} + R_{c2}) \right]}$$
(3.37)

3.7.3 Input resistance $R_{i,g,b}$ (bypassed version [$R_{c1} = 0$ for AC] and its bootstrap effect):

$$i_{5}=0 \implies r_{g,t}=\infty$$

$$\Rightarrow \frac{v_{g,c}}{R_{g}} = \frac{v_{i}}{R_{i,g,b}}$$

$$\frac{v_{i}-v_{o}}{R_{g}} = \frac{v_{i}}{R_{i,g,b}}$$

$$\frac{v_{i}\left(1-G_{cf2,b}\right)}{R_{g}} = \frac{v_{i}}{R_{i,g,b}}$$

$$\Rightarrow R_{i,g,b} = \frac{R_{g}}{1-G_{cf2,b}}$$
(3.39)

$$\frac{\frac{v_{g,c} + v_{R,cl}}{R_g} = \frac{v_i}{R_{i,g,u}}}{\frac{v_i (1 - G_{cf2,u}) + v_{R,cl}}{R_g} = \frac{v_i}{R_{i,g,u}}}$$
(3.40)

$$v_{R.c1} = v_0 \frac{R_{c1}}{R_{c1} + R_{c2}}$$

= $v_i G_{cf2.u} \frac{R_{c1}}{R_{c1} + R_{c2}}$

$$\Rightarrow \frac{v_{i}(1 - G_{cf2.u}) + v_{i} G_{cf2.u} \frac{R_{c1}}{R_{c1} + R_{c2}}}{R_{g}} = \frac{v_{i}}{R_{i.g.u}}$$
(3.41)

$$\Rightarrow R_{i.g.u} = \frac{R_g}{1 - G_{cf2.u} \frac{R_{cl}}{R_{cl} + R_{c2}}}$$
(3.42)

consequently:

$$R_{i.g.b} > ... >> R_{i.g.u}$$
 (3.43)

3.8 Gain stage frequency and phase response calculations



Figure 3.6 Simplified⁶ equivalent circuit of Figure 3.3 (bypassed version) - including all frequency and phase response relevant components



Figure 3.7 Simplified⁷ equivalent circuit of Figure 3.3 (un-bypassed version) - including all frequency and phase response relevant components

3.8.1 Gain stage input transfer function $T_{i1}(f)$ and phase $\phi_{i1}(f)$ - including source resistance R_s and an oscillation preventing resistor $R_{gg} \leq R_g$:

from Chapter 1, paragraphs 1.4.1 & 1.4.2 and with replacement of R_g by $R_{i,g.2.b}$ & $R_{i,g.2.u}$ we'll get $T_i\left(f\right)$ and $\phi_i\left(f\right)^8$:

$$T_{i2.b}(f) = T_{i2.u}(f) = T_i(f)$$

$$\varphi_{i2.b}(f) = \varphi_{i2.u}(f) = \varphi_i(f)$$
(3.44)

3.8.2 Gain stage output transfer functions $T_{o2,b}(f)$, $T_{o2,u}(f)$ and phases $\varphi_{o2,b}(f)$, $\varphi_{o2,b}(f)$:

$$T_{o2.b}(f) = \frac{v_o}{v_{R.c2}} = \left(\frac{R_{c1} \| r_{c.t}}{R_{c1} \| r_{c.t} + Z3(f)}\right) \left(\frac{R_L}{R_L + R_{o.c2.b} + Z4(f)}\right)$$
(3.45)

$$Z3(f) = (2j\pi f C_{c1})^{-1}$$
(3.46)

$$Z4(f) = (2j\pi f C_{out})^{-1}$$
(3.47)

$$T_{o2.u}(f) = \frac{v_o}{v_{R.c2}} = \frac{R_L}{R_L + R_{o.c2.u} + Z4(f)}$$
(3.48)

 7 see footnote 2 of Chapter 1 see footnote 2 of Chapter 1 to get C for the CE2 and

⁶ see footnote 2 of Chapter 1 and footnote 3 of Chapter 2

⁸ to get C_{i.tot} for the CF2 see paragraph 3.6.6 of this Chapter

$$\varphi_{o2.b}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{o2.b}(f)\right]}{\operatorname{Re}\left[T_{o2.b}(f)\right]}\right\}$$
(3.49)

$$\varphi_{o2.u}(f) = \arctan\left\{\frac{\mathrm{Im}\left[T_{o2.u}(f)\right]}{\mathrm{Re}\left[T_{o2.u}(f)\right]}\right\}$$
(3.50)

3.8.3 Fundamental gain stage phase shifts $\phi_{G.cf2.b}(f)$ and $\phi_{G.cf2.u}(f)$:

$$\varphi_{G.cf1.b}(f) = 0^{\circ}$$

$$\varphi_{G.cf1.u}(f) = 0^{\circ}$$
(3.51)

$3.8.4 \ \ \text{Gain stage transfer functions } T_{tot.2.b}\left(f\right), \ T_{tot.2.u}\left(f\right) \text{ and phases } \phi_{tot.2.b}\left(f\right), \ \phi_{tot.2.u}\left(f\right) \text{:}$

$$T_{tot.2.u}(f) = T_{i2.u}(f) T_{o2.u}(f) G_{cf2.u}$$
(3.52)

$$T_{tot.2.b}(f) = T_{i2.b}(f) T_{o2.b}(f) G_{cf2.b}$$
(3.53)

$$\varphi_{\text{tot.2.b}}(f) = \varphi_{i2.b}(f) + \varphi_{o2.b}(f) + \varphi_{G.cf2.b}(f)$$
 (3.54)

$$\varphi_{\text{tot.2.u}}(f) = \varphi_{i2.u}(f) + \varphi_{o2.u}(f) + \varphi_{G.cf2.u}(f)$$
(3.55)

MCD Worksheet III-1 CF1 calculations



CF1-Example with ECC83 / 12AX7 (83):



3.9.1 Triode bias data:

 $I_{a.83} = 1.2 \cdot 10^{-3} A$ $V_{cc.83} = 250 V$ $V_{a.83} = 250 V$ $V_{g.83} = -2 V$

3.9.2 Triode valve constants:

$g_{m.83} := 1.6 \cdot 10^{-5} \cdot S$	$\mu_{83} := 100$	$r_{a.83} := 62.5 \cdot 10^{3} \Omega$
$C_{g.c.83} \coloneqq 1.65 \cdot 10^{-12} F$	$C_{g.a.83} \coloneqq 1.6 \cdot 10^{-12} F$	$C_{a.c.83} \coloneqq 0.33 \cdot 10^{-12} F$
		$C_{0.83} := C_{a.c.83}$

3.9.3 Circuit variables:

$R_{a.83} \coloneqq 0.001\Omega$	$R_{c.83} \coloneqq 1.6 \cdot 10^3 \Omega$	$R_{g.83} \coloneqq 1.10^{6} \Omega$
$R_{S} := 1 \cdot 10^{3} \Omega$	$R_L := 1 \cdot 10^4 \Omega$	$R_{gg.83} \coloneqq 0.22 \cdot 10^3 \Omega$
$C_{stray.83} = 10 \cdot 10^{-12} F$	$C_{in.83} := 100 \cdot 10^{-9} F$	$C_{out.83} := 100 \cdot 10^{-6} F$

f := 10Hz, 20Hz.. 20000 Hz

h := 1000 Hz

3.9.4 Calculation relevant data:

frequency range f for the below shown graphs:

3.9.5 Gain G_{cf1}:

$$G_{cf1.83} := \frac{g_{m.83} \cdot \left(\frac{r_{a.83} \cdot R_{c.83}}{r_{a.83} + R_{c.83}}\right)}{1 + g_{m.83} \cdot \left(\frac{r_{a.83} \cdot R_{c.83}}{r_{a.83} + R_{c.83}}\right)}$$

$$G_{cf1.83} = 0.714$$

3.9

MCD Worksheet III-1 CF1 calculations \triangleright

 $G_{cf1.83.e} = -2.926$ [dB] $G_{cf1 83 e} := 20 \cdot \log(G_{cf1 83})$ 3.9.6 Cathode output resistance R_{b.c1}: $r_{c.83} \coloneqq \frac{r_{a.83}}{1 + \mu_{83}}$ $r_{c.83} = 618.812 \ \Omega$ $R_{0.c1.83} := \left(\frac{1}{r_{c.83}} + \frac{1}{R_{c.83}}\right)^{-1}$

 $r_{c.83.rot} := \frac{1}{g_{m.83}}$ $r_{c.83 \text{ rot}} = 625 \Omega$

3.9.7 Total input capacitance Ci.tot:

 $C_{i.tot.83} := C_{g.a.83} + C_{stray.83} + (1 - G_{cf1.83}) \cdot C_{g.c.83}$

 $C_{i \text{ tot } 83} = 12.072 \times 10^{-12} \text{F}$

 $R_{0,c1,83} = 446.229 \Omega$

3.9.8 Gain stage frequency and phase responses:







Figure 3.10 Transfer of i/p network



Figure 3.12 Transfer of o/p network

 $T_{tot.\,1.83}(f) := T_{i1}(f) \cdot T_{o1}(f) \cdot G_{cf1.83}$

 $T_{tot.\,1.83.e}(f) := 20 \cdot \log(|T_{tot.\,1.83}(f)|)$



Figure 3.11 Phase of i/p network

$$T_{o1}(f) \coloneqq \frac{R_L}{R_L + R_{o.c1.83} + Z4(f)}$$

$$T_{o1.e}(f) \coloneqq 20 \cdot \log(|T_{o1}(f)|)$$



Figure 3.13 Phase of o/p network

 $\phi_{G.cfl.83}(f) := 0 \cdot deg$

 $\phi_{\text{tot. 1.83}}(f) \coloneqq \phi_{i1}(f) + \phi_{o1}(f) + \phi_{G.cf1.83}(f)$

MCD Worksheet III-1 CF1 calculations



Figure 3.15 Phase response of the whole CF1 gain stage

➢ MCD Worksheet III-2 CF2_b calculations

3.10 CF2 _b-Example with ECC83 / 12AX7 (83):



Figure 3.16 CF2_b example circuitry

3.10.1 Triode bias data:

 $I_{a,83} = 1.2 \cdot 10^{-3} A$ $V_{cc.83} = 370V$ $V_{a.83} = 370V$ $V_{g.83} = 122V$ 3.10.2 Triode valve constants: $g_{m,83} := 1.6 \cdot 10^{-3} \cdot S$ $r_{a.83} := 62.5 \cdot 10^3 \Omega$ $\mu_{83} := 100$ $C_{g,c,83} \coloneqq 1.65 \cdot 10^{-12} F$ $C_{g,a,83} \coloneqq 1.6 \cdot 10^{-12} F$ $C_{a,c,83} := 0.33 \cdot 10^{-12} F$ $C_{0.83} := C_{a.c.83}$ 3.10.3 Circuit variables: $R_{9.83} := 1 \cdot 10^6 \Omega$ $R_{c1.83} := 1.6 \cdot 10^3 \Omega$ $R_{a,83} := 0.001 \Omega$ $R_{c2\,83} := 100 \cdot 10^3 \Omega$ $R_{S} := 1 \cdot 10^{3} \Omega$ $R_{I} := 10 \cdot 10^{3} \Omega$ $C_{stray.83} := 10 \cdot 10^{-12} F$ $C_{in.83} := 100 \cdot 10^{-9} F$ $C_{out 83} := 100 \cdot 10^{-6} F$ $R_{gg.83} := 0.22 \cdot 10^3 \Omega$

3.10.4 Calculation relevant data:

frequency range f for the below shown graphs:	f := 10 Hz, 20 Hz 20000 Hz
	h := 1000Hz

MCD Worksheet III-2 CF2_b calculations ۶

3.10.5 Gain
$$G_{ef2,b}$$
:
 $G_{cf2,b,83} \coloneqq \frac{g_{m,83} \cdot \left(\frac{r_{a,83} \cdot R_{c2,83}}{r_{a,83} + R_{c2,83}}\right)}{1 + g_{m,83} \cdot \left(\frac{r_{a,83} \cdot R_{c2,83}}{r_{a,83} + R_{c2,83}}\right)}$
 $G_{cf2,b,83} \coloneqq 20 \cdot \log(G_{cf2,b,83})$
 $G_{cf2,b,83,e} \coloneqq 20 \cdot \log(G_{cf2,b,83})$
 $G_{cf2,b,83,e} \coloneqq -0.14$ [dB]
3.10.6 Grid input resistance $R_{i,g2,b}$:
 $R_{i,g2,b,83} \coloneqq \frac{R_{g,83}}{1 - G_{cf2,b,83}}$
 $R_{i,g2,b,83} = 62.538 \times 10^{6} G$
3.10.7 Cathode output resistance $R_{o,c2,b}$:
 $r_{c,83} \coloneqq \frac{r_{a,83}}{1 + \mu_{83}}$
 $r_{c,83} = 618.812 \Omega$
 $R_{o,c2,b,83} \coloneqq \left(\frac{1}{r_{c,83}} + \frac{1}{R_{c2,83}}\right)^{-1}$
 $R_{o,c2,b,83} = 615.006 \Omega$
 $r_{c,83,rot} \coloneqq \frac{1}{g_{m,83}}$
 $r_{c,83,rot} \coloneqq 625 \Omega$

3.10.8 C_{c1} calculation:

v.0

$$f_{c} \coloneqq 20Hz \qquad f_{c.opt} \coloneqq \frac{f_{c}}{100} \qquad f_{c.opt} \equiv 0.2 Hz$$

$$C_{c1.83} \coloneqq \frac{1}{2 \cdot \pi \cdot f_{c.opt} \cdot R_{o.c2.b.83}} \qquad C_{c1.83} \equiv 1.294 \times 10^{-2}$$

3.10.9 Total input capacitance C_{i.tot}:

 $C_{i.tot.83} \coloneqq C_{g.a.83} + C_{stray.83} + (1 - G_{cf2.b.83}) \cdot C_{g.c.83} \qquad C_{i.tot.83} = 11.626 \times 10^{-12} F_{cf2.b.83}$



Figure 3.17 = Figure 3.6

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➢ MCD Worksheet III-2

CF2_b calculations







MCD Worksheet III-2 CF2_b calculations

```
T_{tot.2.b.83}(f) \coloneqq T_{i2.b}(f) \cdot T_{o2.b}(f) \cdot G_{cf2.b.83} \qquad \phi_{G.cf2.b.83}(f) \coloneqq 0 \cdot \deg
```

 $T_{\text{tot.}2.b.83.e}(f) \coloneqq 20 \cdot \log(|T_{\text{tot.}2.b.83}(f)|) \qquad \phi_{\text{tot.}2.b.83}(f) \coloneqq \phi_{12.b}(f) + \phi_{02.b}(f) + \phi_{G.cf2.b.83}(f)$

3.10.11 Frequency and phase response plots:



Figure 3.22 Frequency response of the whole CF2_b gain stage



Figure 3.23 Phase response of the whole CF2_b gain stage

➢ MCD Worksheet III-3 CF2_u calculations

3.11 CF2_u-Example with ECC83 / 12AX7 (83):



Figure 3.24 CF2_u example circuitry

3.11.1 Triode bias data:

 $I_{a.83} = 1.2 \cdot 10^{-3} A$ $V_{cc.83} = 370 V$ $V_{a.83} = 370 V$ $V_{g.83} = 122 V$

3.11.2 Triode valve constants:

 $g_{m,83} \coloneqq 1.6 \cdot 10^{-3} \cdot S \qquad \mu_{83} \coloneqq 100 \qquad r_{a,83} \coloneqq 62.5 \cdot 10^{3} \Omega$ $C_{g,c,83} \coloneqq 1.65 \cdot 10^{-12} F \qquad C_{g,a,83} \coloneqq 1.6 \cdot 10^{-12} F \qquad C_{a,c,83} \coloneqq 0.33 \cdot 10^{-12} F$ $C_{o,83} \coloneqq C_{a,c,83} \coloneqq 0.33 \cdot 10^{-12} F$

3.11.3 Circuit variables:

$R_{a.83} := 0.001 \Omega$	$R_{g.83} \coloneqq 1.10^{6} \Omega$	$R_{c1.83} \coloneqq 1.6 \cdot 10^3 \Omega$
$R_{S} := 1 \cdot 10^{3} \Omega$	$R_L := 1 \cdot 10^4 \Omega$	$R_{c2.83} := 100 \cdot 10^3 \Omega$

 $C_{stray.83} \coloneqq 10 \cdot 10^{-12} F$ $C_{in.83} \coloneqq 100 \cdot 10^{-9} F$ $C_{out.83} \coloneqq 100 \cdot 10^{-6} F$

3.11.4 Calculation relevant data:

frequency range f for the below shown graphs:

3.11.5 Gain Gcf2.u:

$$G_{cf2.u.83} \coloneqq \frac{g_{m.83} \left(\frac{1}{r_{a.83}} + \frac{1}{R_{c2.83} + R_{c1.83}}\right)^{-1}}{1 + g_{m.83} \left(\frac{1}{r_{a.83}} + \frac{1}{R_{c2.83} + R_{c1.83}}\right)^{-1}}$$

f := 10Hz, 20Hz.. 20000 Hz h := 1000 Hz

 $R_{gg.83} := 0.22 \cdot 10^3 \Omega$

 $G_{cf2.u.83} = 0.984$

MCD Worksheet III-3 CF2_u calculations ۶

$$G_{cf2.u.83.e} := 20 \cdot \log(G_{cf2.u.83}) \qquad G_{cf2.u.83.e} := -0.139 \quad [dB]$$
3.11.6 Grid input resistance $R_{i,g2.u}$:
 $R_{i,g2.u.83} := \frac{R_{g.83}}{1 - G_{cf2.u.83}} \frac{R_{c2.83}}{R_{c2.83} + R_{c1.83}} \qquad R_{i,g2.u.83} = 31.855 \times 10^{6} \Omega$
3.11.7 Cathode output resistance $R_{o,c2.u}$:
 $r_{c.83} = \frac{r_{a.83}}{1 + \mu_{83}} \qquad r_{c.83} = 618.812 \Omega$
 $R_{o,c2.u.83} := \left(\frac{1}{r_{c.83}} + \frac{1}{R_{c2.83} + R_{c1.83}}\right)^{-1} \qquad R_{o,c2.u.83} = 618.812 \Omega$
 $r_{c.83.rot} := \frac{1}{8m.83} \qquad r_{c.83.rot} = 625 \Omega$
3.11.8 Total input capacitance $C_{i.tot}$:
 $C_{i.tot.83} := C_{g.a.83} + C_{stray.83} + (1 - G_{cf2.u.83}) \cdot C_{g.c.83} \qquad C_{i.tot.83} = 11.626 \times 10^{-12} F$
3.11.9 Gain stage frequency and phase response:
 $F_{i.g.2.u.83} := C_{i.tot} \cdot C_{i.tot} + C_{i.tot} \cdot C_{i.tot} \cdot C_{i.tot} + C_{i.tot} \cdot C_{i.to$

 $\frac{Z2(\mathfrak{f}) \cdot \left(\frac{1}{R_{1,g,2,u,83}} + \frac{1}{R_{gg,83} + Z2(\mathfrak{f})}\right)^{-1}}{\left(Z2(\mathfrak{f}) + R_{gg,83}\right) \cdot \left[R_{S} + Z1(\mathfrak{f}) + \left(\frac{1}{R_{1,g,2,u,83}} + \frac{1}{R_{gg,83} + Z2(\mathfrak{f})}\right)^{-1}\right]}$

 $T_{i2.u}(f) := -$

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MCD Worksheet III-3

CF2_u calculations

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➢ MCD Worksheet III-3 CF2_u calculations



4.1 Circuit diagram



Figure 4.1 Basic design of a Common Grid Gain Stage (CGS)

4.2 Basic formulae (excl. stage load (R_L)-effect)

4.2.1 Gain G_t expressed in terms of $g_{m,t}$ and μ_t :

$$G_{t} = (g_{m.t} r_{a.t} + 1) \frac{R_{a}}{r_{a.t} + R_{a}}$$
(4.1)

$$G_{t} = (\mu_{t} + 1) \frac{R_{a}}{r_{a.t} + R_{a}}$$
(4.2)

4.2.2 Internal cathode input resistance r_{c.t}:

$$r_{c.t} = \frac{r_{a.t} + R_a}{\mu_t + 1}$$
(4.3)

4.2.3 Plate output resistance $R_{o.a}$ and impedance $Z_{o.a}(f)$:

$$R_{o.a} = R_a \| \left[r_{a.t} + (\mu_t + 1) (R_S \| R_c) \right]$$
(4.4)

$$Z_{o.a}(f) = R_a \| \left[r_{a.t} + (\mu_t + 1)(R_S \| R_c) \right] \| C_{o.tot}$$
(4.5)

4.2.4 Cathode input resistance $R_{i,c}$ and impedance $Z_{i,c}(f)$:

$$R_{i.c} = \frac{R_a + r_{a.t}}{\mu_t + 1} \| R_c$$
(4.6)

$$Z_{i,c}(f) = \frac{R_a + r_{a,t}}{\mu_t + 1} \| R_c \| C_{i,tot}$$
(4.7)

4.2.5 Input capacitance Cin:

$$C_{in} = \frac{1}{2\pi f_{c.opt} R_{i.c}}$$
(4.8)

$$f_{c.opt} = \frac{f_c}{100} = \frac{20Hz}{100} = 0.2Hz$$
(4.9)

4.3 Derivations



Figure 4.2 Equivalent circuit of Figure 4.1

4.3.1 Gain Gt and Gt.eff:

sum of currents at node A:

$$\frac{v_o}{R_a} + \frac{v_o - v_i}{r_{a.t}} + g_{m.t} v_{g.c} = i_o$$
(4.10)

AC voltage situation at node C:

$$\mathbf{v}_{g,c} = -\mathbf{v}_i \tag{4.11}$$

we set $i_0 = 0$ and do not take into account R_L , R_S and R_c , hence,

$$\frac{v_o}{R_a} + \frac{v_o - v_i}{r_{a,t}} = g_{m,t} v_i$$
(4.12)

rearrangement leads to the stage gain Gt:

$$G_{t} = \frac{v_{o}}{v_{i}} = \frac{g_{m,t} + \frac{1}{r_{a,t}}}{\frac{1}{r_{a,t}} + \frac{1}{R_{a}}}$$
(4.13)

$$\Rightarrow G_t = (\mu + 1) \frac{R_a}{r_{a.t} + R_a}$$
(4.14)

$$\Rightarrow G_t = \left(g_{m.t} r_{a.t} + 1\right) \frac{R_a}{r_{a.t} + R_a}$$
(4.15)

$R_{a.eff}$ replaces R_a in all calculations that include R_L as gain stage load!

$$\mathbf{R}_{a.eff} = \mathbf{R}_a \parallel \mathbf{R}_L \tag{4.16}$$

$$G_{t.eff} = (\mu + 1) \frac{R_a \parallel R_L}{r_{a.t} + (R_a \parallel R_L)}$$
(4.17)

$$G_{t.eff} = (g_{m.t} r_{a.t} + 1) \frac{R_a \| R_L}{r_{a.t} + (R_a \| R_L)}$$
(4.18)

4.3.2 Internal cathode input impedance $r_{c.t} \text{ and } r_{c.t.eff}$

at node C we find:

$$\mathbf{r}_{\mathrm{c.t}} = \frac{\mathbf{v}_{\mathrm{i}}}{\mathbf{i}_{\mathrm{4}}} \tag{4.19}$$

at node A we find:

$$i_1 = -i_4 = -(i_2 + i_3) \tag{4.20}$$

thus,

$$i_{1} = \frac{v_{o}}{R_{a}} = \frac{v_{i}}{r_{c.t}}$$

$$\Rightarrow \frac{v_{o}}{v_{i}} = G_{t} = \frac{R_{a}}{r_{c.t}}$$
(4.21)

$$r_{c.t} = \frac{R_a}{G_t}$$

$$r_{c.t} = \frac{r_{a.t} + R_a}{\mu + 1}$$
(4.22)

$$r_{c.t.eff} = \frac{R_{a.eff}}{G_{t.eff}}$$
(4.23)

4.3.3 The inclusion of R_{c} and R_{S} into the calculation course:

 $r_{c.t}$ becomes $r_{i.c.t.eff}$ the following way:

$$\mathbf{r}_{i.c.t.eff} = \mathbf{r}_{c.t} \| \mathbf{R}_c \| \mathbf{R}_S \tag{4.24}$$

4.3.4 Total input and output capacitances C_{i.tot} and C_{o.tot}:

As long as the valve is suitable for cascoded operation (eg. 6922 / E88CC, etc.) the input capacitance C_i of the cathode can be found in data sheets under cathode input capacitance C_i in CGS mode:

$$C_i = C_{c.g} \tag{4.25}$$

hence, Ci.tot becomes:

$$C_{i.tot} = C_i \parallel C_{stray} \tag{4.26}$$

The data sheet output capacitance C_o in CGS mode becomes:

$$C_{o} = C_{a.g} \tag{4.27}$$

hence, C_{o.tot} becomes:

$$C_{o.tot} = C_{a.g} \parallel C_{a.c} \tag{4.28}$$

Input and output capacitances in data sheets:

Ci	= CGS input capacitance between cathode and grid	$= C_{c.g}$
	= CCS input capacitance between grid and cathode	$= C_{g.c}$

$$\begin{array}{ll} C_o & = CGS \text{ output capacitance between plate and grid} & = C_{ag} \\ & = CCS \text{ output capacitance between plate and cathode} & = C_{ac} \end{array}$$

4.4 Gain stage frequency and phase response



Figure 4.3 Simplified¹ equivalent circuit of Figure 4.1 - including all frequency and phase response relevant components

4.4.1 Gain stage input transfer function $T_i(f)$ and phase $\phi_i(f)$ - including source resistance R_S :

$$\Gamma_{i}\left(f\right) = \frac{v_{i}}{v_{0}} \tag{4.29}$$

¹ see footnote 3 of Chapter 1

$$\varphi_{i}(f) = \arctan\left\{\frac{\operatorname{Im}[T_{i}(f)]}{\operatorname{Re}[T_{i}(f)]}\right\}$$
(4.30)

$$T_{i}(f) = \frac{\left[\left(\frac{1}{r_{c,t}} + \frac{1}{R_{c}}\right) + 2j\pi f C_{i,tot}\right]^{-1}}{R_{S} + \frac{1}{2j\pi f C_{in}} + \left[\left(\frac{1}{r_{c,t}} + \frac{1}{R_{c}}\right) + 2j\pi f C_{i,tot}\right]^{-1}}$$
(4.31)

4.4.2 Gain stage output transfer function $T_o(f)$:

$$T_{o}(f) = \frac{V_{o}}{V_{a}}$$
(4.32)

$$\varphi_{o}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{o}(f)\right]}{\operatorname{Re}\left[T_{o}(f)\right]}\right\}$$
(4.33)

$$T_{o}(f) = \left(\frac{Z1(f) \| (Z2(f) + R_{L})}{R_{o.a} + [Z1(f) \| (Z2(f) + R_{L})]}\right) \left(\frac{R_{L}}{R_{L} + Z2(f)}\right)$$
(4.34)

$$Z1(f) = (2j\pi f C_{o.tot})^{-1}$$

$$Z2(f) = (2j\pi f C_{out})^{-1}$$
(4.35)

4.4.3 Fundamental gain stage phase shift $\phi_{G.t}(f)$:

$$\varphi_{\mathrm{G},\mathrm{t}}(\mathrm{f}) = 0^{\circ} \tag{4.36}$$

4.4.4 Gain stage transfer function $T_{tot}(f)$ and phase $\phi_{tot}(f)$:

$$T_{tot}(f) = T_i(f) T_o(f) G_t$$
(4.37)

$$\varphi_{\text{tot}}(f) = \varphi_{i}(f) + \varphi_{o}(f) + \varphi_{G,t}(f)$$
(4.38)

4.5

MCD Worksheet IV CGS calculations

1st example with EC92 / 6AB4 (92):

V.cc C.in R.c v.0 Figure 4.4 CGS example circuitry 4.5.1 Triode bias data: $I_{a,92} = 10 \cdot 10^{-3} A$ $V_{cc,92} = 370 V$ $V_{a,92} = 250 V$ $V_{g,92} = -2 V$ 4.5.2 Triode valve constants: $g_{m.92} := 5.6 \cdot 10^{-3} \cdot S$ $\mu_{92} := 60$ $r_{a.92} := 10.7 \cdot 10^3 \Omega$ $C_{i,92} := 4.6 \cdot 10^{-12} F$ $C_{g,a,92} := 1.8 \cdot 10^{-12} F$ $C_{o,92} := 2 \cdot 10^{-12} F$ 4.5.3 Circuit variables: $R_{a,92} := 12 \cdot 10^{3} \Omega$ $R_{c,92} := 0.2 \cdot 10^{3} \Omega$ $R_{L} := 1 \cdot 10^{6} \Omega$ $C_{stray,92} := 10 \cdot 10^{-12} F$ $C_{out,92} := 1 \cdot 10^{-6} F$ $R_S := 50\Omega$ 4.5.4 Calculation relevant data: frequency range f for the below shown graphs: f := 10Hz, 20Hz.. 20000 Hz h := 1000 Hz4.5.5 Gain G_t:

$$\begin{split} G_{92} &\coloneqq \left(\mu_{92} + 1 \right) \cdot \frac{R_{a,92}}{r_{a,92} + R_{a,92}} & G_{92} = 32.247 \\ G_{92,e} &\coloneqq 20 \cdot \log \Bigl(G_{92} \Bigr) & G_{92,e} = 30.17 \quad [dB] \end{split}$$

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4.5.6 Internal cathode input resistance r_{ct}: $r_{c.92} \coloneqq \frac{r_{a.92} + R_{a.92}}{\mu_{92} + 1}$ $r_{c,92} = 372.131 \Omega$ 4.5.7 Plate output resistance R_{0.a}: $R_{o.a.92} \coloneqq \left[\frac{1}{R_{a.92}} + \frac{1}{r_{a.92} + (\mu_{92} + 1) \cdot \left(\frac{1}{R_S} + \frac{1}{R_{o.02}}\right)^{-1}} \right]^{-1} \qquad R_{o.a.92} = 6.272 \times 10^3 \Omega$ 4.5.8 Cathode input resistance R_{i.c}: $R_{i.c.92} := \left(\frac{1}{R_{c.92}} + \frac{1}{r_{c.92}}\right)^{-1}$ $R_{ic.92} = 130.086 \Omega$ 4.5.9 Input capacitance C_{in}: $f_{c.opt} \coloneqq \frac{f_c}{100}$ $f_c := 20Hz$ $f_{c.opt} = 0.2 Hz$ $C_{in.92} \coloneqq \frac{1}{2 \cdot \pi \cdot f_{c \text{ opt}} \cdot R_{ic.92}}$ $C_{in 02} = 6.117 \times 10^{-3} F$ 4.5.10 Total input and output capacitance Ci.tot and Co.tot: $C_{i,tot 92} = 14.6 \times 10^{-12} \,\mathrm{F}$ $C_{i.tot.92} \coloneqq C_{stray.92} + C_{i.92}$ $C_{o.tot.92} = 3.8 \times 10^{-12} F$ $C_{o.tot.92} := C_{g.a.92} + C_{o.92}$

4.5.11 Gain stage frequency and phase response:



$$T_{i}(f) \coloneqq \frac{\left[\left(\frac{1}{r_{c.92}} + \frac{1}{R_{c.92}}\right) + 2j \cdot \pi \cdot f \cdot C_{i.tot.92}\right]^{-1}}{R_{S} + \frac{1}{2j \cdot \pi \cdot f \cdot C_{in.92}} + \left[\left(\frac{1}{r_{c.92}} + \frac{1}{R_{c.92}}\right) + 2j \cdot \pi \cdot f \cdot C_{i.tot.92}\right]^{-1}}$$

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 $T_{tot.92.e}(f) \coloneqq 20 \cdot \log(|T_{tot.92}(f)|)$

 $\phi_{tot.92}(f) \coloneqq \phi_i(f) + \phi_0(f) + \phi_{G.92}(f)$

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Figure 4.11 Phase response of the whole CGS gain stage

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4.6 2nd example with EC92 / 6AB4 (92) with changed circuitry components and valve constants:

4.6.1 Triode bias data (n = new):

 $I_{a.92.n} = 2 \cdot 10^{-3} A$ $V_{cc.92.n} = 370 V$ $V_{a.92.n} = 250 V$ $V_{g.92.n} = -4.4 V$

4.6.2 Triode valve constants:

$g_{m.92.n} \coloneqq 1.6 \cdot 10^{-3} \cdot S$	$\mu_{92.n} := 45$	$r_{a.92.n} \coloneqq 28 \cdot 10^3 \Omega$
$C_{i92,n} := 4.6 \cdot 10^{-12} F$	$C_{g a 92 n} := 1.8 \cdot 10^{-12} F$	$C_{0.92 \text{ n}} \coloneqq 2 \cdot 10^{-12} \text{F}$

4.6.3 Circuit variables:

$R_{a.92.n} \coloneqq 60.10^3 \Omega$	$R_{c.92.n} \coloneqq 2.2 \cdot 10^3 \Omega$	$R_L \coloneqq 1.10^6 \Omega$

 $R_S := 50\Omega$

 $C_{stray.92.n} = 10 \cdot 10^{-12} F$

 $C_{out.92.n} := 1 \cdot 10^{-6} F$

4.6.4 Calculation relevant data:

frequency range f for the below shown graphs:

f := 10Hz, 20Hz.. 20000 Hz

4.6.5 ff:

same calculation course as above leads to an overall gain improvement of appr. 2dB - mainly because of a higher $R_{ic,92}(130R1 \text{ vs. } 1k023)$

Constant current generators as of Figure 5.1 ... 4 ensure stable DC current conditions for any kind of load impedance $R_{L1...4}$. This might be a resistance as well as another valve - including its associated components.

5.1 Constant Current Source (CCSo-lo) - low impedance version



Figure 5.1 CCSo-lo that generates a lower impedance than the Figure 5.3 case

5.1.2 CCSo-lo:

With a rather low-valued R_{e1} (depending on the valve's bias settings) in Figure 5.1 a less complex version of the Figure 5.3 CCSo-hi leads to a lower valued Figure 5.1 resistance $R_{so.1}$ and impedance $Z_{so.1}(f)$.

Based on the derivation course and formulae found in Chapter 1.3 and the following equivalent circuit (see also Figure 1.2) $R_{so.1}$ and $Z_{so.1}(f)$ become:



Figure 5.1-1 Equivalent circuit of the Figure 5.1 current source

$$R_{so.1} = r_{a.v1} + (1 + \mu_{v1}) R_{c1}$$
(5.1)

$$Z_{\text{so.1}}(f) = \left[\left(r_{a.v1} \| C_{a.c.1} \right) + \left(1 + \mu_{v1} \right) \left(R_{c1} \| C_{g.c.1} \right) \right] \| C_{g.a.1} \| C_{\text{stray.1}}$$
(5.2)

5.1.2 DC voltage and current settings:

To get the required anode current $I_{a1} R_{c1}$ sets the right gate voltage V_{g1} according to the following steps:

- step 1 choose Ia1
- step 2 choose V_{a1} at a given V_{cc}

step 3: take V_{g1} from the valve's I_a/V_g vs. V_a characteristics diagram, hence,

$$V_{R,c1} = -V_{g1}$$
 (5.3)

$$R_{c1} = \frac{\left|V_{g1}\right|}{I_{a1}} \tag{5.4}$$

thus, V_{L1} becomes:

$$V_{L1} = V_{cc} - V_{a1} - V_{R.c1}$$
(5.5)



5.2 Constant Current Sink (CCSi-lo) - low impedance version

Figure 5.2 CCSi-lo that generates a lower impedance than the Figure 5.4 case

5.2.1 CCSi-lo:

With a rather low-valued R_{c2} in Figure 5.2 (depending on the valve's bias settings) a less complex version of the Figure 5.4 CCSi-hi leads to a lower valued Figure 5.2 resistance $R_{si,2}$ and impedance $Z_{si,2}(f)$.

Based on the equivalent circuit of the previous section and on the derivation course and formulae found in Chapter 1.3 $R_{si,2}$ and $Z_{si,2}(f)$ become:

$$R_{si,2} = r_{a,v2} + (1 + \mu_{v2}) R_{c2}$$
(5.6)

$$Z_{si,2}(f) = \left[(r_{a,v2} || C_{a,c,2}) + (1 + \mu_{v2}) (R_{c2} || C_{g,c,2}) \right] || C_{g,a,2} || C_{stray,2}$$
(5.7)

5.2.2 DC voltage and current settings:

To get the required anode current $I_{a2} R_{c2}$ sets the right gate voltage V_{g2} according to the following steps:

- step 1 choose Ia2
- step 2 choose V_{a2} at a given V_{cc}
- step 3: take V_{g2} from the valve's I_a/V_g vs. V_a characteristics diagram, hence,

$$V_{R,c2} = -V_{g2}$$
 (5.8)

$$R_{c2} = \frac{\left|V_{g2}\right|}{I_{a2}} \tag{5.9}$$

thus, V_{L2} becomes:

$$V_{L2} = V_{cc} - V_{a2} - V_{R,c2}$$
(5.10)



5.3 Constant Current Source (CCSo-hi) - high impedance version

Figure 5.3 CCSo-hi that generates a higher impedance the Figure 5.1 case
5.3.1 CCSo-hi:

Basically, this rather complex CCG uses the same mechanics like the Figure 5.1 version. Additionally, because of the inclusion of C_{g3} the whole arrangement has to fulfil certain requirements concerning its frequency bandwidth. Otherwise, it would work like the Figure 5.1 version - but with much higher impedance $R_{so.3}$ and $Z_{so.3}(f)$. The following equivalent circuit shows why.

Based on the derivation course and formulae found in Chapter 1.3 and the below shown equivalent circuit (see also Figure 1.2) R_{so3} and Z_{so3} (f) become:



Figure 5.3-1 Equivalent circuit of Figure 5.3 - and its change into a Figure 5.1 type of CCG

$$R_{so.3} = r_{a.v3} + (1 + \mu_{v3}) \left(R_{c3.1} + R_{c3.2} \parallel R_{g3} \right)$$
(5.11)

 $Z_{\text{so.3}}(f) = \left[\left(r_{a,v3} \| C_{a,c,3} \right) + \left(1 + \mu_{v3} \right) \left(\left\{ R_{c3.1} + R_{c3.2} \| R_{g3} \right\} \| C_{g,c,3} \right) \right] \| C_{g,a,3} \| C_{\text{stray.3}}$ (5.12)

- \Rightarrow A high valued R_{c3} automatically leads to a very high valued R_{s0.3}
- \Rightarrow A high valued C_{stray.3} automatically leads to a heavy decrease of Z_{so.3}(f) at frequencies > 1kHz (see MCD Worksheet V-3)

5.3.2 DC voltage and current settings:

To get the required anode current $I_{a3} R_{c3}$ sets the right gate voltage V_{g3} according to the following steps:

- step 1 choose I_{a3}
- step 2 choose V_{a3} at a given V_{cc}
- step 3: take V_{g3} from the valve's I_a/V_g vs. V_a characteristics diagram, hence,

$$V_{R.c3.1} = -V_{g3}$$
(5.13)

$$R_{c3.1} = \frac{|V_{g3}|}{I_{a3}}$$
(5.14)

step 4: choose R_{c3.2}, hence, V_{R.c3.2} becomes:

$$V_{R.c3.2} = I_{a3} R_{c3.2}$$
(5.15)

step 5: calculate V_{L3}:

$$V_{L3} = V_{cc} - V_{a3} - V_{R,c3.1} - V_{R,c3.2}$$
(5.16)

! A voltage V_{L3} too low or too high has to lead to an adaptation of V_{cc} and / or $R_{c3.2}$!

step 6: calculate Cg3, the gain G_{CCSo.hi} and R_{in.3}:

$$C_{g3} = \frac{1}{2\pi f_{c.opt} R_{in.3}}$$
(5.17)

$$f_{c} = 20Hz$$

$$f_{c.opt} = \frac{20Hz}{100}$$
(5.18)

Basically, the CCSo-hi equals a cathode follower type $CF2_u$. But its input is connected via the input capacitance C_{g3} to the bottom lead of $R_{c3.2}$, which acts as an input short-circuit for the $CF2_u$.

Consequently, $R_{\text{in},3}$ can be calculated with the respective formulae of Chapter 3.6.2 \ldots 3.

$$R_{in.3} = \frac{R_{g3}}{1 - G_{CCSo.hi} \frac{\left(R_{c3.2} \parallel R_{g3}\right)}{R_{c3.1} + \left(R_{c3.2} \parallel R_{g3}\right)}}$$
(5.19)
$$G_{CCSo.hi} = \mu_{v3} \frac{R_{c3.1} + \left(R_{c3.2} \parallel R_{g3}\right)}{r_{a.v3} + (1 + \mu_{v3})\left(R_{c3.1} + \left[R_{c3.2} \parallel R_{g3}\right]\right)}$$
(5.20)

It's obvious that at frequencies below $f_{c.opt}$ the impedance of C_{g3} will steadily increase, thus, turning this kind of CCG more and more into a CCSo-lo type of CCG.



5.4 Constant Current Sink (CCSi-hi) - high impedance version

Figure 5.4 CCSi-hi that generates a higher impedance than the Figure 5.2 case

5.4.1 CCSi-hi:

Based on the equivalent circuit of the previous section and on the derivation course and formulae found in Chapter 1.3 $R_{si.4}$ and $Z_{si.4}(f)$ become:

$$R_{si,4} = r_{a,v4} + (1 + \mu_{v4}) R_{c4}$$
(5.21)

$$Z_{si.4}(f) = \left[(r_{a.v4} \parallel C_{a.c.4}) + (1 + \mu_{v4}) (R_{c4} \parallel C_{g.c.4}) \right] \parallel C_{g.a.4} \parallel C_{stray.4}$$
(5.22)

- \Rightarrow A high valued R_{e4} (in conjunction with the right values for R_{g4.1} and R_{g4.2}) automatically leads to a very high valued R_{si.4}.
- \Rightarrow A high valued C_{stray.4} automatically leads to a heavy decrease of Z_{so.4}(f) at frequencies > 1kHz (see MCD Worksheet V-4)

5.4.2 DC voltage and current settings:

To get the required anode current I_{a4} R_{c4} , $R_{g4.1}$ and $R_{g4.2}$ set the right gate voltage V_{g4} according to the following steps:

- step 1: choose I_{a4}
- step 2: choose V_{a4} at a given V_{cc}
- step 3: choose $V_{R.c4}$ and calculate R_{c4} and V_{L4}

$$R_{c4} = \frac{V_{R,c4}}{I_{a4}}$$
(5.23)

$$V_{L4} = V_{cc} - V_{a4} - V_{R.c4}$$
(5.24)

! A voltage V_{L4} too low or too high has to lead to an adaptation of V_{cc} and / or $V_{R,c4}$ and / or R_{c4} !

step 4: take V_{g4} from the valve's I_a/V_g vs. V_a characteristics diagram and calculate $V_{C,g4}$

$$V_{C.g4} = V_{R.c4} + V_{g4}$$
(5.25)

step 5: calculate voltage divider R_{g4.1} and R_{g4.2}:

$$\frac{V_{C.g4}}{V_{cc}} = \frac{R_{g4.1}}{R_{g4.1} + R_{g4.2}}$$
(5.26)

$$\frac{R_{g4.2}}{R_{g4.1}} = \frac{V_{cc}}{V_{C,g4}} - 1$$
(5.27)

$$R_{g4.1} \parallel R_{g4.2} \le \max. \text{ allowed}$$
grid resistance of the value
(5.28)

5.4.3 Calculation of C_{g4}:

$$C_{g4} = \frac{1}{2\pi f_{c.opt} \left(R_{g4.1} \| R_{g4.2} \right)}$$
(5.29)

$$f_{c} = 20 \text{Hz}$$

$$f_{c.opt} = \frac{20 \text{Hz}}{100}$$
(5.30)

 $Z_{si.4}(f)$ wouldn't be touched negatively at the lower end of B_{20k} as long as C_{g4} 's value is high enough, hence, ensuring a flat frequency and phase response of <0.1dB and <1° at 20Hz. If this would not be the case, than, the noise voltage produced by $R_{g4.1} \| R_{g4.2}$ would become a growing negative factor at the output of the current sink. It would be multiplied with the valve's gain and added to the noise voltage of the valve. The amount of noise voltage depends on the lp (formed by C_{g4} and $R_{g4.1} \| R_{g4.2}$) corner frequency f_{noise} and on the size of the two resistors.

Therefore:

$$f_{\text{noise}} \le f_{\text{c.opt}}$$
 (5.31)

MCD Worksheet V-1 CCSo-lo calculations \triangleright

5.5 Constant current source (CCSo-lo) Example with EC92 / 6AB4 (92):



Figure 5.5 CCSo-lo example circuitry

5.5.1 DC voltage & current:

step 1 - choose I a1:

 $I_{a1} := 5 \cdot 10^{-3} A$

step 2 - choose V_{a1} at a given V_{cc} :

 $V_{a1} := 100 V$

step 3 - determine V_{g1} , calculate R_{c1} and V_{L1} :

$$\begin{split} v_{g1} &\coloneqq -0.7V & & V_{R,c1} &\coloneqq -V_g \\ R_{c1} &\coloneqq \frac{|V_{g1}|}{I_{a1}} & & R_{c1} &\equiv 140 \, \Omega \\ V_{L1} &\coloneqq V_{cc} - V_{a1} - V_{R,c1} & & V_{L1} &\equiv 269.3 \, V_{c1} \\ \end{split}$$

 $V_{cc} := 370 V$

5.5.2 Impedances:

Determination of triode valve constants at Ia1 and calculation of R_{so.1} and Z_{so.1}(f):

$$\begin{split} g_{m,92} &\coloneqq 5 \cdot 10^{-3} \cdot S & \mu_{92} &\coloneqq 66 & r_{a,92} &\coloneqq 13.2 \cdot 10^{3} \Omega \\ C_{g,c,92} &\coloneqq 2.2 \cdot 10^{-12} F & C_{g,a,92} &\coloneqq 1.5 \cdot 10^{-12} F & C_{a,c,92} &\coloneqq 0.24 \cdot 10^{-12} F \\ C_{stray,1} &\coloneqq 10 \cdot 10^{-12} F & X_{a,g,1}(f) &\coloneqq 2j \cdot \pi \cdot f \left(C_{g,a,92} + C_{stray,1} \right) \end{split}$$

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MCD Worksheet V-1 CCSo-lo calculations





Figure 5.6 Frequency response of the impedance of the CCSo-lo

MCD Worksheet V-2 CCSi-lo calculations \triangleright



Figure 5.7 CCSi-lo example circuitry

5.6.1 DC voltage & current:

step 1 - choose I_{a2}:

 $I_{a2} := 5 \cdot 10^{-3} A$

step 2 - choose V_{a2} at a given V_{cc}:

 $V_{cc} := 370 V$ $V_{a2} := 100 V$

step 3 - determine V_{g2} , calculate R_{c2} and V_{L2} :

$$V_{g2} \coloneqq -0.7V \qquad V_{R.c2} \coloneqq -V_{g2}$$
$$R_{c2} \coloneqq \frac{|V_{g2}|}{I_{a2}} \qquad R_{c2} \equiv 140 \Omega$$
$$V_{L2} \coloneqq V_{cc} - V_{a2} - V_{R.c2} \qquad V_{L2} \equiv 269.3 V$$

5.6.2 Impedances: Determination of triode valve constants at Ia2 and calculation of R_{si.2} and Z_{si.2}(f):

$g_{m.92} \coloneqq 5 \cdot 10^{-3} \cdot S$	$\mu_{92} := 66$	$\mathbf{r}_{a.92} \coloneqq 13.2 \cdot 10^3 \Omega$
$C_{g.c.92} := 2.2 \cdot 10^{-12} F$	$C_{g.a.92} := 1.5 \cdot 10^{-12} F$	$C_{a.c.92} \coloneqq 0.24 \cdot 10^{-12} F$
$C_{stray.2} \coloneqq 10 \cdot 10^{-12} F$	$X_{g.a.2}(f) := 2j \cdot \pi \cdot f \cdot \left(C_{g.a.92} + C_s\right)$	tray.2)

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Figure 5.8 Frequency response of the impedance of the CCSi-lo

MCD Worksheet V-3 CCSo-hi calculations



MCD Worksheet V-3 CCSo-hi calculations

step 5 - calculate V₁₃: $V_{R,c3,1} \coloneqq -V_{g3}$ $V_{L3} := V_{cc} - V_{a3} - V_{Rc31} - V_{Rc32}$ $V_{L,3} = 103.3 V$ 5.7.2 Impedances & capacitances: 5.7.2.1 Determination of triode valve constants at I_{a3}: $r_{a 92} := 13.2 \cdot 10^3 \Omega$ $g_{m 92} := 5 \cdot 10^{-3} \cdot S$ $\mu_{92} := 66$ $C_{g.c.92} := 2.2 \cdot 10^{-12} F$ $C_{g.a.92} := 1.5 \cdot 10^{-12} F$ $C_{a.c.92} := 0.24 \cdot 10^{-12} F$ $C_{strav.3} := 10 \cdot 10^{-12} F$ $R_{\alpha3} \coloneqq 1.10^6 \Omega$ Other calculation relevant data: frequency range f for the below shown graphs: f := 10Hz, 20Hz.. 100000 Hz $h := 1000 \cdot Hz$ 5.7.2.2 step 6 Calculation of C c3: $f_{c.opt} = 0.2 Hz$ $f_c := 20Hz$ $f_{c.opt} := f_c \cdot 0.01$ $G_{\text{CCSo,hi,3}} \coloneqq \mu_{92} \cdot \frac{R_{c3.1} + \left(\frac{1}{R_{c3.2}} + \frac{1}{R_{g3}}\right)^{-1}}{r_{a.92} + \left(1 + \mu_{92}\right) \cdot \left[R_{c3.1} + \left(\frac{1}{R_{c3.2}} + \frac{1}{R_{g3}}\right)^{-1}\right]} \quad G_{\text{CCSo,hi,3}} = 0.979$ $R_{in.3} = 3.976 \times 10^7 \Omega$ $R_{in,3} := \frac{R_{g3}}{\left(\frac{1}{R_{c3,2}} + \frac{1}{R_{g3}}\right)^{-1}} \frac{\left(\frac{1}{R_{c3,2}} + \frac{1}{R_{g3}}\right)^{-1}}{\left[R_{c3,1} + \left(\frac{1}{R_{c3,2}} + \frac{1}{R_{c3}}\right)^{-1}\right]}$ $C_{g3} \coloneqq \frac{1}{2 \cdot \pi \cdot f_{c} \text{ opt} \cdot R_{in 3}}$ $C_{\alpha 3} = 20.013 \times 10^{-9} F$

MCD Worksheet V-3 CCSo-hi calculations



Figure 5.10 Frequency response of the impedance of the CCSo-hi

MCD Worksheet V-4 CCSi-hi calculations



MCD Worksheet V-4 CCSi-hi calculations

5.8.2 Impedances & capacitances: 5.8.2.1 Calculation of C $_{g4}$: $f_c := 20Hz$ $f_{c opt} \coloneqq 0.01 \cdot 20 Hz$ $f_{c opt} = 0.2 Hz$ $C_{g4} \coloneqq \frac{1}{2 \cdot \pi \cdot f_{c.opt} \cdot \left(\frac{1}{R_{o4,1}} + \frac{1}{R_{o4,2}}\right)^{-1}}$ $C_{\alpha 4} = 1.088 \times 10^{-6} F$ 5.8.2.2 Determination of triode valve constants at I_{a4}: $r_{a 92} := 1.2 \cdot 10^3 \Omega$ $g_{m 92} := 5 \cdot 10^{-3} \cdot S$ $\mu_{92} := 66$ $C_{g,c,92} \coloneqq 2.2 \cdot 10^{-12} F$ $C_{g,a,92} \coloneqq 1.4 \cdot 10^{-12} F$ $C_{a,c,92} \coloneqq 0.24 \cdot 10^{-12} F$ $C_{stray.4} = 10 \cdot 10^{-12} F$ $X_{g.a.4}(f) := 2j \cdot \pi \cdot f \cdot \left(C_{g.a.92} + C_{stray.4}\right)$ Other calculation relevant data: frequency range f for the below shown graphs: f := 10Hz, 20Hz.. 100000 Hz $h := 1000 \cdot Hz$ 5.8.2.3 Calculation of R_{si4} and Z_{si4} (f): $R_{si.4} := r_{a.92} + (1 + \mu_{92}) \cdot R_{c.4}$ $R_{si\,4} = 1.341 \times 10^6 \Omega$ $Z_{\text{si},4}(f) := \left[\left[\left(\frac{1}{r_{a,92}} + 2j \cdot \pi \cdot f \cdot C_{a,c,92} \right)^{-1} + \left(1 + \mu_{92} \right) \left[\frac{1}{R_{c,4}} + \left(2j \cdot \pi \cdot f \cdot C_{g,c,92} \right)^{-1} \right]^{-1} + X_{g,a,4}(f) \right]^{-1} \right]^{-1} + X_{g,a,4}(f) \right]^{-1}$ $|Z_{si,4}(h)| = 1.335 \times 10^{6} \Omega$ $1.5 \cdot 10^{6}$ 1.10^{6} $\frac{1}{2}$ 5.10⁵ 0 1.10^{3} 1.10^{4} 10 100 1.10^{5} [Hz]

Figure 5.12 Frequency response of the impedance of the CCSi-hi

6.1 Circuit diagram



Figure 6.1 Basic design of the Cascode Amplifier Gain Stage (CAS)

6.2 Basic assumptions

Generally, the whole CAS gain stage consists of a CCS or CCS-Cc gain stage (V1 with gain G1) of Chapters 1 or 2 with a CGS gain stage (V2 with gain G2) as the plate load (alternatively, the gain of V1 can be increased by adding a resistor parallel to V2 plus $R_{a,2}$, thus, increasing the DC current of V1 as well).

 $V_{g,2}$ sets the V2 biasing DC voltage, thus, defining the DC plate current I_a of both valves. $R_{c,1}$ has to be chosen adequately.

To get all relevant formulae shown further down these lines the following assumption were made:

- V1 equals V2 (ideal case: double triode)
- plate current V1 = plate current V2
- $g_{m.v1} = g_{m.v2} = g_{m.t}$
- $\mathbf{r}_{a.v1} = \mathbf{r}_{a.v2} = \mathbf{r}_{a.t}$
- $\mu_{v1} = \mu_{v2} = \mu_t$
- $R_{c2} = R_{c1} = R_c$
- bypassed version (b): R_{c1} = bypassed by C_{c1}
- un-bypassed version (u): $R_{c1} = un-bypassed$

6.3 Basic formulae (excl. stage load (R_L)-effect)

$$G_{cas} = G1G2 \tag{6.1}$$

6.3.1 bypassed version - gain G_{cas.b}:

$$G_{cas.b} = -\mu_t \left(\mu_t + 1\right) \frac{R_a}{(\mu_t + 2)r_{a.t} + R_a}$$
(6.2)

rule of thumb for Gcas.b:

$$G_{\text{cas.b.rot}} \approx -g_{\text{m.t}} R_a$$
 (6.3)

6.3.2 un-bypassed version - gain G_{cas.u}:

$$G_{cas.u} = -\mu_t \frac{R_a + r_{a.t}}{R_a + r_{a.t} (\mu_t + 2) + R_{c1} (\mu_t^2 + \mu_t + 2)}$$
(6.4)

6.3.3 V2 plate output resistance $R_{0.a2}$ and impedance $Z_{0.a2}(f)$:

$$R_{o.a2.b} = \left(\frac{1}{R_a} + \frac{1}{r_{a.t}(\mu_t + 2)}\right)^{-1}$$
(6.5)

$$R_{o.a2.u} = \left(\frac{1}{R_a} + \frac{1}{r_{a.t}(\mu_t + 2) + (\mu_t + 1)^2 R_{c1}}\right)^{-1}$$
(6.6)

$$Z_{o.a2.b}(f) = R_a \| C_{a.g2} \| \left[(r_{a.t} \| C_{o.1}) + (\mu_t + 1)(r_{a.t} \| C_{o.2}) \right]$$
(6.7)

$$Z_{o,a2.u}(f) = R_{a} \| C_{a,g2} \| \left\{ \left(\left[r_{a,v1} + (\mu_{v1} + 1) R_{c1} \right] \| C_{o,1} \right) + \left[\left(r_{a,v2} + (\mu_{v2} + 1) \left\{ r_{a,v1} + (\mu_{v1} + 1) R_{c1} \right\} \right) \| C_{o,2} \right] \right\}$$
(6.8)

6.4 Derivations



Figure 6.2 Simplified equivalent circuit of the CAS gain stage

6.4.1 Gains:

We do not need a rather complex equivalent circuit to describe the gain mechanics of the CAS gain stage. Without big extra derivation efforts all gains can be derived from Figure 6.2 plus the respective formulae given in the previous chapters.

 $G1_b$ is a CCS+Cc gain stage with AC-grounded cathode à la Chapter 2. $G1_u$ is a CCS gain stage à la Chapter 1. G2 is a CGS gain stage à la Chapter 4. As the V1 plate load the internal cathode resistance of the CGS (V2) gain stage sets the gain G1.

6.4.1.1 bypassed version:

the internal cathode resistance $r_{c.v2}$ of the upper valve V2 becomes:

$$\mathbf{r}_{c.v2} = \frac{\mathbf{r}_{a.v2} + \mathbf{R}_{a2}}{\mu_{v2} + 1} \tag{6.9}$$

the gain of a CCS+Cc gain stage becomes¹:

¹ see Chapter 2

$$Gl_{b} = -g_{m.v1}(r_{a.v1} || r_{c.v2})$$
(6.10)

$$Gl_{b} = -\mu_{v1} \frac{r_{c.v2}}{r_{a.v2} + r_{c.v2}}$$
(6.11)

thus, G1_b becomes:

$$Gl_{b} = -\mu_{t} \frac{r_{a,t} + R_{a}}{(\mu_{t} + 2)r_{a,t} + R_{a}}$$
(6.12)

G2 becomes²:

$$G2 = (\mu_t + 1) \frac{R_a}{r_{a.t} + R_a}$$
(6.13)

hence, G_{cas.b} becomes:

$$G_{cas.b} = G1_{b} G2$$

= $-\mu_{t} (\mu_{t} + 1) \frac{R_{a}}{(\mu_{t} + 2) r_{a.t} + R_{a}}$ (6.14)

rule of thumb for G_{cas.b}:

$$G_{\text{cas.b.rot}} \approx -\mu_t \frac{R_a}{r_{a.t} + \frac{R_a}{1 + \mu_t}}; \frac{1}{1 + \mu_t} << 1$$

$$\approx -\mu_t \frac{R_a}{r_{a.t}}$$
(6.15)

$$G_{cas.b.rot} \approx -g_{m.t} R_a$$
 (6.16)

un-bypassed version: 6.4.1.2

the gain of a CCS gain stage becomes³

$$Gl_{u} = -\mu_{v1} \frac{r_{c.v2}}{r_{a.v1} + r_{c.v2} + (\mu_{v1} + 1)R_{c1}}$$
(6.17)

thus, G1_u becomes:

$$Gl_{u} = -\mu_{t} \frac{r_{a.t} + R_{a}}{r_{a.t} (\mu_{t} + 2) + R_{a} + (\mu_{t} + 2) R_{c1} + {\mu_{t}}^{2} R_{c1}}$$
(6.18)

2 see Chapter 4 see Chapter 1

³

hence, G_{cas.u} becomes:

$$G_{cas.u} = G1_{u} G2$$

= $-\mu_{t} \frac{R_{a} + r_{a.t}}{R_{a} + r_{a.t} (\mu_{t} + 2) + R_{c1} (\mu_{t}^{2} + \mu_{t} + 2)}$ (6.19)

rule of thumb for G_{cas.u}: n. a.

6.4.2 Specific resistances and impedances:

6.4.2.1 bypassed version - output resistances and impedances at the plates of V1 and V2:

V1&V2 o/p resistance $R_{o.a1.b}^{4}$ and $R_{o.a2.b}$ and V2 o/p impedance $Z_{o.a2.b}(f)$:

$$\mathbf{R}_{\mathbf{0},\mathbf{a}\mathbf{1},\mathbf{b}} = \mathbf{r}_{\mathbf{a},\mathbf{v}\mathbf{1}} \tag{6.20}$$

According to Chapter 4 the o/p resistance $R_{o.a2,b}$ at the plate of V2 becomes:

$$R_{o,a2,b} = R_{a2} \| \left[r_{a,v2} + (\mu_{v2} + 1) r_{a,v1} \right]$$
(6.21)

$$\mathbf{R}_{o.a2.b} = \mathbf{R}_{a} \parallel \left[\mathbf{r}_{a.t} \left(\boldsymbol{\mu}_{t} + 2 \right) \right]$$
(6.22)

$$Z_{o.a2.b}(f) = R_a \| C_{a.g2} \| \left[(r_{a.t} \| C_{o.1}) + (\mu_t + 1)(r_{a.t} \| C_{o.2}) \right]$$
(6.23)

since $C_{o.1} = C_{o.2} = C_o$ $Z_{o.a2,b}(f)$ becomes:

$$Z_{o,a2,b}(f) = R_a \| \left[(r_{a,t} \| C_o) (\mu_t + 2) \right]$$
(6.24)

6.4.2.2 un-bypassed version - output resistances and impedances at the plates of V1 and V2:

V1&V2 o/p resistance $R_{o.a1.u}^{5}$ and $R_{o.a2.u}$ and V2 o/p impedance $Z_{o.a2.u}(f)$:

$$R_{o.a1.u} = r_{a.v1} + (1 + \mu_{v1})R_{c1}$$
(6.25)

According to Chapter 4 and with the respective equation from Chapter 1 $R_{o.a2.u}$ becomes:

$$R_{o.a2.u} = R_{a2} \| \left[r_{a.v2} + (\mu_{v2} + 1) r_{o.a.v1} \right]$$
(6.26)

⁴ see Chapter 2

⁵ see Chapter 1

$$\mathbf{r}_{o.a.v1} = \mathbf{r}_{a.v1} + (\mu_{v1} + 1) \mathbf{R}_{c1}$$
(6.27)

$$R_{o.a2.u} = R_a \| \left[r_{a.t} \left(\mu_t + 2 \right) + \left(\mu_t + 1 \right)^2 R_{c1} \right]$$
(6.28)

$$Z_{o,a2.u}(f) = R_{a} \| C_{a,g2} \| \begin{cases} \left(\left[r_{a,v1} + (\mu_{v1} + 1) R_{c1} \right] \| C_{o,1} \right) + \\ \left[\left(r_{a,v2} + (\mu_{v2} + 1) \left\{ r_{a,v1} + (\mu_{v1} + 1) R_{c1} \right\} \right) \| C_{o,2} \right] \end{cases}$$
(6.29)

since $C_{o.1} = C_{o.2} = C_o$ $Z_{o.a2.u}(f)$ becomes:

$$Z_{o,a2.u}(f) = R_{a} \|C_{a,g2}\| \left\{ \begin{bmatrix} r_{a,t} + (\mu_{t} + 1)R_{c1} \end{bmatrix} \|C_{o} + \left[r_{a,t}(\mu_{t} + 2) + (\mu_{t} + 1)^{2}R_{c1} \right] \|C_{o} \right\}$$
(6.30)

6.4.3 Role of R_L:

In the above given formulae it is assumed that $R_L >> R_{a2}$, thus, not disturbing significantly the above shown calculation course. But a relatively small value of R_L should lead to new calculations of all formulae by replacing R_a with $R_{a.eff}$.

$$R_{a2.eff} = \frac{R_{a2} R_L}{R_{a2} + R_L}$$
(6.31)

6.5 Total input capacitance $C_{i.tot}$, total output capacitance $C_{o.tot}$ and cathode capacitance $C_{c.1}$

6.5.1 Input capacitances:

One of the advantages of the CGS gain stage is the rather low value of the input capacitance because of the very low gain |G1| of V1⁶. Hence⁷,

$$C_{i.1.tot,b} = \left[\left(1 + |Gl_b| \right) C_{g.a.v1} \right] \| C_{i.v1} \| C_{stray.1}$$
(6.32)

$$C_{i.1.tot.u} = \left[\left(1 + |GI_u| \right) C_{g.a.v1} \right] \| C_{i.v1} \| C_{stray.1}$$
(6.33)

$$C_{i.2.tot} = C_{i.v2} \parallel C_{stray.2}$$
 (6.34)

6.5.2 Total output capacitance C_{o.tot}:

$$C_{0.1.tot} = C_{0.1} \| C_{g,a1}$$
(6.35)

$$C_{o.2.tot} = C_{o.2} \parallel C_{g.a2}$$
(6.36)

6.5.3 Input and output capacitances in data sheets:

Ci	= CGS input capacitance between cathode and grid	$= C_{g.c}$
	= CCS input capacitance between grid and cathode	$= C_{g.c}$

Co	= CGS output capacitance between plate and grid	$= C_{g.a}$
	= CCS output capacitance between plate and cathode	$= C_{a,c}$

6.5.4 Capacitance C_{c1}⁸:

C_{c1} becomes⁹:

$$C_{c1} = \frac{1}{2\pi f_{c.opt} R_{o.c1}}$$
(6.37)

$$R_{o.c1} = r_{c1} \parallel R_{c1}$$
(6.38)

$$r_{c1} = \frac{r_{a.v1} + r_{c2}}{\mu_{v1} + 1}$$
(6.39)

$$r_{c2} = \frac{r_{a.v2} + R_{a2}}{\mu_{v2} + 1} \tag{6.40}$$

⁶ see MCD Worksheet VI - 6.7.8

⁷ for $C_{\text{stray.1}}$ and $C_{\text{stray.2}}$ (also $C_{i.1.\text{tot}}$ and $C_{i.2.\text{tot}}$) see footnote 2 of Chapter 1

⁸ see MCD Worksheet VI - 6.7.7 & 6.7.8

⁹ see respective formulae of Chapters 2 and 4

6.6 Gain stage frequency and phase response calculations

6.6.1 Bypassed version



Figure 6.3 Simplified¹⁰ equivalent circuit of Figure 6.1 (bypassed version) - including all frequency and phase response relevant components

6.6.1.1 1^{st} stage (V1 = V1_c+V1_a) input transfer function $T_{i.1.b}(f)$ and phase $\varphi_{i.1.b}(f)$ - including source resistance R_s and an oscillation preventing resistor $R_{ggl} \ll R_{gl}$:

$$T_{i.1.b}(f) = \frac{v_{g.1}}{v_0}$$
(6.41)

$$T_{i.1.b}(f) = \frac{Z2_{b}(f) \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{b}(f)}\right)^{-1}}{\left(R_{gg1} + Z2_{b}(f)\right) \left[R_{S} + Z1(f) + \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{b}(f)}\right)^{-1}\right]}$$
(6.42)

$$Z1(f) = (2j\pi f C_{in})^{-1}$$

$$Z2_{b}(f) = (2j\pi f C_{i1 \text{ tot } b})^{-1}$$
(6.43)

$$\varphi_{i.1.b}(f) = \arctan\left\{\frac{\text{Im}\left[T_{i.1.b}(f)\right]}{\text{Re}\left[T_{i.1.b}(f)\right]}\right\}$$
(6.44)

6.6.1.2 1^{st} stage V1_c cathode transfer function $T_{c.1.b}(f)$ and phase $\varphi_{c.1.b}(f)$:

$$T_{c.1.b}(f) = \frac{R_{o.cl}}{R_{o.cl} + \frac{1}{2j\pi f C_{cl}}}$$
(6.45)

$$\varphi_{c.1.b}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{c.1.b}(f)\right]}{\operatorname{Re}\left[T_{c.1.b}(f)\right]}\right\}$$
(6.46)

¹⁰ concerning C_{0.2} see footnote 3 of Chapter 1, concerning "simplified" see footnote 3 of Chapter 2

6.6.1.3 1^{st} stage output transfer function $T_{o.1.b}(f)$ and phase $\varphi_{o.1.b}(f)$:

$$T_{o.1.b}(f) = \frac{v_{c.2}}{v_{a.1}}$$
(6.47)

$$T_{o.1.b}(f) = \frac{Z3(f)}{R_{o.a1.b} + Z3(f)}$$
(6.48)

$$Z3(f) = \left[2j\pi f \left(C_{0.1.tot} + C_{1.2.tot}\right)\right]^{-1}$$
(6.49)

$$\varphi_{o.1.b}(f) = \arctan\left\{\frac{\text{Im}\left[T_{o.1.b}\left(f\right)\right]}{\text{Re}\left[T_{o.1.b}\left(f\right)\right]}\right\}$$
(6.50)

6.6.1.4 2^{nd} stage output transfer function $T_{o.2.b}(f)$ and phase $\phi_{o.2.b}(f)$:

$$T_{o.2.b}(f) = \frac{v_o}{v_{a.2}}$$
(6.51)

$$T_{o.2.b}(f) = \left(\frac{Z4(f) \| (Z5(f) + R_L)}{R_{o.a.2.b} + [Z4(f) \| (Z5(f) + R_L)]}\right) \left(\frac{R_L}{R_L + Z5(f)}\right)$$
(6.52)

$$Z4(f) = (2j\pi f C_{o.2.tot})^{-1}$$

Z5(f) = (2j\pi f C_{out})^{-1} (6.53)

$$\varphi_{o.2.b}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{o.2.b}(f)\right]}{\operatorname{Re}\left[T_{o.2.b}(f)\right]}\right\}$$
(6.54)

6.6.1.5 1^{st} stage fundamental phase shift $\varphi_{G,v1}(f)$:

$$\varphi_{G.v1}(f) = \varphi_{G.cas.b}(f) = -180^{\circ}$$
 (6.55)

6.6.1.6 total gain stage transfer function $T_{tot,b}(f)$ and phase $\varphi_{tot,b}(f)$:

$$T_{tot.b}(f) = T_{i.1.b}(f) T_{c.1.b}(f) T_{o.1.b}(f) T_{o.2.b}(f) G_{cas.b}$$
(6.56)

$$\varphi_{\text{tot,b}}(f) = \varphi_{i.1.b}(f) + \varphi_{c.1.b}(f) + \varphi_{o.1.b}(f) + \varphi_{o.2.b}(f) + \varphi_{G.cas.b}(f)$$
(6.57)

6.6.2 Un-bypassed version



Figure 6.4 Simplified¹¹ equivalent circuit of Figure 6.1 (un-bypassed version) - including all frequency and phase response relevant components

$$T_{i.1.u}(f) = \frac{v_{g.1}}{v_0}$$
(6.58)

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$$T_{i.1.u}(f) = \frac{Z2_{u}(f) \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{u}(f)}\right)^{-1}}{\left(R_{gg1} + Z2_{u}(f)\right) \left[R_{S} + Z1(f) + \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{u}(f)}\right)^{-1}\right]}$$
(6.59)

$$Z1(f) = (2j\pi f C_{in})^{-1}$$

$$Z2_{u}(f) = (2j\pi f C_{i.1.tot.u})^{-1}$$
(6.60)

$$\varphi_{i.1.u}(f) = \arctan\left\{\frac{\text{Im}\left[T_{i.1.u}\left(f\right)\right]}{\text{Re}\left[T_{i.1.u}\left(f\right)\right]}\right\}$$
(6.61)

6.6.2.2 1^{st} stage output transfer function $T_{o.1.u}(f)$ and phase $\varphi_{o.1.u}(f)$:

$$T_{o.1.u}(f) = \frac{v_{c.2}}{v_{a.1}}$$
(6.62)

$$T_{o.1.u}(f) = \frac{Z3(f)}{R_{o.a1.b} + Z3(f)}$$
(6.63)

$$Z3(f) = \left[2j\pi f(C_{o.1.tot} || C_{i.2.tot})\right]^{-1}$$
(6.64)

¹¹ concerning C_{0.1} and C_{0.2} see footnote 3 of Chapter 1 concerning C_{i.1.tot} and C_{i.2.tot} see footnote 2 of Chapter 1

$$\varphi_{o.1.u}(f) = \arctan\left\{\frac{\text{Im}\left[T_{o.1.u}\left(f\right)\right]}{\text{Re}\left[T_{o.1.u}\left(f\right)\right]}\right\}$$
(6.65)

6.6.2.3 2^{nd} stage output transfer function $T_{o.2.u}(f)$ and phase $\phi_{o.2.u}(f)$:

$$T_{o.2.u}(f) = \frac{v_o}{v_{a.2}}$$
(6.66)

$$T_{o.2.u}(f) = \left(\frac{Z4(f) \| (Z5(f) + R_L)}{R_{o.a2.u} + [Z4(f) \| (Z5(f) + R_L)]}\right) \left(\frac{R_L}{R_L + Z5(f)}\right)$$
(6.67)

$$Z4(f) = (2j\pi f C_{o.2.tot})^{-1}$$

Z5(f) = (2j\pi f C_{out})^{-1} (6.68)

$$\varphi_{o.2.u}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{o.2.u}(f)\right]}{\operatorname{Re}\left[T_{o.2.u}(f)\right]}\right\}$$
(6.69)

6.6.2.4 1^{st} stage fundamental phase shift $\varphi_{G,v1}(f)$:

$$\varphi_{G.v1}(f) = \varphi_{G.cas.u}(f) = -180^{\circ}$$
 (6.70)

6.6.2.5 total gain stage transfer function $T_{tot.u}(f)$ and phase $\varphi_{tot.u}(f)$:

$$T_{tot.u}(f) = T_{i.1.u}(f) T_{o.1.u}(f) T_{o.2.u}(f) G_{cas.u}$$
(6.71)

$$\varphi_{\text{tot.u}}(f) = \varphi_{i.1.u}(f) + \varphi_{o.1.u}(f) + \varphi_{o.2.u}(f) + \varphi_{G.cas.u}(f)$$
 (6.72)

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6.7.4 Calculation relevant data:

frequency range f for the below shown graphs:

6.7.5 Gain G_{cas.b} :

$$\begin{split} & G1_{188,b} \coloneqq - \left[\mu_{188} \cdot \frac{r_{a.188} + R_{a2.188}}{(\mu_{188} + 2) \cdot r_{a.188} + R_{a2.188}} \right] \\ & G1_{188,b,e} \coloneqq 20 \cdot \log(\left| G1_{188,b} \right|) \\ & G2_{188} \coloneqq (\mu_{188} + 1) \frac{R_{a2.188}}{r_{a.188} + R_{a2.188}} \\ & G2_{188,e} \coloneqq 20 \cdot \log(\left| G2_{188} \right|) \\ & G_{cas.188,b} \coloneqq G1_{188,b} \cdot G2_{188} \end{split}$$

$$G_{cas.188.b.e} \approx 20 \cdot \log(|G_{cas.188.b}|)$$

 $G_{cas.188.b.rot} := -g_{m.188} \cdot R_{a2.188}$

$$G_{cas.188.b.rot.e} \coloneqq 20 \cdot \log(|G_{cas.188.b.rot}|)$$

$$G_{cas,188,b,e} - G_{cas,188,b,rot,e} = -1.31 \times 10^{\circ}$$
 [dB

6.7.6 Gain G_{cas.188.u}:

$$Gl_{188.u} \coloneqq -\mu_{188} \cdot \frac{r_{a.188} + R_{a2.188}}{r_{a.188} \cdot (\mu_{188} + 2) + R_{a2.188} + (\mu_{188}^2 + \mu_{188} + 2)R_{c1.188}}$$

$$Gl_{188.u} \coloneqq -1.724 \times 10^0$$

$$Gc_{as.188.u} \coloneqq -45.71 \times 10^0$$

$$Gc_{as.188.u} \equiv -477.788 \times 10^0 \Omega$$

$$r_{c2} \coloneqq \frac{4.100 - 42.100}{\mu_{188} + 1}$$
 $r_{c2} = 477.788$

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[dB]

 $G1_{188.b.e} = 12.615 \times 10^0$

f := 10Hz, 20Hz.. 100000 Hz

 $h := 1000 \cdot Hz$

 $G2_{188} = 26.512 \times 10^0$

 $G1_{188.b} = -4.273 \times 10^{0}$

$$G2_{188.e} = 28.469 \times 10^0$$
 [dB]

$$G_{cas.188.b} = -113.295 \times 10^{\circ}$$

 $G_{cas.188.b.e} = 41.084 \times 10^0$ [dB]

 $G_{cas.188.b.rot} = -131.737 \times 10^{0}$

$$G_{cas.188.b.rot.e} = 42.394 \times 10^{0}$$

$$_{188 \text{ h e}} - G_{\text{cas } 188 \text{ h rot e}} = -1.31 \times 10^0$$
 [dB]

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$$R_{0,c1} := \left[\left(\frac{r_{a,188} + r_{c2}}{\mu_{188} + 1} \right)^{-1} + \frac{1}{R_{c1,188}} \right]^{-1} \qquad R_{0,c1} = 65.427 \times 10^{0} \Omega$$

$$R_{0,a1,188,u} = r_{a,188} + (\mu_{188} + 1) \cdot R_{c1,188} \qquad R_{0,a1,188,u} = 8.545 \times 10^{3} \Omega$$

$$R_{0,a2,188,b} := \left[\frac{1}{r_{a,188} (\mu_{188} + 2)} + \frac{1}{R_{a2,188}} \right]^{-1} \qquad R_{0,a2,188,b} = 11.308 \times 10^{3} \Omega$$

$$R_{0,a2,188,u} := \left[\frac{1}{r_{a,188} (\mu_{188} + 2)} + (\mu_{188} + 1)^{2} \cdot R_{c1,188} + \frac{1}{R_{a2,188}} \right]^{-1} \qquad R_{0,a2,188,u} = 12.128 \times 10^{3} \Omega$$

$$R_{0,a2,188,u} := \left[\frac{1}{r_{a,188} (\mu_{188} + 2)} + (\mu_{188} + 1)^{2} \cdot R_{c1,188} + \frac{1}{R_{a2,188}} \right]^{-1} \qquad R_{0,a2,188,u} = 12.128 \times 10^{3} \Omega$$
6.7.8 Specific input and output capacitances:

$$C_{1,110t,188,b} := (1 + |G1_{188,b}|) \cdot C_{g,a1,188} + C_{g,c1,188} + C_{stray,188,1} \\ C_{1,110t,188,u} := (1 + |G1_{188,u}|) \cdot C_{g,a1,188} + C_{g,c1,188} + C_{stray,188,1} \\ C_{1,110t,188,u} := (1 + |G1_{188,u}|) \cdot C_{g,a1,188} + C_{g,c1,188} + C_{stray,188,1} \\ C_{1,110t,188,u} := (1 + |G1_{188,u}|) \cdot C_{g,a1,188} + C_{g,c1,188} + C_{stray,188,1} \\ C_{1,110t,188,u} := (1 + |G1_{188,u}|) \cdot C_{g,a1,188} + C_{g,c1,188} + C_{stray,188,1} \\ C_{1,110t,188,u} := (2 - 2 + 188 + C_{g,a2,188} \\ C_{0,1,10t,188} := C_{0,2,188} + C_{g,a2,188} \\ C_{0,1,10t,188} := C_{0,2,188} + C_{g,a2,188} \\ C_{0,2,10t,188} := 2.0 \times 10^{-12} F \\ f_{c} := 2.0 Hz \\ C_{c1} := \frac{1}{2\pi \cdot f_{c,opt} \cdot R_{0,c1}} \\ C_$$

Figure 6.6 = Figure 6.3

 $Z1(f) := \frac{1}{2j \cdot \pi \cdot f \cdot C_{\text{in}, 188}}$

 $Z2_{b}(f) \coloneqq \frac{1}{2j \cdot \pi \cdot f \cdot C_{i,1,tot,188,b}}$

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 $T_{o.1.b.e}(f) \coloneqq 20 \cdot \log(\left|T_{o.1.b}(f)\right|)$

$$\Psi_{0.1.b}(1) := \operatorname{atan}\left(\frac{\operatorname{Re}(T_{0.1.b}(f))}{\operatorname{Re}(T_{0.1.b}(f))}\right)$$

 $T_{0.1.b.e}(h) = -604.234 \times 10^{-9} \quad [dB]$





 $T_{tot.188.b}(f) := T_{i.1.b}(f) \cdot T_{c.1.b}(f) T_{o.1.b}(f) \cdot T_{o.2.b}(f) \cdot G_{cas.188.b}$

$$T_{tot. 188.b.e}(f) := 20 \cdot \log(|T_{tot. 188.b}(f)|)$$

 $\phi_{G.188}(f) := -180 \text{deg}$

 $\phi_{\text{tot.}188,b}(f) := \phi_{i,1,b}(f) + \phi_{c,1,b}(f) + \phi_{o,1,b}(f) + \phi_{o,2,b}(f) + \phi_{G,188}(f)$

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 $\phi_{\text{tot.}188.u}(f) \coloneqq \phi_{i.1.u}(f) + \phi_{o.1.u}(f) + \phi_{o.2.u}(f) + \phi_{G.188}(f)$

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1.103

f [Hz]

100

Figure 6.17 Phase responses of the bypassed and un-bypassed CAS gain stage

 1.10^{4}

 1.10^{5}

 $\frac{\phi_{\text{tot. 188. u}}(f)^{-180}}{\phi_{\text{tot. 188. u}}(f)}$ deg

-185

-190

10

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Figure 6.18 Input impedances for the bypassed and un-bypassed versions

7.1 Circuit diagram



Figure 7.1 Basic design of the Shunt Regulated Push-Pull Gain Stage (SRPP)

7.2 Basic assumptions

Generally, the whole SRPP gain stage consists of a CCS or CCS+Cc gain stage (V1 with gain G1) of Chapters 1 or 2 with an active constant current source of Chapter 5.1 as the plate load (CCSo-lo with V2 and gain G2). This active load also acts like an improved cathode follower $CF2_u$ of Chapter 3.5. In this connection the impedance of the Figure 7.1 V1 plus R_{c1}/C_{c1} form the resistance $R_{c.2}$ of Figure 3.4.

To get all relevant formulae shown further down these lines the following assumption were made:

- V1 equals V2 (ideal case: double triode)
- plate current V1 = plate current V2
- $g_{m.v1} = g_{m.v2} = g_{m.t}$
- $\mathbf{r}_{a.v1} = \mathbf{r}_{a.v2} = \mathbf{r}_{a.t}$
- $\mu_{v1} = \mu_{v2} = \mu_t$
- $R_{c2} = R_{c1} = R_c$
- bypassed version (b): R_{c1} = bypassed by C_{c1}
- un-bypassed version (u): $R_{c1} = un-bypassed$

7.3 Basic formulae (excl. stage load (R_L)-effect)

$$G_{srpp} = G1G2 \tag{7.1}$$

7.3.1 bypassed version - gain G_{srpp.b} in terms of g_{m.t}:

$$G_{srpp,b} = Gl_b G2_b$$

$$Gl_b = -g_{m,t} \frac{r_{a,t} \left[r_{a,t} + (1 + g_{m,t}r_{a,t}) R_c \right]}{2r_{a,t} + (1 + g_{m,t}r_{a,t}) R_c}$$

$$G2_b = \frac{g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{R_c + r_{a,t}} \right)^{-1}}{1 + g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{R_c + r_{a,t}} \right)^{-1}}$$
(7.2)

bypassed version - gain $G_{srpp.b}$ in terms of μ_t :

$$G_{srpp.b} = -\mu_t^2 \frac{\left[r_{a.t} + (1+\mu_t)R_c\right](R_c + r_{a.t})}{\left[2r_{a.t} + (1+\mu_t)R_c\right]\left[2r_{a.t} + (1+\mu_t)R_c + \mu_t r_{a.t}\right]}$$
(7.3)

rule of thumb for G_{srpp.b}:

$$G2_{b.rot} = 1$$

$$G_{srpp.b.rot} = \mu_t \frac{r_{a.t} + (1 + \mu_t) R_c}{2r_{a.t} + (1 + \mu_t) R_c}$$
(7.4)

7.3.2 un-bypassed version - gain $G_{srpp.u}$ in terms of $g_{m.t}$ and μ_t :

$$G_{srpp.u} = Gl_{u} G2_{u}$$

$$Gl_{u} = -\frac{1}{2}g_{m.t}r_{a.t}$$

$$G2_{u} = \frac{g_{m.t}\left(\frac{1}{r_{a.t}} + \frac{1}{r_{a.t} + (2 + \mu_{t})R_{c}}\right)^{-1}}{1 + g_{m.t}\left(\frac{1}{r_{a.t}} + \frac{1}{r_{a.t} + (2 + \mu_{t})R_{c}}\right)^{-1}}$$
(7.5)

rule of thumb for Gsrpp.u:

$$G2_{u,rot} = 1$$

$$G_{srpp.u.rot} = -\frac{1}{2}\mu_t$$
(7.6)

7.3.3 bypassed version - V2 cathode output resistance Ro.c.v2.b:

$$R_{o.c.v2.b} = r_{a.t} \left[\frac{r_{a.t} + R_c}{(2 + \mu_t) r_{a.t} + (1 + \mu_t) R_c} \right]$$
(7.7)

7.3.4 un-bypassed version - V2 cathode output resistance Roc.v2.u:

$$R_{o.c.v2.u} = r_{a.t} \left[\frac{r_{a.t} + (2 + \mu_t) R_c}{(2 + \mu_t) r_{a.t} + (2 + 3\mu_t + {\mu_t}^2) R_c} \right]$$
(7.8)

7.3.5 V1-R_{c1} bypass capacitance C_{c1}:

To get a flat frequency response in B_{20k} as well as a phase response deviation of $<1^\circ$ at 20Hz C_{c1} should be calculated as follows:

$$C_{c1} = \frac{1}{\pi f_{c.opt}} \frac{\left[r_{a.t} + (1 + \mu_t) R_c\right]}{\left[2r_{a.t} + (1 + \mu_t) R_c\right] R_c}$$
(7.9)

$$f_{c.opt} = 0.2 Hz$$
 (7.10)
7.4 Derivations



Figure 7.2 Equivalent circuit of Figure 7.1



Figure 7.3 Simplified equivalent circuit of Figure 7.2

7.4.1 Gains:

Instead of producing a lot of equations derived from Figure 7.2 to get the respective gain formulae we take the much easier to handle Figure 7.3. It shows that the SRPP gain stage is made of two gain blocks G1 and G2.

 $G1_b$ is a CCS+Cc gain stage with AC-grounded cathode à la Chapter 2. $G1_u$ is a CCS gain stage à la Chapter 1. G2 is an improved cathode follower $CF2_u$ à la Chapter 3.5 as well as a constant current source (CCSo-lo) à la Chapter 5.1. The impedance of the SRPP's V1 plus its components form the $CF2_u$'s lower cathode resistance R_{c2} whereas R_{c2} of the Figure 7.1 SRPP forms the $CF2_u$'s upper cathode resistance R_{c1} .

Without big extra derivation efforts the respective formulae of the chapters mentioned can be used to calculate the gains $G_{srpp,b}$ or $G_{srpp,u}$.

7.4.1.1 bypassed version:

with the upper valve's active AC resistance R_{v2} (seen from node A1):

$$R_{v2} = r_{a.t} + (1 + g_{m.t}r_{a.t})R_c$$
(7.11)

in terms of g_{m.t} G_{srpp.b} becomes:

$$Gl_{b} = -g_{m,t} \left(R_{v2} \| r_{a,t} \right)$$
(7.12)

$$Gl_{b} = -g_{m.t} \left(\frac{1}{R_{v2}} + \frac{1}{r_{a.t}} \right)^{-1}$$
 (7.13)

$$Gl_{b} = -g_{m.t} \frac{r_{a.t} \left[r_{a.t} + (1 + g_{m.t} r_{a.t}) R_{c} \right]}{2r_{a.t} + (1 + g_{m.t} r_{a.t}) R_{c}}$$
(7.14)

$$G2_{b} = \frac{g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{R_{c} + r_{a,t}}\right)^{-1}}{1 + g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{R_{c} + r_{a,t}}\right)^{-1}}$$
(7.15)

$$G_{\text{srpp.b}} = Gl_b G2_b \tag{7.16}$$

$$G_{srpp.b} = -g_{m.t}^{2} \frac{r_{a.t}^{2} [r_{a.t} + (1 + g_{m.t}r_{a.t}) R_{c}] (R_{c} + r_{a.t})}{[2r_{a.t} + (1 + g_{m.t}r_{a.t}) R_{c}] [2r_{a.t} + (1 + g_{m.t}r_{a.t}) R_{c} + g_{m.t}r_{a.t}^{2}]}$$
(7.17)

since $\mu_t = g_{m,t} * r_{a,t}$ in terms of $\mu_t G_{srpp,b}$ becomes:

$$G_{srpp.b} = -\mu_t^2 \frac{\left[r_{a.t} + (1+\mu_t)R_c\right](R_c + r_{a.t})}{\left[2r_{a.t} + (1+\mu_t)R_c\right]\left[2r_{a.t} + (1+\mu_t)R_c + \mu_t r_{a.t}\right]}$$
(7.18)

7.4.1.2 un-bypassed version:

in terms of $g_{m.t} G_{srpp.u}$ becomes:

$$Gl_{u} = -g_{m.t} \frac{r_{a.t} R_{v2}}{r_{a.t} + R_{v2} + (1 + g_{m.t} r_{a.t})R_{c}}$$
(7.19)

$$Gl_{u} = -\frac{1}{2}g_{m.t} r_{a.t}$$
(7.20)

since $\mu_t = g_{m,t} * r_{a,t}$ in terms of $\mu_t G1_u$ becomes:

$$G1_{u} = -\frac{1}{2}\mu_{t}$$
(7.21)

$$G2_{u} = \frac{g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{r_{a,t} + (2 + \mu_{t}) R_{c}} \right)^{-1}}{1 + g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{r_{a,t} + (2 + \mu_{t}) R_{c}} \right)^{-1}}$$
(7.22)

$$G_{\text{srpp.u}} = Gl_u G2_u \tag{7.23}$$

7.4.2 Specific resistances and capacitance C_{c1}:

7.4.2.1 bypassed version - V1 plate output resistances R_{o.a.v1.b}:

$$R_{o.a.v1.b} = r_{a.t} \tag{7.24}$$

V2 cathode resistance $r_{c.v2}$:

$$r_{c.v2} = \frac{r_{a.t}}{\mu_t + 1}$$
(7.25)

V2 cathode load resistance R1_b:

$$Rl_b = r_{a.t} + R_c \tag{7.26}$$

output resistance R_{o.c.v2.b}:

$$R_{o.c.v2.b} = Rl_{b} || r_{c.v2}$$

$$= \left(\frac{1}{Rl_{b}} + \frac{1}{r_{c.v2}}\right)^{-1}$$
(7.27)

$$R_{o.c.v2.b} = r_{a.t} \left[\frac{r_{a.t} + R_c}{r_{a.t} (2 + \mu_t) + R_c (1 + \mu_t)} \right]$$
(7.28)

7.4.2.3 V1 bypass capacitance C_{c1}:

sine R_{v2} is:

$$R_{v2} = r_{a,t} + (\mu_t + 1) R_c$$
(7.29)

V1 cathode resistance r_{c.v1} becomes:

$$\mathbf{r}_{c.v1} = \frac{\mathbf{r}_{a.t} + \mathbf{R}_{v2}}{1 + \mu_t} \tag{7.30}$$

V1 cathode resistance R_{c.v1}becomes:

$$R_{c.v1} = r_{c.v1} || R_c$$

= $\left(\frac{1}{r_{c.v1}} + \frac{1}{R_c}\right)^{-1}$ (7.31)

and capacitance Cc1 becomes:

$$C_{c1} = \frac{1}{2\pi f_{c.opt} R_{c.v1}}$$
(7.32)

$$\Rightarrow C_{c1} = \frac{1}{\pi f_{c.opt}} \frac{\left[r_{a.t} + (1 + \mu_t) R_c\right]}{\left[2r_{a.t} + (1 + \mu_t) R_c\right] R_c}$$
(7.33)

7.4.2.4 un-bypassed version - V1 anode output resistance R_{o.a.v1.u}:

$$R_{o.a.v1.u} = r_{a.t} + (1 + \mu_t) R_c$$
(7.34)

7.4.2.5 un-bypassed version - V2 cathode output resistance R_{o.c.v2.u}:

V2 cathode resistance rc.v2:

$$r_{c.v2} = \frac{r_t}{\mu_t + 1}$$
(7.35)

V2 cathode load resistance R1_u:

$$Rl_{u} = r_{a.t} + (2 + \mu_{t})R_{c}$$
(7.36)

output resistance Ro.c.v2.b:

$$R_{o.c.v2.u} = R1_{u} || r_{c.v2}$$
$$= \left(\frac{1}{R1_{u}} + \frac{1}{r_{c.v2}}\right)^{-1}$$
(7.37)

$$R_{o.c.v2.u} = r_{a.t} \left[\frac{r_{a.t} + (2 + \mu_t) R_c}{(2 + \mu_t) r_{a.t} + (2 + 3\mu_t + \mu_t^2) R_c} \right]$$
(7.38)

7.5 Input capacitances C_{i,v1} and C_{i,v2} Output capacitances C_{0,v1} and C_{0,v2}

data sheet figures:	$\begin{array}{l} C_{g.c.v1} = \mbox{grid-cathode capacitance of V1} \\ C_{g.a.v1} = \mbox{grid-plate capacitance of V1} \\ C_{a.c.v1} = \mbox{plate-cathode capacitance of V1} \\ C_{g.c.v2} = \mbox{grid-cathode capacitance of V2} \\ C_{g.a.v2} = \mbox{grid-plate capacitance of V2} \\ C_{a.c.v2} = \mbox{plate-cathode capacitance of V2} \\ \end{array}$
to be guessed:	$\begin{array}{l} C_{stray.l} = sum \ of \ stray \ capacitances \ around \ V1 \\ C_{stray.2} = sum \ of \ stray \ capacitances \ around \ V2 \end{array}$
to be ignored ¹ :	$C_{o,c,v2}$ = cathode capacitance of V2

Note: the Miller capacitance of the input depends on V1's gain G1 only²!

$$C_{i,v1,b} = (1 + |G1_b|)C_{g,a,v1} || C_{g,c,v1} || C_{stray,1}$$
(7.39)

$$C_{i,v1.u} = (1 + |G1_u|) C_{g.a.v1} || C_{g.c.v1} || C_{stray.1}$$
(7.40)

$$C_{i,v2,b} = (1 - G_{2_b}) C_{g,c,v2} \| C_{g,a,v2} \| C_{stray,2}$$
(7.41)

$$C_{i,v2.u} = (1 - G_{2u})C_{g.c.v2} \| C_{g.a.v2} \| C_{stray.2}$$
(7.42)

$$C_{o.v1} = C_{a.c.v1} \| C_{g.a.v1} \| C_{g.a.v2}$$
(7.43)

$$C_{o.v2} = C_{a.c.v2}$$
 (7.44)

7.6 Input impedance Z_{in}

$$Z_{in}(f) = R_{g1} \| C_{i,v1}$$
(7.45)

Inclusion of $R_{\rm gg}$ and $C_{\rm in}$ into the calculation course leads to:

$$Z_{\text{in.b}}(f) = \left[\left(R_{gg} + \frac{1}{2j\pi f C_{i.v1.b}} \right)^{-1} + \frac{1}{R_{g1}} \right]^{-1} + \frac{1}{2j\pi f C_{in}}$$
(7.46)

$$Z_{\text{in.u}}(f) = \left[\left(R_{gg} + \frac{1}{2j\pi f C_{i.v1.u}} \right)^{-1} + \frac{1}{R_{g1}} \right]^{-1} + \frac{1}{2j\pi f C_{in}}$$
(7.47)

 $^{^1}$ to be ignored in B_{20k} only because - compared with the size of the corresponding capacitances - the output impedance is rather low

² Miller capacitance effects on C_i and C_o : see Chapter 1.3.2.5

7.7 Gain stage frequency and phase response calculations

7.7.1 Bypassed version:



Figure 7.4 Simplified³ equivalent circuit of Figure 7.1 (bypassed version) - including all frequency and phase response relevant components

7.7.1.1 1^{st} stage (V1 = V1_c+V1_a) input transfer function $T_{i,1,b}(f)$ and phase $\varphi_{i,1,b}(f)$ - including source resistance R_s and an oscillation preventing resistor $R_{gg} << R_g$.

$$T_{i.1.b}(f) = \frac{v_{g.1}}{v_0}$$
(7.48)

1

$$\varphi_{i.1.b}(\mathbf{f}) = \arctan\left\{\frac{\mathrm{Im}\left[\mathrm{T}_{i.1.b}\left(\mathbf{f}\right)\right]}{\mathrm{Re}\left[\mathrm{T}_{i.1.b}\left(\mathbf{f}\right)\right]}\right\}$$
(7.49)

$$T_{i,1,b}(f) = \frac{Z2_{b}(f) \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{b}(f)}\right)^{-1}}{\left(R_{gg1} + Z2_{b}(f)\right) \left[R_{S} + Z1(f) + \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{b}(f)}\right)^{-1}\right]}$$
(7.50)
$$Z1(f) = (2j\pi f C_{in})^{-1}$$
(7.51)
$$Z2_{b}(f) = (2j\pi f C_{i,v1,b})^{-1}$$
(7.51)

7.7.1.2 1^{st} stage V1_c cathode transfer function $T_{c.1.b}(f)$ and phase $\varphi_{c.1.b}(f)$:

$$\varphi_{c.1.b}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{c.1.b}(f)\right]}{\operatorname{Re}\left[T_{c.1.b}(f)\right]}\right\}$$
(7.52)

$$T_{c.1.b}(f) = \frac{R_{c.v1}}{R_{c.v1} + \frac{1}{2j\pi f C_{c.1}}}$$
(7.53)

3

See also footnotes 2 and 3 of Chapter 1 and footnote 3 of Chapter 2

7.7.1.3 1^{st} stage output transfer function $T_{o.1.b}(f)$ and phase $\varphi_{o.1.b}(f)$:

$$T_{o.1.b}(f) = \frac{v_{g.2}}{v_{a.1}}$$
(7.54)

$$\varphi_{o.1.b}(f) = \arctan\left\{\frac{\mathrm{Im}\left[\mathrm{T}_{o.1.b}(f)\right]}{\mathrm{Re}\left[\mathrm{T}_{o.1.b}(f)\right]}\right\}$$
(7.55)

$$T_{o.1.b}(f) = \frac{Z3_{b}(f)}{R_{o.a.1.b} + Z3_{b}(f)}$$
(7.56)

$$Z3_{b}(f) = \left[2j\pi f(C_{o.v1} + C_{i.v2.b})\right]^{-1}$$
(7.57)

7.7.1.4 2^{nd} stage output transfer function $T_{o.2.b}(f)$ and phase $\varphi_{o.2.b}(f)$:

$$T_{o.2.b}(f) = \frac{v_o}{v_{c.2}}$$
(7.58)

$$\varphi_{o.2.b}(f) = \arctan\left\{\frac{\mathrm{Im}\left[T_{o.2.b}(f)\right]}{\mathrm{Re}\left[T_{o.2.b}(f)\right]}\right\}$$
(7.59)

$$T_{o.2.b}(f) = \frac{R_L}{R_{o.c.v2.b} + R_L + Z4(f)}$$
(7.60)

$$Z4(f) = (2j\pi f C_{out})^{-1}$$
(7.61)

7.7.1.5 1^{st} stage fundamental phase shift $\varphi_{G.v1}(f)$:

$$\varphi_{G.v1}(f) = \varphi_{G.srpp.b}(f) = -180^{\circ}$$
(7.62)

7.7.1.6 total gain stage transfer function $T_{tot,b}(f)$ and phase $\phi_{tot,b}(f)$:

$$T_{tot.b}(f) = T_{i.1.b}(f) T_{c.1.b}(f) T_{o.1.b}(f) T_{o.2.b}(f) Gl_b G2_b$$
(7.63)

$$\varphi_{\text{tot,b}}(f) = \varphi_{i.1.b}(f) + \varphi_{c.1.b}(f) + \varphi_{o.1.b}(f) + \varphi_{o.2.b}(f) + \varphi_{G.srpp.b}(f)$$
 (7.64)

7.7.2 Un-bypassed version:



Figure 7.5 Simplified⁴ equivalent circuit of Figure 7.1 (un-bypassed version) - including all frequency and phase response relevant components

7.7.2.1 1^{st} stage (V1) input transfer function $T_{i,1,u}(f)$ and phase $\varphi_{i,1,u}(f)$ - including source resistance R_s and an oscillation preventing resistor $R_{gg} \ll R_g$:

$$T_{i.1.u}(f) = \frac{v_{g.1}}{v_0}$$
(7.65)

$$\varphi_{i.1.u}(\mathbf{f}) = \arctan\left\{\frac{\mathrm{Im}\left[\mathrm{T}_{i.1.u}\left(\mathbf{f}\right)\right]}{\mathrm{Re}\left[\mathrm{T}_{i.1.u}\left(\mathbf{f}\right)\right]}\right\}$$
(7.66)

$$T_{i.1.u}(f) = \frac{Z2_{u}(f) \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{u}(f)}\right)^{-1}}{\left(R_{gg1} + Z2_{u}(f)\right) \left[R_{S} + Z1(f) + \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{u}(f)}\right)^{-1}\right]}$$
(7.67)
$$Z1(f) = (2j\pi f C_{in})^{-1}$$
$$Z2_{u}(f) = (2j\pi f C_{i,v1.u})^{-1}$$
(7.68)

7.7.2.2 1^{st} stage output transfer function $T_{o.1.u}(f)$ and phase $\phi_{o.1.u}(f)$:

$$T_{o.1.u}(f) = \frac{v_{g.2}}{v_{a.1}}$$
(7.69)

$$\varphi_{o.1.u}(f) = \arctan\left\{\frac{\text{Im}\left[T_{o.1.u}(f)\right]}{\text{Re}\left[T_{o.1.u}(f)\right]}\right\}$$
(7.70)

$$T_{o.1.u}(f) = \frac{Z3_u(f)}{R_{o.a.1.b} + Z3_u(f)}$$
(7.71)

⁴ See also footnotes 2 and 3 of Chapter 1

$$Z3_{u}(f) = \left[2j\pi f(C_{o,v1} + C_{i,v2.u})\right]^{-1}$$
(7.72)

7.7.2.3 2^{nd} stage output transfer function $T_{o.2.u}(f)$ and phase $\phi_{o.2.u}(f)$:

$$T_{o.2.u}(f) = \frac{v_o}{v_{c.2}}$$
(7.73)

$$\varphi_{o.2.u}(f) = \arctan\left\{\frac{\operatorname{Im}[T_{o.2.u}(f)]}{\operatorname{Re}[T_{o.2.u}(f)]}\right\}$$
(7.74)

$$T_{o.2.u}(f) = \frac{R_L}{R_{o.c.v2.u} + R_L + Z4(f)}$$
(7.75)

$$Z4(f) = (2j\pi f C_{out})^{-1}$$
(7.76)

7.7.2.4 1^{st} stage fundamental phase shift $\varphi_{G,v1}(f)$:

$$\varphi_{G.v1}(f) = \varphi_{G.srpp.u}(f) = -180^{\circ}$$
(7.77)

7.7.2.5 total gain stage transfer function $T_{tot.u}(f)$ and phase $\varphi_{tot.u}(f)$:

$$T_{tot.u}(f) = T_{i.1.u}(f) T_{o.1.u}(f) T_{o.2.u}(f) Gl_u G2_u$$
(7.78)

$$\varphi_{\text{tot.u}}(f) = \varphi_{i.1.u}(f) + \varphi_{o.1.u}(f) + \varphi_{o.2.u}(f) + \varphi_{G.srpp.u}(f)$$
(7.79)

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7.8.4 Calculation relevant data: frequency range f for the below shown graphs: f := 10Hz, 20Hz.. 100000 Hz $h := 1000 \cdot Hz$ 7.8.5 Gain G_{srpp.83.b}: $R_{v2} := r_{a.v2} + (1 + \mu_{v2}) \cdot R_{c2.83}$ $R_{12} = 100.743 \times 10^3 \Omega$ $Gl_b := -g_{m.83} \cdot \left(\frac{1}{R_{y2}} + \frac{1}{r_{2,83}} \right)^{-1}$ via V1 $G1_{\rm h} = -64.415 \times 10^0$ $G2_{b} := \frac{g_{m,v2} \left(\frac{1}{r_{a,v2}} + \frac{1}{R_{c2,83} + r_{a,v1}}\right)^{-1}}{1 + g_{m,v2} \left(\frac{1}{r_{a,v2}} + \frac{1}{R_{c2,83} + r_{a,v1}}\right)^{-1}}$ via V2 $G2_{\rm h} = 980.744 \times 10^{-3}$ $G_{srpp 83 b} = -63.174 \times 10^{0}$ $G_{srpp.83.b} \coloneqq G1_b \cdot G2_b$ $G_{\text{srpp.83.b.e}} := 20 \cdot \log(|G_{\text{srpp.83.b}}|)$ $G_{srmp 83 he} = 36.011 \times 10^0 [dB]$ $G_{srpp 83 h rot} = -64.415 \times 10^{0}$ $G_{srpp.83.b.rot} := G1_b$ $G_{srpp.83.b.rot.e} = 36.18 \times 10^0 [dB]$ $G_{\text{srpp.83.b.rot.e}} \coloneqq 20 \cdot \log(|G_{\text{srpp.83.b.rot}}|)$ $G_{srpp.83.b.e} - G_{srpp.83.b.rot.e} = -168.887 \times 10^{-3}$ 7.8.6 Gain G_{srpp.83.u}: $G1_{u} := -\frac{1}{2} \cdot g_{m.83} \cdot r_{a.83}$ $G1_{...} = -50.75 \times 10^{0}$ $G2_{u} \coloneqq \frac{g_{m,v2} \left[\frac{1}{r_{a,v2}} + \frac{1}{R_{c2.83} + r_{a.v1} + (1 + \mu_{v1}) \cdot R_{c1.83}} \right]^{-1}}{1 + g_{m,v2} \left[\frac{1}{r_{a.v2}} + \frac{1}{R_{c2.83} + r_{a.v1} + (1 + \mu_{v1}) \cdot R_{c1.83}} \right]^{-1}} \qquad G2_{u} = 984.736 \times 10^{-3}$ $G_{srmp 83 \mu} = -49.975 \times 10^{0}$ $G_{srpp.83.u} \coloneqq G1_u \cdot G2_u$ $G_{\text{srmp 83 u.e}} = 33.975 \times 10^0$ $G_{\text{srpp.83.u.e}} \coloneqq 20 \cdot \log(|G_{\text{srpp.83.u}}|)$ [dB] $G_{srpp 83 \mu rot} = -50.75 \times 10^{0}$ $G_{srpp.83.u.rot} := G1_u$ $G_{srpp.83.u.rot.e} = 34.109 \times 10^{0} [dB]$ $G_{\text{srpp.83.u.rot.e}} := 20 \cdot \log(|G_{\text{srpp.83.u.rot}}|)$ $G_{srpp.83.u.e} - G_{srpp.83.u.rot.e} = -133.607 \times 10^{-3}$

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7.8.7 Specific resistances: $R_{o.a.v1.b} \coloneqq r_{a.v1}$ $R_{o.a.v1.u} := r_{a.v1} + (1 + \mu_{v1}) \cdot R_{c1.83}$ $R_{0.0,v1,v} = 100.743 \times 10^3 \Omega$ $\mathbf{r}_{c.v1} \coloneqq \frac{\mathbf{r}_{a.v1} + \mathbf{R}_{v2}}{1 + \mu_{v1}}$ $\mathbf{R}_{c.v1} := \left(\frac{1}{\mathbf{r}_{c.v1}} + \frac{1}{\mathbf{R}_{c1.83}}\right)^{-1}$ $r_{c.v2} := \frac{r_{a.v2}}{1 + \mu_{v2}}$ $Rl_b := r_{a.v1} + R_{c2.83}$ $R_{0.c.v2.b} := \left(\frac{1}{Rl_b} + \frac{1}{r_{c.v2}}\right)^{-1}$ $Rl_{u} := r_{a.v1} + (1 + \mu_{v1}) \cdot R_{c1.83} + R_{c2.83}$ $R1_{u} = 101.159 \times 10^{3} \Omega$ $R_{0.c.v2.u} := \left(\frac{1}{Rl_u} + \frac{1}{r_{c.v2}}\right)^{-1}$ 7.8.8 Capacitance C_{c1}:

$$f_{c} := 20Hz \qquad f_{c.opt} := \frac{f_{c}}{100} \qquad f_{c.opt} = 200 \times 10^{-3} Hz$$

$$C_{c1} := \frac{1}{2 \cdot \pi \cdot f_{c.opt} \cdot R_{c.v1}} \qquad C_{c1} = 2.422 \times 10^{-3} F$$

7.8.9 Specific input and output capacitances:
$$C_{i,v1,b} \coloneqq (1 + |G1_b|) \cdot C_{g.a.1.83} + C_{g.c.1.83} + C_{stray.83.1}$$
 $C_{i,v1,b} = 116.314 \times 10^{-12} F$ $C_{i,v1,u} \coloneqq (1 + |G1_u|) \cdot C_{g.a.1.83} + C_{g.c.1.83} + C_{stray.83.1}$ $C_{i,v1,u} = 94.45 \times 10^{-12} F$ $C_{i,v2,b} \coloneqq (1 - G2_b) \cdot C_{g.a.2.83} + C_{g.c.2.83} + C_{stray.83.2}$ $C_{i,v2,b} = 11.681 \times 10^{-12} F$ $C_{i,v2,u} \coloneqq (1 - G2_u) \cdot C_{g.a.2.83} + C_{g.c.2.83} + C_{stray.83.2}$ $C_{i,v2,u} = 11.674 \times 10^{-12} F$ $C_{i,v2,u} \coloneqq (1 - G2_u) \cdot C_{g.a.2.83} + C_{g.c.2.83} + C_{stray.83.2}$ $C_{i,v2,u} = 11.674 \times 10^{-12} F$ $C_{o,v1} \coloneqq C_{a,c.1.83} + C_{g.a.1.83} + C_{g.a.2.83}$ $C_{o,v2} \coloneqq C_{a,c.2.83}$

$$c_{c,v1} = 1.549 \times 10^{3} \Omega$$

$$R_{c,v1} = 328.539 \times 10^{0} \Omega$$

$$c_{c,v2} = 565.854 \times 10^{0} \Omega$$

$$R_{b} = 58.417 \times 10^{3} \Omega$$

$$R_{o.c.v2.b} = 560.425 \times 10^{\circ} \Omega$$

$$R_{o.c.v2.u} = 562.706 \times 10^{9} \Omega$$

$$f_{c.opt} = 200 \times 10^{-3} Hz$$

 $C_{c1} = 2.422 \times 10^{-3} F$

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Figure 7.10 Transfer of V1 cathode network





 $\frac{\phi_{c.1.b}(f)}{\text{deg}}$ _2 $\cdot 10^3 \ 1 \cdot 10^4 \ 1 \cdot 10^5$ 10 100 [Hz]

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$$o.1.b(f) \coloneqq \frac{Z3_b(f)}{R_{o.a.v1.b} + Z3_b(f)}$$

$$T_{o.1.b.e}(f) \coloneqq 20 \cdot \log(|T_{o.1.b}(f)|)$$







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 $T_{tot 83 b}(f) := T_{i1b}(f) \cdot T_{c1b}(f) T_{o1b}(f) \cdot T_{o2b}(f) \cdot G_{1b}(f) \cdot G_{2b}(f)$ $T_{tot.83.b.e}(f) := 20 \cdot \log(|T_{tot.83.b}(f)|)$ $\phi_{G,83}(f) := -180 \deg$ $\phi_{\text{tot.83.b}}(f) := \phi_{i.1.b}(f) + \phi_{c.1.b}(f) + \phi_{o.1.b}(f) + \phi_{o.2.b}(f) + \phi_{G.83}(f)$ 7.8.11 Gain stage frequency and phase response - un-bypassed version: -01 Figure 7.16 = Figure 7.5 $Z2_{u}(f) := \frac{1}{2j \cdot \pi \cdot f \cdot C_{i v 1 u}}$ $\frac{Z2_{u}(f) \cdot \left(\frac{1}{R_{g1.83}} + \frac{1}{R_{gg1.83} + Z2_{u}(f)}\right)^{-1}}{\left(Z2_{u}(f) + R_{gg1.83}\right) \left[R_{S} + Z1(f) + \left(\frac{1}{R_{g1.83}} + \frac{1}{R_{gg1.83} + Z2_{u}(f)}\right)^{-1}\right]}$ $T_{i,1,u}(f) := Z3_{u}(f) := \frac{1}{2j \cdot \pi \cdot f \cdot \left(C_{o,v1} + C_{j,v2,u}\right)}$ $\phi_{i,1,u}(f) := \operatorname{atan}\left(\frac{\operatorname{Im}(T_{i,1,u}(f))}{\operatorname{Re}(T_{i,1,u}(f))}\right)$ $T_{0.1.u}(f) := \frac{Z3_u(f)}{R_{0.3.v1.u} + Z3_u(f)}$ $\phi_{0.1.u}(f) \coloneqq atan \left(\frac{Im \left(T_{0.1.u}(f) \right)}{Re \left(T_{0.1.u}(f) \right)} \right)$ $\phi_{0,2,u}(f) \coloneqq \operatorname{atan}\left(\frac{\operatorname{Im}(T_{0,2,u}(f))}{\operatorname{Re}(T_{0,2,u}(f))}\right)$ $T_{0.2.u}(f) := \frac{R_L}{R_0 c v^2 u^+ R_L + Z4(f)}$ $\mathsf{T}_{\text{tot.}\,83.u}(\mathsf{f}) \coloneqq \mathsf{T}_{i.1.u}(\mathsf{f}) \,\mathsf{T}_{o.1.u}(\mathsf{f}) \cdot\mathsf{T}_{o.2.u}(\mathsf{f}) \cdot\mathsf{G1}_u \cdot\mathsf{G2}_u$ $T_{tot.83.u.e}(f) := 20 \cdot \log(|T_{tot.83.u}(f)|)$ $\phi_{G,83}(f) := -180 \deg$ $\phi_{\text{tot. 83.u}}(f) := \phi_{1,1,u}(f) + \phi_{0,1,u}(f) + \phi_{0,2,u}(f) + \phi_{G,83}(f)$

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Figure 7.18 Phase responses of the bypassed and un-bypassed SRPP gain stage

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Figure 7.19 Input impedances for the bypassed and un-bypassed versions

8.1 Circuit diagram



Figure 8.1 Basic design of the μ -Follower Gain Stage

8.2 Basic assumptions

Generally, the whole μ -F gain stage consists of a CCS or CCS+Cc gain stage (V1 with gain G1) of Chapters 1 or 2 with an active constant current source (CCSo-hi with V2 and gain G2) of Chapter 5.3 as the plate load. This active load also acts like an improved cathode follower CF2_u of Chapter 3.5. In this connection the impedance of the Figure 8.1 V1 plus R_{c1}/C_{c1} form the resistance R_{c2} of Figure 3.4.The output voltage of V1 is fed to the input (grid) of V2 via C_{g2}.

To get all relevant formulae shown further down these lines the following assumption were made:

- V1 equals V2 (ideal case: double triode)
- plate current V1 = plate current V2
- $g_{m.v1} = g_{m.v2} = g_{m.t}$
- $\mathbf{r}_{a.v1} = \mathbf{r}_{a.v2} = \mathbf{r}_{a.t}$
- $\mu_{v1} = \mu_{v2} = \mu_t$
- $R_{c1} = R_{c2} = R_c$
- bypassed version (b): R_{c1} = bypassed by C_{c1}
- un-bypassed version (u): $R_{c1} = un-bypassed$

8.3 Basic formulae (excl. stage load (R_L)-effect)

$$G_{\mu,F} = G1G2 \tag{8.1}$$

8.3.1 bypassed version - gain $G_{\mu,F,b}$ in terms of $g_{m,t}$:

$$G_{\mu,F,b} = Gl_{b} G2_{b}$$

$$Gl_{b} = -g_{m,t} \frac{r_{a,t} \left[r_{a,t} + (1 + g_{m,t}r_{a,t}) \left(R_{c} + R_{a1} \parallel R_{g2} \right) \right]}{2r_{a,t} + (1 + g_{m,t}r_{a,t}) \left(R_{c} + R_{a1} \parallel R_{g2} \right)}$$

$$G2_{b} = \frac{g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{R_{c} + R_{a1} + r_{a,t}} \right)^{-1}}{1 + g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{R_{c} + R_{a1} + r_{a,t}} \right)^{-1}}$$
(8.2)

by passed version - gain $G_{\mu,F,b}$ in terms of $\mu_t\!:$

$$G_{\mu,F,b} = -\mu_{t}^{2} \frac{\left[r_{a,t} + (1+\mu_{t})\left(R_{c} + R_{a1} \parallel R_{g2}\right)\right]}{\left[2r_{a,t} + (1+\mu_{t})\left(R_{c} + R_{a1} \parallel R_{g2}\right)\right]} \\ * \frac{\left(R_{c} + R_{a1} + r_{a,t}\right)}{\left[2r_{a,t} + R_{c} + R_{a1} + \mu_{t}\left(R_{c} + R_{a1} + r_{a,t}\right)\right]}$$
(8.3)

rule of thumb for $G_{\mu.F.b}$:

$$G2_{b.rot} = 1$$

$$G_{\mu.F.b.rot} = \mu_t$$
(8.4)

8.3.2 un-bypassed version - gain $G_{\mu,F,u}$ in terms of $g_{m,t}$ and μ_t :

$$\begin{aligned} G_{\mu,F,u} &= GI_{u} G2_{u} \\ GI_{u} &= -\mu_{t} \frac{r_{a.t} + (1+\mu_{t}) \left(R_{c} + R_{a1} \parallel R_{g2}\right)}{2r_{a.t} + (1+\mu_{t}) \left(2R_{c} + R_{a1} \parallel R_{g2}\right)} \\ G2_{u} &= \frac{g_{m.t} \left(\frac{1}{r_{a.t}} + \frac{1}{R_{a1} + r_{a.t} + (2+\mu_{t}) R_{c}}\right)^{-1}}{1 + g_{m.t} \left(\frac{1}{r_{a.t}} + \frac{1}{R_{a1} + r_{a.t} + (2+\mu_{t}) R_{c}}\right)^{-1}} \end{aligned}$$

$$(8.5)$$

rule of thumb for $G_{\mu,F,u}$:

$$G2_{u.rot} = 1$$

$$G_{\mu,F.u.rot} = \mu_t$$
(8.6)

8.3.3 bypassed version - V2 cathode output resistance Rockv2.b:

$$R_{o.c.v2.b} = r_{a.t} \left[\frac{r_{a.t} + R_c}{(2 + \mu_t) r_{a.t} + (1 + \mu_t) R_c} \right]$$
(8.7)

8.3.4 un-bypassed version - V2 cathode output resistance R_{o.c.v2.u}:

$$R_{o.c.v2.u} = r_{a.t} \left[\frac{r_{a.t} + (2 + \mu_t) R_c}{(2 + \mu_t) r_{a.t} + (2 + 3\mu_t + \mu_t^2) R_c} \right]$$
(8.8)

8.3.5 V1-R_{c1} bypass capacitance C_{c1}:

To get a flat frequency response in B_{20k} as well as a phase response deviation of $<1^\circ$ at 20Hz C_{c1} should be calculated as follows:

$$C_{c1} = \frac{1}{\pi f_{c.opt}} \frac{\left[r_{a.t} + (1 + \mu_t) R_c\right]}{\left[2r_{a.t} + (1 + \mu_t) R_c\right] R_c}$$
(8.9)

$$f_{c.opt} = 0.2 Hz \tag{8.10}$$

8.4 Derivations



Figure 8.2 Equivalent circuit of Figure 8.1



Figure 8.3 Simplified equivalent circuit of Figure 8.2

8.4.1 Gains:

Instead of producing a lot of equations derived from Figure 8.2 to get the respective gain formulae we take the much easier to handle Figure 8.3. It shows that the μ -F gain stage is made of two gain blocks G1 and G2.

 $G1_b$ is a CCS+Cc gain stage with AC-grounded cathode à la Chapter 2. $G1_u$ is a CCS gain stage à la Chapter 1. G2 is an improved cathode follower $CF2_u$ à la Chapter 3.5 as well as a constant current source CCSo-hi à la Chapter 5.3. The impedance of the μ -F's V1 plus its components form the $CF2_u$'s lower cathode resistance R_{c2} whereas R_{a1} plus R_{c2} of the Figure 8.1 μ -F form the $CF2_u$'s upper cathode resistance R_{c1} .

Without big extra derivation efforts the respective formulae of the chapters mentioned can be used to calculate the gains $G_{\mu,F,b}$ or $G_{\mu,F,u}$.

8.4.1.1 bypassed version:

with the upper valve's active AC resistance $R_{\nu 2}$ (seen from node A1):

$$R_{v2} = r_{a.t} + (\mu_t + 1) (R_{c2} + R_{a1} || R_{g2})$$
(8.11)

in terms of $g_{m.t} G_{\mu.F.b}$ becomes:

$$Gl_b = -g_{m,t} \left(R_{v2} \| r_{a,t} \right)$$
 (8.12)

$$Gl_{b} = -g_{m,t} \left(\frac{1}{R_{v2}} + \frac{1}{r_{a,t}} \right)^{-1}$$
(8.13)

$$G2_{b} = \frac{g_{m.t} \left(\frac{1}{r_{a.t}} + \frac{1}{R_{c} + R_{a1} + r_{a.t}}\right)^{-1}}{1 + g_{m.t} \left(\frac{1}{r_{a.t}} + \frac{1}{R_{c} + R_{a1} + r_{a.t}}\right)^{-1}}$$
(8.14)

$$G_{\mu,F,b} = Gl_b G2_b \tag{8.15}$$

$$G_{\mu,F,b} = -g_{m,t}^{2} \frac{r_{a,t}^{2} \left[r_{a,t} + (1 + g_{m,t}r_{a,t}) \left(R_{c} + R_{a1} \parallel R_{g2} \right) \right]}{\left[2r_{a,t} + (1 + g_{m,t}r_{a,t}) \left(R_{c} + R_{a1} \parallel R_{g2} \right) \right]} \\ * \frac{\left(R_{c} + R_{a1} + r_{a,t} \right)}{\left[2r_{a,t} + R_{c} + R_{a1} + g_{m,t}r_{a,t} \left(R_{c} + R_{a1} + r_{a,t} \right) \right]}$$
(8.16)

since $\mu_t = g_{m,t} * r_{a,t}$ in terms of $\mu_t G_{\mu,F,b}$ becomes:

$$G_{\mu.F.b} = -\mu_{t}^{2} \frac{\left[r_{a.t} + (1 + \mu_{t})\left(R_{c} + R_{a1} \parallel R_{g2}\right)\right]}{\left[2r_{a.t} + (1 + \mu_{t})\left(R_{c} + R_{a1} \parallel R_{g2}\right)\right]} \\ * \frac{\left(R_{c} + R_{a1} + r_{a.t}\right)}{\left[2r_{a.t} + R_{c} + R_{a1} + \mu_{t}\left(R_{c} + R_{a1} + r_{a.t}\right)\right]}$$

$$(8.17)$$

8.4.1.2 un-bypassed version:

in terms of $g_{m.t} G_{\mu.F.u}$ becomes:

$$G1_{u} = -g_{m.t} \frac{r_{a.t} R_{v2}}{r_{a.t} + R_{v2} + R_{c}(1 + g_{m.t} r_{a.t})}$$
(8.18)

since $\mu_t = g_{m,t} * r_{a,t}$ in terms of $\mu_t G1_u$ becomes:

$$Gl_{u} = -\mu_{t} \frac{r_{a.t} + (1 + \mu_{t}) (R_{c} + R_{a1} \parallel R_{g2})}{2r_{a.t} + (1 + \mu_{t}) (2R_{c} + R_{a1} \parallel R_{g2})}$$
(8.19)

$$G2_{u} = \frac{g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{R_{a1} + r_{a,t} + (2 + \mu_{t})R_{c}}\right)^{-1}}{1 + g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{R_{a1} + r_{a,t} + (2 + \mu_{t})R_{c}}\right)^{-1}}$$

$$G_{\mu,F,u} = G1_{u} G2_{u}$$
(8.20)
(8.21)

8.4.2 Specific resistances and capacitances C_{c1} & C_{g2}:

8.4.2.1 bypassed version - V1 anode output resistances R_{o.a.v1.b}:

$$\mathbf{R}_{\mathbf{0}.\mathbf{a}.\mathbf{v}1.\mathbf{b}} = \mathbf{r}_{\mathbf{a}.\mathbf{t}} \tag{8.22}$$

.

8.4.2.2 bypassed version - V2 cathode output resistance R_{o.c.v2.b}:

V2 cathode resistance r_{c.v2}:

$$\mathbf{r}_{c.v2} = \frac{\mathbf{r}_{a.t}}{\mu_t + 1} \tag{8.23}$$

V2 cathode load resistance R1_b:

$$R1_{b} = r_{a,t} + R_{c2} + R_{a1}$$
(8.24)

output resistance Ro.c.v2.b:

$$R_{o.c.v2.b} = R1_{b} || r_{c.v2}$$
$$= \left(\frac{1}{R1_{b}} + \frac{1}{r_{c.v2}}\right)^{-1}$$
(8.25)

8.4.2.3 V1 bypass capacitance C_{c1}:

since Rv2 is:

$$R_{v2} = r_{a.t} + (\mu_t + 1) (R_{c2} + R_{a1} || R_{g2})$$
(8.26)

V1 cathode resistance $r_{c.v1}$ becomes:

$$\mathbf{r}_{c.v1} = \frac{\mathbf{r}_{a.t} + \mathbf{R}_{v2}}{1 + \mu_t} \tag{8.27}$$

V1 cathode resistance R_{c.v1} becomes:

$$R_{c.v1} = r_{c.v1} || R_{c}$$

$$= \left(\frac{1}{r_{c.v1}} + \frac{1}{R_{c}}\right)^{-1}$$
(8.28)

and capacitance Cc1 becomes:

$$C_{c1} = \frac{1}{2\pi f_{c.opt} R_{c.v1}}$$
(8.29)

8.4.2.4 V2 input capacitance C_{g2} :

according to Chapter 3.5 the grid's input resistance $R_{\rm in,v2}\, of$ the V2 gain stage becomes:

$$R_{in.v2} = \frac{R_{g2}}{1 - G2\left(\frac{Zl_u - R_c}{Zl_u}\right)}$$
(8.30)

$$R1_{u} = r_{a.t} + (2 + \mu_{t})R_{c} + R_{a1}$$
(8.31)

hence, Cg2 becomes:

$$C_{g2} = \frac{1}{2\pi f_{c.opt} R_{in.v2}}$$
(8.32)

8.4.2.5 un-bypassed version - V1 anode output resistance R_{o.a.v1.u}:

$$R_{o.a.v1.u} = r_{a.t} + (1 + \mu_t) R_c$$
(8.33)

8.4.2.6 un-bypassed version - V2 cathode output resistance R_{o.c.v2.u}:

V2 cathode resistance r_{c.v2}:

$$r_{c.v2} = \frac{r_{a.t}}{\mu_t + 1}$$
(8.34)

output resistance R_{o.c.v2.b}:

$$R_{o.c.v2.u} = R I_{u} || r_{c.v2}$$
$$= \left(\frac{1}{R I_{u}} + \frac{1}{r_{c.v2}}\right)^{-1}$$
(8.35)

8.5 Input capacitances C_{i,v1} and C_{i,v2} Output capacitances C_{0,v1} and C_{0,v2}

data sheet figures:	$\begin{array}{l} C_{g.c.v1} = \mbox{grid-cathode capacitance of V1} \\ C_{g.a.v1} = \mbox{grid-plate capacitance of V1} \\ C_{a.c.v1} = \mbox{plate-cathode capacitance of V1} \\ C_{g.c.v2} = \mbox{grid-cathode capacitance of V2} \\ C_{g.a.v2} = \mbox{grid-plate capacitance of V2} \\ C_{a.c.v2} = \mbox{plate-cathode capacitance of V2} \\ \end{array}$
to be guessed:	$C_{stray.1}$ = sum of stray capacitances around V1 $C_{stray.2}$ = sum of stray capacitances around V2
to be ignored ¹ :	$C_{0,c,v2}$ = cathode capacitance of V2

Note: the Miller capacitance of the input depends on V1's gain G1 only²!

$$C_{i,v1,b} = (1 + |G1_b|)C_{g,a,v1} || C_{g,c,v1} || C_{stray,1}$$
(8.36)

$$C_{i,v1,u} = (1 + |G1_u|) C_{g,a,v1} || C_{g,c,v1} || C_{stray,1}$$
(8.37)

$$C_{i,v2,b} = (1 - G_{2_b}) C_{g,c,v2} \| C_{g,a,v2} \| C_{stray,2}$$
(8.38)

$$C_{i,v2.u} = (1 - G2_u) C_{g,c.v2} \| C_{g,a.v2} \| C_{stray.2}$$
(8.39)

$$C_{o.v1} = C_{a.c.v1} \| C_{c.g.v1} \| C_{g.a.v2}$$
(8.40)

$$C_{o,v2} = C_{a,c,v2} \tag{8.41}$$

8.6 Input impedance Z_{in}

$$Z_{in}(f) = R_{g1} \| C_{i,v1}$$
(8.42)

Inclusion of R_{gg} and C_{in} into the calculation course leads to:

$$Z_{\text{in.b}}(f) = \left[\left(R_{gg} + \frac{1}{2j\pi f C_{i.v1.b}} \right)^{-1} + \frac{1}{R_{g1}} \right]^{-1} + \frac{1}{2j\pi f C_{in}}$$
(8.43)

$$Z_{\text{in.u}}(f) = \left[\left(R_{gg} + \frac{1}{2j\pi f C_{i.vl.u}} \right)^{-1} + \frac{1}{R_{gl}} \right]^{-1} + \frac{1}{2j\pi f C_{in}}$$
(8.44)

 $^{^1}$ to be ignored in B_{20k} only because - compared with the size of the corresponding capacitances - the output impedance is rather low

² Miller capacitance effects on C_i and C_o : see Chapter 1.3.2.5

8.7 Gain stage frequency and phase response calculations³

8.7.1 Bypassed version:



Figure 8.4 Simplified⁴ equivalent circuit of Figure 8.1 (bypassed version) - including all frequency and phase response relevant components

8.7.1.1 1^{st} stage (V1 = V1_c+V1_a) input transfer function $T_{i,1,b}(f)$ and phase $\varphi_{i,1,b}(f)$ - including source resistance R_s and an oscillation preventing resistor $R_{gg} << R_g$.

$$T_{i.1.b}(f) = \frac{v_{g.1}}{v_0}$$
(8.45)

$$\varphi_{i.1.b}(f) = \arctan\left\{\frac{\mathrm{Im}\left[\mathrm{T}_{i.1.b}(f)\right]}{\mathrm{Re}\left[\mathrm{T}_{i.1.b}(f)\right]}\right\}$$
(8.46)

$$T_{i.1.b}(f) = \frac{Z2_{b}(f) \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{b}(f)}\right)^{-1}}{\left(R_{gg1} + Z2_{b}(f)\right) \left[R_{S} + Z1(f) + \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{b}(f)}\right)^{-1}\right]}$$
(8.47)
$$Z1(f) = (2j\pi f C_{in})^{-1}$$
(8.48)
$$Z2_{b}(f) = (2j\pi f C_{i,v1,b})^{-1}$$
(8.48)

8.7.1.2 1^{st} stage V1_c cathode transfer function $T_{c.1.b}(f)$ and phase $\varphi_{c.1.b}(f)$:

$$\varphi_{c.1.b}(f) = \arctan\left\{\frac{\mathrm{Im}\left[\mathrm{T}_{c.1.b}(f)\right]}{\mathrm{Re}\left[\mathrm{T}_{c.1.b}(f)\right]}\right\}$$
(8.49)

$$T_{c.1.b}(f) = \frac{R_{c.v1}}{R_{c.v1} + \frac{1}{2j\pi f C_{c.1}}}$$
(8.50)

³ I've not included into the calculation course a second oscillation preventing resistor $R_{gg,2}$ between $R_{g,2}$ and grid of V2, thus, forming a lp by $R_{gg,2}$ and $C_{i,v2}$. Automatically, this would mean a further worsening of the phase response at the upper end of B_{20k} .

⁴ See also footnotes 2 and 3 of Chapter 1 and footnote 3 of Chapter 2

8.7.1.3 1^{st} stage output transfer function $T_{o.1.b}(f)$ and phase $\varphi_{o.1.b}(f)$:

$$T_{o.1.b}(f) = \frac{v_{g.2}}{v_{a.1}}$$
(8.51)

$$\varphi_{o.1.b}(f) = \arctan\left\{\frac{\text{Im}\left[T_{o.1.b}\left(f\right)\right]}{\text{Re}\left[T_{o.1.b}\left(f\right)\right]}\right\}$$
(8.52)

$$T_{o.1.b}(f) = \frac{\left[\frac{1}{Z^{3}(f)} + \frac{1}{Z^{4}(f) + \left(\frac{1}{R_{in.2}} + \frac{1}{Z^{5}_{b}(f)}\right)^{-1}}\right]^{-1}}{R_{o.a.v1.b} + \left[\frac{1}{Z^{3}(f)} + \frac{1}{Z^{4}(f) + \left(\frac{1}{R_{in.2}} + \frac{1}{Z^{5}_{b}(f)}\right)^{-1}}\right]^{-1}} \\ \frac{\left(\frac{1}{R_{in.2}} + \frac{1}{Z^{5}_{b}(f)}\right)^{-1}}{Z^{4}(f) + \left(\frac{1}{R_{in.2}} + \frac{1}{Z^{5}_{b}(f)}\right)^{-1}} \\ Z^{3}(f) = (2j\pi f C_{o.v1})^{-1}}$$

$$(8.53)$$

$$Z4(f) = (2j\pi f C_{g,2})^{-1}$$

$$Z5(f) = (2j\pi f C_{i,v2,b})^{-1}$$
(8.54)

8.7.1.4 2^{nd} stage output transfer function $T_{o.2.b}(f)$ and phase $\varphi_{o.2.b}(f)$:

$$T_{o.2.b}(f) = \frac{v_0}{v_{c.2}}$$
(8.55)

$$\varphi_{o.2.b}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{o.2.b}(f)\right]}{\operatorname{Re}\left[T_{o.2.b}(f)\right]}\right\}$$
(8.56)

$$T_{o.2.b}(f) = \frac{R_L}{R_{o.c.v2.b} + R_L + Z6(f)}$$
(8.57)

$$Z6(f) = (2j\pi f C_{out})^{-1}$$
 (8.58)

8.7.1.5 1^{st} stage fundamental phase shift $\varphi_{G,v1}(f)$:

$$\varphi_{G,v1}(f) = \varphi_{G,\mu,F,b}(f) = -180^{\circ}$$
(8.59)

8.7.1.6 total gain stage transfer function $T_{tot.b}(f)$ and phase $\varphi_{tot.b}(f)$:

$$T_{\text{tot.b}}(f) = T_{i.1.b}(f) T_{c.1.b}(f) T_{o.1.b}(f) T_{o.2.b}(f) G1_b G2_b$$
(8.60)

$$\varphi_{\text{tot,b}}(f) = \varphi_{i.1.b}(f) + \varphi_{c.1.b}(f) + \varphi_{o.1.b}(f) + \varphi_{o.2.b}(f) + \varphi_{G,\mu,F,b}(f)$$
(8.61)

8.7.2 Un-bypassed version:



Figure 8.5 Simplified⁵ equivalent circuit of Figure 8.1 (un-bypassed version) - including all frequency and phase response relevant components

8.7.2.1 1^{st} stage (V1) input transfer function $T_{i.1.u}(f)$ and phase $\varphi_{i.1.u}(f)$ - including source resistance R_s and an oscillation preventing resistor $R_{gg} << R_g$:

$$T_{i.1.u}(f) = \frac{v_{g.1}}{v_0}$$
(8.62)

⁵ See also footnotes 2 and 3 of Chapter 1

$$\varphi_{i.1.u}(f) = \arctan\left\{\frac{\text{Im}\left[T_{i.1.u}\left(f\right)\right]}{\text{Re}\left[T_{i.1.u}\left(f\right)\right]}\right\}$$
(8.63)

$$T_{i.1.u}(f) = \frac{Z2_{u}(f) \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{u}(f)}\right)^{-1}}{\left(R_{gg1} + Z2_{u}(f)\right) \left[R_{S} + Z1(f) + \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{u}(f)}\right)^{-1}\right]} \qquad (8.64)$$
$$Z1(f) = (2j\pi f C_{in})^{-1}$$
$$Z2_{u}(f) = (2j\pi f C_{i.v1.u})^{-1} \qquad (8.65)$$

8.7.2.2 1^{st} stage output transfer function $T_{o.1.u}(f)$ and phase $\phi_{o.1.u}(f)$:

$$T_{o.1.u}(f) = \frac{v_{g.2}}{v_{a.1}}$$
(8.66)

$$\varphi_{o.1.u}(f) = \arctan\left\{\frac{\operatorname{Im}[T_{o.1.u}(f)]}{\operatorname{Re}[T_{o.1.u}(f)]}\right\}$$
(8.67)

$$T_{o.1.u}(f) = \frac{\left[\frac{1}{Z^{3}(f)} + \frac{1}{Z^{4}(f) + \left(\frac{1}{R_{in.2}} + \frac{1}{Z^{5}_{u}(f)}\right)^{-1}}\right]^{-1}}{R_{o.a.v1.b} + \left[\frac{1}{Z^{3}(f)} + \frac{1}{Z^{4}(f) + \left(\frac{1}{R_{in.2}} + \frac{1}{Z^{5}_{u}(f)}\right)^{-1}}\right]^{-1}} \\ \frac{\left(\frac{1}{R_{in.2}} + \frac{1}{Z^{5}_{u}(f)}\right)^{-1}}{Z^{4}(f) + \left(\frac{1}{R_{in.2}} + \frac{1}{Z^{5}_{u}(f)}\right)^{-1}}$$

$$(8.68)$$

$$Z3(f) = (2j\pi f C_{o.v1})^{-1}$$

$$Z4(f) = (2j\pi f C_{g.2})^{-1}$$

$$Z5(f) = (2j\pi f C_{i.v2,b})^{-1}$$
(8.69)

8.7.2.3 2^{nd} stage output transfer function $T_{o.2.u}(f)$ and phase $\varphi_{o.2.u}(f)$:

$$T_{0.2.u}(f) = \frac{V_0}{V_{c.2}}$$
(8.70)

$$\varphi_{o.2.u}(f) = \arctan\left\{\frac{\text{Im}\left[T_{o.2.u}(f)\right]}{\text{Re}\left[T_{o.2.u}(f)\right]}\right\}$$
(8.71)

$$T_{o.2.u}(f) = \frac{R_L}{R_{o.c.v2.u} + R_L + Z6(f)}$$
(8.72)

$$Z6(f) = (2j\pi f C_{out})^{-1}$$
 (8.73)

8.7.2.4 1^{st} stage fundamental phase shift $\varphi_{G.v1}(f)$:

$$\varphi_{G.v1}(f) = \varphi_{G,\mu,F.u}(f) = -180^{\circ}$$
(8.74)

8.7.2.5 total gain stage transfer function $T_{tot,u}(f)$ and phase $\varphi_{tot,u}(f)$:

$$T_{tot.u}(f) = T_{i.1.u}(f) T_{o.1.u}(f) T_{o.2.u}(f) Gl_u G2_u$$
(8.75)

$$\varphi_{\text{tot.}u}(f) = \varphi_{i,1.u}(f) + \varphi_{o,1.u}(f) + \varphi_{o,2.u}(f) + \varphi_{G,\mu,F,u}(f)$$
(8.76)

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Figure 8.6 µ-Follower example circuitry

8.8.1 Triode bias data:

$I_{a1.83} = I_{a2.83} = 1.2 \cdot 10^{-3} A$	$V_{a1.83} = 100 V$	$V_{a2.83} = 100V$
$V_{cc} = 268.5 V$	$V_{g183} = -0.5V$	$V_{92,83} = 168V$

8.8.2 Triode valve constants:

$g_{m.83} := 1.75 \cdot 10^{-5} \cdot S$	$\mu_{83} := 101.5$	$\mathbf{r}_{a.83} \coloneqq 58 \cdot 10^{3} \Omega$
$\mathtt{g}_{m,v1}\coloneqq\mathtt{g}_{m,83}$	$\mu_{v1} \coloneqq \mu_{83}$	$r_{a.v1} \coloneqq r_{a.83}$
$g_{m.v2} \coloneqq g_{m.83}$	$\mu_{v2} \coloneqq \mu_{83}$	$r_{a.v2} \coloneqq r_{a.83}$
$C_{g.c.1.83} \coloneqq 1.65 \cdot 10^{-12} F$	$C_{g.a.1.83} \coloneqq 1.6 \cdot 10^{-12} F$	$C_{a.c.1.83} \coloneqq 0.33 \cdot 10^{-12} F$
$C_{g.c.2.83} \coloneqq 1.65 \cdot 10^{-12} F$	$C_{g.a.2.83} \coloneqq 1.6 \cdot 10^{-12} F$	$C_{a.c.2.83} \coloneqq 0.33 \cdot 10^{-12} F$

8.8.3 Circuit variables:

$R_{c1.83} \coloneqq 417\Omega$	$R_{c2.83} := R_{c1.83}$	$R_{c.83} := R_{c1.83}$
$R_{S} := 1 \cdot 10^{3} \Omega$	$R_{L} := 47.5 \cdot 10^{3} \Omega$	$R_{gg1.83} \coloneqq 0.22 \cdot 10^3 \Omega$
$R_{g1.83} := 47.5 \cdot 10^3 \Omega$	$C_{in.83} := 2.2 \cdot 10^{-6} F$	$C_{out.83} := 10 \cdot 10^{-6} F$
$R_{g2.83} \coloneqq 1.10^6 \Omega$	$C_{stray.83.1} := 10 \cdot 10^{-12} F$	$C_{stray.83.2} := 10 \cdot 10^{-12} F$
$R_{a1.83} := 56.2 \cdot 10^3 \Omega$		

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8.8.4 Calculation relevant data:

frequency range f for the below shown graphs:

8.8.5 Gain G_{µ.F.83.b} :

$$R_{v2} \coloneqq r_{a,v2} + \left(1 + \mu_{v2}\right) \left[R_{c2.83} + \left(\frac{1}{R_{a1.83}} + \frac{1}{R_{g2.83}}\right)^{-1} \right]$$

$$G1_{b} \coloneqq -\underline{g}_{m.83} \cdot \left(\frac{1}{R_{v2}} + \frac{1}{r_{a.83}}\right)$$

$$G2_b := \frac{g_{m.v2} \left(\frac{1}{r_{a.v2}} + \frac{1}{R_{c2.83} + R_{a1.83} + r_{a.v1}} \right)}{1 + g_{m.v2} \left(\frac{1}{r_{a.v2}} + \frac{1}{R_{c2.83} + R_{a1.83} + r_{a.v1}} \right)^{-1}}$$

$$G_{\mu,F.83.b} \coloneqq G1_b \cdot G2_b$$

$$G_{\mu,F.83.b.e} \coloneqq 20 \cdot \log(|G_{\mu,F.83.b}|)$$

 $G_{\mu.F.83.b.rot} \coloneqq \mu_{83}$

8.8.6 Gain G_{µ.F.83.u}:

 $G_{\mu,F.83.b.rot.e} \coloneqq 20 \cdot \log(|G_{\mu,F.83.b.rot}|)$

$$G_{\mu,F.83.b.e} - G_{\mu,F.83.b.rot.e} = -218.156 \times 10^{-5}$$

\ − 1

$$G1_{u} \coloneqq -g_{m.83} \cdot \frac{r_{a.83} \cdot R_{v2}}{R_{v2} + r_{a.83} + R_{c.83} \cdot (1 + \mu_{83})} \qquad G1_{u} = -99.692 \times 10^{0}$$

$$G2_{u} \coloneqq \frac{g_{m.v2} \cdot \left[\frac{1}{r_{a.v2}} + \frac{1}{R_{c2.83} + R_{a1.83} + r_{a.v1} + (1 + \mu_{v1}) \cdot R_{c1.83}}\right]^{-1}}{1 + g_{m.v2} \cdot \left[\frac{1}{r_{a.v2}} + \frac{1}{R_{c2.83} + R_{a1.83} + r_{a.v1} + (1 + \mu_{v1}) \cdot R_{c1.83}}\right]^{-1}}$$

$$G2_{u} = 986.696 \times 10^{-3}$$

$$R_{v2} = 5.555 \times 10^{6} \Omega$$

via V1 $G1_b = -100.451 \times 10^0$

via V2
$$G2_b = 985.379 \times 10^{-2}$$

$$G_{\mu,F,83,b} = -98.982 \times 10^{0}$$

$$G_{\mu,F,83,b,e} = 39.911 \times 10^{0} \qquad [dB]$$

$$G_{\mu,F,83,b,rot} = 101.5 \times 10^{0}$$

$$G_{\mu,F.83.b.rot.e} = 40.129 \times 10^{0} \text{ [dB]}$$

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$$\begin{split} G_{\mu,F,83,u} &\coloneqq G1_{u} \cdot G2_{u} & G_{\mu,F,83,u} &= -98.366 \times 10^{0} \\ G_{\mu,F,83,u,e} &\coloneqq 20 \cdot \log(|G_{\mu,F,83,u}|) & G_{\mu,F,83,u,e} &= 39.857 \times 10^{0} \\ G_{\mu,F,83,u,rot} &\coloneqq \mu_{83} & G_{\mu,F,83,u,rot} &= 101.5 \times 10^{0} \\ G_{\mu,F,83,u,rot,e} &\coloneqq 20 \cdot \log(|G_{\mu,F,83,u,rot}|) & G_{\mu,F,83,u,rot,e} &= 40.129 \times 10^{0} \\ \end{split}$$

$$G_{\text{II}} = 6_{\text{II}} = -G_{\text{II}} = -272.453 \times 10^{-3}$$

$$\begin{array}{ll} \textbf{8.8.7} \quad \textbf{Specific resistances:} \\ R_{o.a.v1.b} \coloneqq r_{a.v1} & R_{o.a.v1.b} \equiv 58 \times 10^{3} \Omega \\ R_{o.a.v1.u} \coloneqq r_{a.v1} + (1 + \mu_{v1}) \cdot R_{c1.83} & R_{o.a.v1.u} \equiv 100.743 \times 10^{3} \Omega \\ r_{c.v1} \coloneqq \frac{r_{a.v1} + R_{v2}}{1 + \mu_{v1}} & r_{c.v1} \equiv 54.758 \times 10^{3} \Omega \\ R_{c.v1} \coloneqq \left(\frac{1}{r_{c.v1}} + \frac{1}{R_{c1.83}}\right)^{-1} & R_{c.v1} \equiv 413.848 \times 10^{0} \Omega \\ r_{c.v2} \coloneqq \frac{r_{a.v2}}{1 + \mu_{v2}} & r_{c.v2} \equiv 565.854 \times 10^{0} \Omega \\ R_{1b} \coloneqq r_{a.v1} + R_{c2.83} + \left(\frac{1}{R_{a1.83}} + \frac{1}{R_{g2.83}}\right)^{-1} & R_{1b} \equiv 111.627 \times 10^{3} \Omega \\ R_{0.c.v2.b} \coloneqq \left(\frac{1}{R_{1b}} + \frac{1}{r_{c.v2}}\right)^{-1} & R_{0.c.v2.b} \equiv 563 \times 10^{0} \Omega \\ R_{1u} \coloneqq r_{a.v1} + (1 + \mu_{v1}) \cdot R_{c1.83} + R_{c2.83} + \left(\frac{1}{R_{a1.83}} + \frac{1}{R_{g2.83}}\right)^{-1} & R_{1u} \equiv 154.369 \times 10^{3} \Omega \\ R_{0.c.v2.u} \coloneqq \left(\frac{1}{R_{1u}} + \frac{1}{r_{c.v2}}\right)^{-1} & R_{0.c.v2.u} \equiv 563.787 \times 10^{0} \Omega \\ \end{array}$$

8.8.8 Capacitance C_{c1} and C_{g2} :

$$f_{c} := 20Hz f_{c.opt} := \frac{f_{c}}{100} f_{c.opt} = 200 \times 10^{-3} Hz$$

$$C_{c1} := \frac{1}{2 \cdot \pi \cdot f_{c.opt} \cdot R_{c.v1}} C_{c1} = 1.923 \times 10^{-3} F$$

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$$R_{in,v2} := \frac{R_{g2.83}}{1 - G2_{u} \cdot \frac{R_{1u} - R_{c2.83}}{R_{1u}}}$$

$$R_{in,v2} = 62.619 \times 10^{6} \Omega$$

$$R_{g2} := \frac{1}{2 \cdot \pi \cdot f_{c.opt} \cdot R_{in,v2}}$$

$$C_{g2} := \frac{1}{2 \cdot \pi \cdot f_{c.opt} \cdot R_{in,v2}}$$

$$C_{g2} = 12.708 \times 10^{-9} F$$
8.8.9 Specific input and output capacitances :

$$C_{i \vee l,b} \coloneqq (1 + |Gl_b|) \cdot C_{g.a.1.83} + C_{g.c.1.83} + C_{stray.83.1}$$

$$C_{i \vee l,b} \coloneqq 173.972 \times 10^{-12} F$$

$$C_{i \vee l,u} \coloneqq (1 + |Gl_u|) \cdot C_{g.a.1.83} + C_{g.c.1.83} + C_{stray.83.1}$$

$$C_{i \vee l,u} \coloneqq 172.757 \times 10^{-12} F$$

$$C_{i \vee 2.b} \coloneqq (1 - G2_b) \cdot C_{g.a.2.83} + C_{g.c.2.83} + C_{stray.83.2}$$

$$C_{i \vee 2.u} \coloneqq (1 - G2_u) \cdot C_{g.a.2.83} + C_{g.c.2.83} + C_{stray.83.2}$$

$$C_{i \vee 2.u} \coloneqq 11.671 \times 10^{-12} F$$

$$C_{o.\vee 1} \coloneqq C_{a.c.1.83} + C_{g.a.1.83} + C_{g.a.2.83} + C_{g.a.2.83}$$

$$C_{o.\vee 2} \coloneqq C_{a.c.2.83}$$





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\$ 0.1.b(f) -20 -25 -30 100 $\cdot 10^{3} \ 1 \cdot 10^{4} \ 1 \cdot 10^{5}$ 10 [Hz]

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Figure 8.12 Transfer of V1 o/p network



Figure 8.14 Transfer of V2 o/p network



 $T_{tot.83.b.e}(f) \coloneqq 20 \cdot \log(|T_{tot.83.b}(f)|)$

 $\phi_{G,83}(f) := -180 \deg$

 $\phi_{\text{tot.83,b}}(f) := \phi_{i,1,b}(f) + \phi_{c,1,b}(f) + \phi_{o,1,b}(f) + \phi_{o,2,b}(f) + \phi_{G,83}(f)$







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Figure 8.18 Phase responses of the bypassed and un-bypassed $\ensuremath{\mu\mbox{-}F}$ gain stage

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Figure 8.19 Input impedances for the bypassed and un-bypassed versions

9.1 Circuit diagram



Figure 9.1 Basic design of the AIK Gain Stage



Figure 9.2 Current source alternatives: a) = low-Z (lo) and b) = high-Z (hi)¹

 $^{^{1} \}qquad \text{Inclusion of an oscillation preventing resistor R_{gg2} [between R_{g2} and grid of $V2$ alternative b)]$ into the calculation course, thus, forming a lp by R_{gg2} and C_{iv2}, will automatically lead to a worsening of the frequency and phase response at the upper end of B_{20k}.}$

9.2 **Basic assumptions**

Generally, the whole AIK gain stage consists of a CCS or CCS+Cc gain stage (V1 with gain G) of Chapters 1 or 2 with an active high impedance (high-Z) or low impedance (low-Z) current source (V2) of Chapters 5.1 or 5.3 as the plate load. The output signal of the gain stage is taken from the plate of V1, thus, the output impedance is rather high and will react highly sensitive on rather low load impedances R_L^2 or Z_L .

To get all relevant formulae shown further down these lines the following assumption were made:

- V1 equals V2 (ideal case: double triode)
- = plate current V2 plate current V1
- $g_{m,v1} = g_{m,v2}$ $= g_{m.t}$
- $\mathbf{r}_{a.v1} = \mathbf{r}_{a.v2}$ $= r_{a.t}$
- $\mu_{v1} = \mu_{v2}$ $= \mu_t$ $= R_c$
- $R_{c2.1} = R_{c1}$
- $R_{c22} > 0R$ •
- bypassed version (b): R_{c1} = bypassed by C_{c1}
- un-bypassed version (u): $R_{c1} = un$ -bypassed

Gains Gaiklo for V1 with the low-Z plate load³ 9.3

The upper valve's active AC resistance Rv2.lo becomes:

$$R_{v2.lo} = r_{a.t} + (1 + \mu_t) R_{c2}$$
(9.1)

9.3.1 bypassed version - gain Gaik.b.lo in terms of gmt - excl. RL-effect:

$$G_{aik.b.lo} = -g_{m.t} \left(\frac{1}{r_{a.t}} + \frac{1}{R_{v2.lo}} \right)$$
 (9.2)

9.3.2 bypassed version - gain Gaik.b.lo.eff in terms of gm.t - incl. RL-effect:

$$G_{aik.b.lo.eff} = -g_{m.t} \left(\frac{1}{r_{a.t}} + \frac{1}{R_L} + \frac{1}{R_{v2.lo}} \right)^{-1}$$
(9.3)

9.3.3 un-bypassed version - gain Gaik.u.lo in terms of gm.t and µt - excl. RL-effect:

$$G_{aik,u,lo} = -\frac{1}{2}g_{m,t}r_{a,t}$$

$$= -\frac{1}{2}\mu_t$$
(9.4)

2 see respective plots (effective gains vs. RL changes) on MCD worksheets IX-1 and IX-2

³ R_L is the resistive part of Z_L in Figure 9.1

9.3.4 un-bypassed version - gain $G_{aik.u.lo.eff}$ in terms of $g_{m.t}$ and μ_t - incl. R_L -effect:

$$G_{aik.u.lo.eff} = -g_{m.t} \frac{r_{a.t}R_L}{r_{a.t} + (1 + \mu_t)R_c + 2R_L}$$

$$= -\mu_t \frac{R_L}{r_{a.t} + (1 + \mu_t)R_c + 2R_L}$$
(9.5)

9.4 Gains G_{aik,hi} for V1 with the high-Z plate load

The upper valve's active AC resistance Rv2.hi becomes:

$$R_{v2,hi} = r_{a,t} + (1 + \mu_t) \Big[R_{c2,1} + (R_{c2,2} \parallel R_{g2}) \Big]$$
(9.6)

9.4.1 bypassed version - gain Gaik.b.hi in terms of gm.t - excl. RL-effect:

$$G_{aik,b,hi} = -g_{m,t} \left(\frac{1}{r_{a,t}} + \frac{1}{R_{v2,hi}} \right)$$
 (9.7)

9.4.2 bypassed version - gain $G_{aik,b,hi,eff}$ in terms of $g_{m,t}$ - incl. R_L -effect:

$$G_{aik.b.hi.eff} = -g_{m.t} \left(\frac{1}{r_{a.t}} + \frac{1}{R_L} + \frac{1}{R_{v2.hi}} \right)^{-1}$$
(9.8)

9.4.3 un-bypassed version - gain $G_{aik,u,hi}$ in terms of $g_{m,t}$ and μ_t - excl. R_L -effect:

$$G_{aik.u.hi} = -g_{m.t} \frac{r_{a.t} R_{v2.hi}}{r_{a.t} + (1 + \mu_t) R_c + R_{v2.hi}}$$

$$= -\mu_t \frac{R_{v2.hi}}{r_{a.t} + (1 + \mu_t) R_c + R_{v2.hi}}$$
(9.9)

9.4.4 un-bypassed version - gain $G_{aik.u.hi.eff}$ in terms of $g_{m.t}$ and μ_t - incl. R_L -effect:

$$G_{aik.u.hi.eff} = -g_{m.t} \frac{r_{a.t} \left(\frac{1}{R_{v2.hi}} + \frac{1}{R_L}\right)^{-1}}{r_{a.t} + (1 + \mu_t) R_c + \left(\frac{1}{R_{v2.hi}} + \frac{1}{R_L}\right)^{-1}}$$

$$= -\mu_t \frac{\left(\frac{1}{R_{v2.hi}} + \frac{1}{R_L}\right)^{-1}}{r_{a.t} + (1 + \mu_t) R_c + \left(\frac{1}{R_{v2.hi}} + \frac{1}{R_L}\right)^{-1}}$$
(9.10)

9.5 Derivations



Figure 9.3 Simplified equivalent circuit of Figure 9.1

9.5.1 Gains⁴:

Because all relevant calculation formulae were given in the previous chapters we can take the much easier to handle Figure 9.3 as the basis of the derivations. It shows that the AIK gain stage is made of one gain block around V1 with gain G only. G_b is a CCS+Cc gain stage with AC-grounded cathode à la Chapter 2, G_u is a CCS gain stage à la Chapter 1 and the active plate load is a low-Z (R_{c2}!) or high-Z (R_{c2.1} plus R_{c2.2}!) current source à la Chapters 5.1 and 5.3. Without big derivation efforts the respective formulae can be used to calculate all relevant gains G_{aik,b} or G_{aik,u} - also by inclusion of all R_L-effects (= _{eff}) and Z_L-effects into the whole calculation course.

9.5.1.1 bypassed lo version:

G_{aik,b,lo} and G_{aik,b,lo,eff} become⁵:

$$Gl_{aik,b,lo} = -g_{m,t} \left(R_{v2,lo} \| r_{a,t} \right)$$
 (9.11)

$$Gl_{aik.b.lo.eff} = -g_{m.t} \left(R_{v2.lo} \| r_{a.t} \| R_L \right)$$
(9.12)

$$R_{v2.lo} = r_{a.t} + (1 + g_{m.t}r_{a.t}) R_c$$

= $r_{a.t} + (1 + \mu_t) R_c$ (9.13)

$$G_{aik.b.lo} = -g_{m.t} \frac{r_{a.t} \left[r_{a.t} + (1 + g_{m.t} r_{a.t}) R_c \right]}{2r_{a.t} + (1 + g_{m.t} r_{a.t}) R_c}$$

$$= -\mu_t \frac{r_{a.t} + (1 + \mu_t) R_c}{2r_{a.t} + (1 + \mu_t) R_c}$$
(9.14)

⁴ no rules of thumb are given in this section because of the high impact of the $o/p \text{ load } Z_L$ on the gains (see MCD IX worksheets)

⁵ see derivation of respective formula of Chapter 2

$$G_{aik.b.lo.eff} = -g_{m.t} \left(\frac{1}{r_{a.t}} + \frac{1}{R_{v2.lo}} + \frac{1}{R_L} \right)^{-1}$$
(9.15)

un-bypassed lo version: 9.5.1.2

Gaik.u.lo and Gaik.u.lo.eff become6:

$$G_{aik.u.lo} = -g_{m.t} \frac{r_{a.t} R_{v2.lo}}{r_{a.t} + R_{v2.lo} + (1 + g_{m.t} r_{a.t})R_c}$$
(9.16)

$$\Rightarrow G_{aik.u.lo} = -\frac{1}{2} g_{m.t} r_{a.t}$$

$$= -\frac{1}{2} \mu_t$$
(9.17)

$$G_{aik.u.lo.eff} = -g_{m.t} \frac{r_{a.t} \left(\frac{1}{R_{v2.lo}} + \frac{1}{R_L}\right)^{-1}}{r_{a.t} + (1 + g_{m.t} r_{a.t})R_c + \left(\frac{1}{R_{v2.lo}} + \frac{1}{R_L}\right)^{-1}}$$
(9.18)

$$\Rightarrow G_{aik.b.lo.eff} = -g_{m.t} \frac{r_{a.t}R_L}{r_{a.t} + (1 + \mu_t)R_c + 2R_L}$$

$$= \mu_t \frac{R_L}{r_{a.t} + (1 + \mu_t)R_c + 2R_L}$$
(9.19)

bypassed hi version7: 9.5.1.3

 $G_{aik,b,hi}$ and $G_{aik,b,hi,eff}$ become:

$$Gl_{aik.b.hi} = -g_{m.t} \left(R_{v2.hi} \| r_{a.t} \right)$$
 (9.20)

$$Gl_{aik.b.hi.eff} = -g_{m.t} \left(R_{v2.hi} \parallel r_{a.t} \parallel R_L \right)$$
(9.21)

$$R_{v2.hi} = r_{a.t} + (1 + \mu_t) \left[R_{c2.1} + \left(\frac{1}{R_{c2.2}} + \frac{1}{R_{g2}} \right)^{-1} \right]$$
(9.22)

$$\Rightarrow G_{aik.b.hi} = -g_{m.t} \left(\frac{1}{r_{a.t}} + \frac{1}{R_{v2.hi}} \right)^{-1}$$
(9.23)

see derivation of respective formula of Chapter 1 see derivation of respective formula of Chapter 2 6 7

$$\Rightarrow G_{aik.b.hi.eff} = -g_{m.t} \left(\frac{1}{r_{a.t}} + \frac{1}{R_{v2.hi}} + \frac{1}{R_L} \right)^{-1}$$
(9.24)

9.5.1.4 un-bypassed hi version:

Gaik.u.hi and Gaik.u.hi.eff become8:

$$\Rightarrow G_{aik.u.hi} = -g_{m.t} \frac{r_{a.t} R_{v2.hi}}{r_{a.t} + (1 + g_{m.t} r_{a.t})R_c + R_{v2.hi}}$$

$$= \mu_t \frac{R_{v2.hi}}{r_{a.t} + (1 + \mu_t)R_c + R_{v2.hi}}$$
(9.25)

$$\Rightarrow G_{aik.u.hi.eff} = -g_{m.t} \frac{r_{a.t} \left(\frac{1}{R_{v2.hi}} + \frac{1}{R_L}\right)^{-1}}{r_{a.t} + (1 + g_{m.t} r_{a.t})R_c + \left(\frac{1}{R_{v2.hi}} + \frac{1}{R_L}\right)^{-1}} = -\mu_t \frac{\left(\frac{1}{R_{v2.hi}} + \frac{1}{R_L}\right)^{-1}}{r_{a.t} + (1 + \mu_t)R_c + \left(\frac{1}{R_{v2.hi}} + \frac{1}{R_L}\right)^{-1}}$$
(9.26)

9.5.2 Specific resistances, impedances and capacitance Cc1:

9.5.2.1 the active load resistances $R_{v2,lo}$ and $R_{v2,hi}$ become⁹:

$$R_{v2.lo} = r_{a.t} + (\mu_t + 1) R_{c2}$$
(9.27)

$$R_{v2.hi} = r_{a.t} + (1 + \mu_t) \left[R_{c2.1} + \left(\frac{1}{R_{c2.2}} + \frac{1}{R_{g2}} \right)^{-1} \right]$$
(9.28)

the active load impedances $Z_{v2.lo}(f)$ and $Z_{v2.hi}(f)$ become:

$$Z_{v2.lo}(f) = \left[\left(r_{a.t} \| C_{a.c.v2} \right) + \left(1 + \mu_t \right) \left(R_{c2} \| C_{g.c.v2} \right) \right] \| C_{g.a.v2} \| C_{stray.2}$$
(9.29)

⁸ see derivation of respective formula of Chapter 1

⁹ see Chapter 5.1 and 5.3

$$Z_{v2.hi}(f) = \begin{pmatrix} \left\{ (r_{a.t} \| C_{a.c.v2}) + \\ (1 + \mu_t) \left[\left\{ R_{c2.1} + (R_{c2.2} \| R_{g2}) \right\} \| C_{g.c.v2} \right] \right\} \\ \| C_{g.a.v2} \| C_{stray.2} \end{pmatrix}$$
(9.30)

9.5.2.2 bypassed version - V1 plate output resistance R_{o.a.v1,b} and impedance Z_{o.a.v1,b}(f):

$$\mathbf{R}_{\mathbf{0}.\mathbf{a}.\mathbf{v}\mathbf{1}.\mathbf{b}} = \mathbf{r}_{\mathbf{a}.\mathbf{t}} \tag{9.31}$$

$$Z_{o.a.v1.b}(f) = R_{o.a.v1.b} || C_{o.v1}$$
(9.32)

$$R_{o.aik.b.lo} = R_{o.a.v1.b} || R_{v2.lo}$$
(9.33)

$$R_{o.aik.b.hi} = R_{o.a.v1.b} || R_{v2.hi}$$
 (9.34)

$$Z_{o.aik.b.lo}(f) = Z_{o.a.v1.b}(f) || Z_{v2.lo}(f)$$
(9.35)

$$Z_{o.aik.b.hi}(f) = Z_{o.a.v1.b}(f) || Z_{v2.hi}(f)$$
(9.36)

9.5.2.4 V1 cathode resistor bypass capacitances C_{c1.lo} and C_{c1.hi} become:

with V1 cathode output resistances $r_{c.v1.lo}$ and $r_{c.v1.hi}\text{:}$

$$r_{c.v1.lo} = \frac{r_{a.t} + Z_{v2.lo}}{1 + \mu_t}$$
(9.37)

$$r_{c.v1.hi} = \frac{r_{a.t} + Z_{v2.hi}}{1 + \mu_t}$$
(9.38)

with V1 cathode output resistances $R_{c.v1.lo}$ and $R_{c.v1.hi}$:

$$R_{c.v1.lo} = r_{c.v1.lo} || R_{c}$$

= $\left(\frac{1}{r_{c.v1.lo}} + \frac{1}{R_{c}}\right)^{-1}$ (9.39)

$$R_{c.v1.hi} = r_{c.v1.hi} || R_{c}$$

$$= \left(\frac{1}{r_{c.v1.hi}} + \frac{1}{R_{c}}\right)^{-1}$$
(9.40)

capacitances $C_{c1.lo}$ and $C_{c1.hi}$ become ($f_{c.opt}\!\leq\!0.2Hz$):

$$C_{c1.lo} = \frac{1}{2\pi f_{c.opt} R_{c.v1.lo}}$$
(9.41)

$$C_{c1.hi} = \frac{1}{2\pi f_{c.opt} R_{c.v1.hi}}$$
(9.42)

9.5.2.5 un-bypassed version - V1 anode output resistance
$$R_{o.a.v1.u}$$

and impedance $Z_{o.a.v1.u}(f)$:
 $R_{o.a.v1.u} = r_{a.t} + (1 + \mu_t) R_c$ (9.43)
 $Z_{o.a.v1.u}(f) = R_{o.a.v1.u} \parallel C_{o.v1}$ (9.44)
9.5.2.6 un-bypassed version - AIK gain stage o/p resistances $R_{o.aik.u.lo}$ and $R_{o.aik.u.hi}$
and o/p impedances $Z_{o.aik.u.lo}(f)$ and $Z_{o.aik.u.hi}(f)$ at the plate of V1:

$$R_{o.aik.u.lo} = R_{o.a.v1.u} || R_{v2.lo}$$
(9.45)

$$R_{o.aik.u.hi} = R_{o.a.v1.u} || R_{v2.hi}$$
(9.46)

$$Z_{o,aik.u.lo}(f) = Z_{o,a.v1.u}(f) || Z_{v2.lo}(f)$$
(9.47)

$$Z_{o.aik.u.hi}(f) = Z_{o.a.v1.u}(f) || Z_{v2.hi}(f)$$
(9.48)

9.6 Input capacitances C_{i,v1} and C_{i,v2} Output capacitances C_{0,v1} & C_{0,v2} and C_L

data sheet figures:	$\begin{array}{l} C_{g.c.v1} = \mbox{grid-cathode capacitance of V1} \\ C_{g.a.v1} = \mbox{grid-plate capacitance of V1} \\ C_{a.c.v1} = \mbox{plate-cathode capacitance of V1} \\ C_{g.c.v2} = \mbox{grid-cathode capacitance of V2} \\ C_{g.a.v2} = \mbox{grid-plate capacitance of V2} \\ C_{a.c.v2} = \mbox{plate-cathode capacitance of V2} \end{array}$
to be guessed:	$C_{stray.1}$ = sum of stray capacitances around V1 $C_{stray.2}$ = sum of stray capacitances around V2

Note: the Miller capacitance of the input depends on V1's gain G_{aik} only¹⁰!

$$C_{i,v1,b,lo,eff} = (1 + |G_{aik,b,lo,eff}|)C_{g,a,v1} ||C_{g,c,v1}||C_{stray,1}$$
(9.49)

$$C_{i.v1.b.hi.eff} = (1 + |G_{aik.b.hi.eff}|) C_{g.a.v1} || C_{g.c.v1} || C_{stray.1}$$
(9.50)

$$C_{i.v1.u.lo.eff} = (1 + |G_{aik.u.lo.eff}|)C_{g.a.v1} ||C_{g.c.v1} ||C_{stray.1}$$
(9.51)

$$C_{i,v1,u,hi,eff} = (1 + |G_{aik,u,hi,eff}|)C_{g,a,v1} ||C_{g,c,v1}||C_{stray,1}$$
(9.52)

$$C_{o.v1.lo} = C_{a.c.v1} \| C_{g.a.v1} \| C_{g.a.v2} \| C_{stray.2}$$
(9.53)

$$C_{o.v2.lo} = C_{a.c.v2}$$
 (9.54)

$$C_{o.v1.hi} = C_{a.c.v1} \parallel C_{g.a.v1}$$
 (9.55)

$$C_{o.v2.hi} = C_{a.c.v2} \parallel C_{stray.2}$$
 (9.56)

output capacitance CL:

to simulate a nearly real situation of an AIK gain stage with its rather high o/p impedance I've included a (tiny) load capacitance C_L into the calculation course, hence, Z_L becomes:

$$\mathbf{Z}_{\mathbf{L}} = \mathbf{R}_{\mathbf{L}} \parallel \mathbf{C}_{\mathbf{L}} \tag{9.57}$$

¹⁰ Miller capacitance effects on C_i and C_o: see Chapter 1, paragraph 1.3.2.5

9.7 Input impedance Z_{in}

$$Z_{in}(f) = R_{g1} \| C_{i,v1}$$
(9.58)

Inclusion of R_{ggl}^{11} and C_{in} into the calculation course leads to:

$$Z_{\text{in.b.lo.eff}}(f) = \left[\left(R_{gg1} + \frac{1}{2j\pi f C_{i.v1.b.lo.eff}} \right)^{-1} + \frac{1}{R_{g1}} \right]^{-1} + \frac{1}{2j\pi f C_{in}}$$
(9.59)

$$Z_{\text{in.b.hi.eff}}(f) = \left[\left(R_{gg1} + \frac{1}{2j\pi f C_{i.v1.b.hi.eff}} \right)^{-1} + \frac{1}{R_{g1}} \right]^{-1} + \frac{1}{2j\pi f C_{in}}$$
(9.60)

$$Z_{\text{in.u.lo.eff}}(f) = \left[\left(R_{gg1} + \frac{1}{2j\pi f C_{i.v1.u.lo.eff}} \right)^{-1} + \frac{1}{R_{g1}} \right]^{-1} + \frac{1}{2j\pi f C_{in}}$$
(9.61)

$$Z_{\text{in.u.hi.eff}}(f) = \left[\left(R_{gg1} + \frac{1}{2j\pi f C_{i.v1.u.hi.eff}} \right)^{-1} + \frac{1}{R_{g1}} \right]^{-1} + \frac{1}{2j\pi f C_{in}} \qquad (9.62)$$

¹¹ R_{gg1} = oscillation prevention resistor between grid of V1 and R_{g1}

Gain stage frequency and phase response calculations¹² 9.8

9.8.1 Bypassed version:



Figure 9.4 Simplified¹³ equivalent circuit of Figure 9.1 (bypassed version) - including all frequency and phase response relevant components

9.8.1.1 1^{st} stage (V1 = V1_c+V1_a) input transfer function $T_{i,1,b}(f)$ and phase $\varphi_{i,1,b}(f)$ including source resistance R_{s} and an oscillation preventing resistor $R_{ggl}{<<}R_{gl}{:}$

$$T_{i.1.b}(f) = \frac{v_{g.1}}{v_0}$$
(9.63)

$$\varphi_{i.1.b}(f) = \arctan\left\{\frac{\operatorname{Im}\left[\operatorname{T}_{i.1.b}(f)\right]}{\operatorname{Re}\left[\operatorname{T}_{i.1.b}(f)\right]}\right\}$$
(9.64)

$$T_{i,1,b}(f) = \frac{Z2_{b}(f) \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{b}(f)}\right)^{-1}}{\left(R_{gg1} + Z2_{b}(f)\right) \left[R_{S} + Z1(f) + \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{b}(f)}\right)^{-1}\right]}$$
(9.65)
$$Z1(f) = (2j\pi f C_{in})^{-1}$$
(9.66)
$$Z2_{b}(f) = (2j\pi f C_{i,v1,b})^{-1}$$
(9.66)

9.8.1.2 1^{st} stage V1_c cathode transfer function $T_{c1,b}(f)$ and phase $\varphi_{c1,b}(f)$:

$$\varphi_{c1.b}(f) = \arctan\left\{\frac{\mathrm{Im}\left[\mathrm{T}_{c1.b}\left(f\right)\right]}{\mathrm{Re}\left[\mathrm{T}_{c1.b}\left(f\right)\right]}\right\}$$
(9.67)

¹² By inclusion of the subscripts "lo" and "hi" the following formulae can be used for both the lo and hi versions (see respective MCD worksheets IX-1 and IX-2) 13

See footnotes 2 and 3 of Chapter 1 and footnote 3 of Chapter 2

$$T_{c1.b}(f) = \frac{R_{c.v1}}{R_{c.v1} + \frac{1}{2j\pi f C_{c1}}}$$
(9.68)

9.8.1.3 1^{st} stage output transfer function $T_{o.1.b}(f)$ and phase $\varphi_{o.1.b}(f)^{14}$:

$$T_{o.1.b}(f) = \frac{v_o}{v_{a.1}}$$
(9.69)

$$\varphi_{o.1.b}(f) = \arctan\left\{\frac{\mathrm{Im}\left[T_{o.1.b}(f)\right]}{\mathrm{Re}\left[T_{o.1.b}(f)\right]}\right\}$$
(9.70)

$$T_{o.1.b}(f) = \frac{Z_{L}(f)}{Z_{L}(f) + Z_{3}(f) + \left(\frac{1}{Z_{v2}(f)} + \frac{1}{Z_{o.a.v1.b}(f)}\right)^{-1}}$$
(9.71)
$$Z_{3}(f) = (2j\pi f C_{out})^{-1}$$
$$Z_{L}(f) = \left(\frac{1}{R_{L}} + 2j\pi f C_{L}\right)^{-1}$$
(9.72)

9.8.1.4
$$1^{st}$$
 stage fundamental phase shift $\varphi_{G,v1}(f)$:

$$\varphi_{G.v1}(f) = \varphi_{G.aik.b}(f) = -180^{\circ}$$
(9.73)

9.8.1.5 total gain stage transfer function $T_{tot,b}(f)$ and phase $\varphi_{tot,b}(f)$:

$$T_{tot.b}(f) = T_{i.1.b}(f) T_{c1.b}(f) T_{o.1.b}(f) G_{aik.b}$$
(9.74)

$$\varphi_{\text{tot.b}}(f) = \varphi_{i.1.b}(f) + \varphi_{c1.b}(f) + \varphi_{o.1.b}(f) + \varphi_{G.aik.b}(f)$$
(9.75)

 $^{^{14}}$ $R_{\rm L}$ and $C_{\rm L}$ need to be carefully chosen because they heavily influence the gain and phase of the AIK; $R_{\rm L}$ should be chosen as high as possible, eg. a CF2 à la Chapter 3

9.8.2 Un-bypassed version:



Figure 9.5 Simplified¹⁵ equivalent circuit of Figure 9.1 (un-bypassed version) - including all frequency and phase response relevant components

9.8.2.1 1^{st} stage (V1_a) input transfer function $T_{i,1,u}(f)$ and phase $\varphi_{i,1,u}(f)$ - including source resistance R_s and an oscillation preventing resistor $R_{gg1} \ll R_{g1}$:

$$T_{i.1.u}(f) = \frac{v_{g.1}}{v_0}$$
(9.76)

$$\varphi_{i.1.u}(f) = \arctan\left\{\frac{\operatorname{Im}\left[T_{i.1.u}(f)\right]}{\operatorname{Re}\left[T_{i.1.u}(f)\right]}\right\}$$
(9.77)

$$T_{i.1.u}(f) = \frac{Z2_{u}(f) \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{u}(f)}\right)^{-1}}{\left(R_{gg1} + Z2_{u}(f)\right) \left[R_{S} + Z1(f) + \left(\frac{1}{R_{g1}} + \frac{1}{R_{gg1} + Z2_{u}(f)}\right)^{-1}\right]} \qquad (9.78)$$

$$Z1(f) = (2j\pi f C_{in})^{-1}$$

$$Z2_{u}(f) = (2j\pi f C_{i.v1.u})^{-1} \qquad (9.79)$$

9.8.2.2 1^{st} stage output transfer function $T_{o.1.u}(f)$ and phase $\varphi_{o.1.u}(f)^{16}$:

$$T_{o.1.u}(f) = \frac{v_o}{v_{a.1}}$$
(9.80)

$$\varphi_{o.1.u}(f) = \arctan\left\{\frac{\mathrm{Im}\left[T_{o.1.u}(f)\right]}{\mathrm{Re}\left[T_{o.1.u}(f)\right]}\right\}$$
(9.81)

¹⁵ See also footnotes 2 and 3 of Chapter 1

¹⁶ see footnote 7

$$T_{o.1.u}(f) = \frac{Z_{L}(f)}{Z_{L}(f) + Z_{3}(f) + \left(\frac{1}{Z_{v2}(f)} + \frac{1}{Z_{o.a.v1.u}(f)}\right)^{-1}}$$
(9.82)
$$Z_{3}(f) = (2j\pi f C_{out})^{-1}$$
$$Z_{L}(f) = \left(\frac{1}{R_{L}} + 2j\pi f C_{L}\right)^{-1}$$
(9.83)

9.8.2.3 1^{st} stage fundamental phase shift $\phi_{G.v1}(f)$:

$$\varphi_{G,v1}(f) = \varphi_{G,aik,u}(f) = -180^{\circ}$$
(9.84)

9.8.2.4 total gain stage transfer function $T_{tot.u}(f)$ and phase $\phi_{tot.u}(f)$:

$$T_{tot.u}(f) = T_{i.1.u}(f) T_{o.1.u}(f) G_{aik.u}$$
(9.85)

$$\varphi_{tot.u}(f) = \varphi_{i.1.u}(f) + \varphi_{o.1.u}(f) + \varphi_{G.aik.u}(f)$$
 (9.86)

9.9 Example with ECC83 / 12AX7 (83 & lo):





9.9.1 Triode bias data:

$I_{a1.83} = I_{a2.83} = 1.2 \cdot 10^{-3} A$	$V_{a1.83} = 100V$	$V_{a2.83} = 100 V$
$V_{cc} = 201 V$	$V_{g1,83} = -0.5V$	$V_{g283} = 100.5V$

9.9.2 Triode valve constants:

$g_{m.83} := 1.75 \cdot 10^{-5} \cdot S$	$\mu_{83} := 101.5$	$\mathbf{r}_{a.83} \coloneqq 58 \cdot 10^{5} \Omega$
$\mathtt{g}_{m,v1}\coloneqq\mathtt{g}_{m,83}$	$\mu_{v1} \coloneqq \mu_{83}$	$r_{a.v1} \coloneqq r_{a.83}$
$\mathtt{g}_{m.v2} \coloneqq \mathtt{g}_{m.83}$	$\mu_{v2} \coloneqq \mu_{83}$	$r_{a.v2} \coloneqq r_{a.83}$
$C_{g.c.1.83} \coloneqq 1.65 \cdot 10^{-12} F$	$C_{g.a.1.83} \coloneqq 1.6 \cdot 10^{-12} F$	$C_{a.c.1.83} \coloneqq 0.33 \cdot 10^{-12} F$
$C_{g.c.2.83} \coloneqq 1.65 \cdot 10^{-12} F$	$C_{g.a.2.83} \coloneqq 1.6 \cdot 10^{-12} F$	$C_{a.c.2.83} \coloneqq 0.33 \cdot 10^{-12} F$
9.9.3 Circuit variables:		
$R_{c1.83} := 417\Omega$	$R_{c2.83} := R_{c1.83}$	$R_{c.83} := R_{c1.83}$
$R_{c1.83} \coloneqq 417\Omega$ $R_{S} \coloneqq 1 \cdot 10^{3}\Omega$	$R_{c2.83} \coloneqq R_{c1.83}$ $R_{g1.83} \coloneqq 47.5 \cdot 10^{3} \Omega$	$R_{c.83} \coloneqq R_{c1.83}$ $R_{gg1.83} \coloneqq 0.22 \cdot 10^{3} \Omega$
$R_{c1.83} := 417\Omega$ $R_{S} := 1 \cdot 10^{3}\Omega$ $R_{L} := 1 \cdot 10^{6}\Omega$	$R_{c2.83} \coloneqq R_{c1.83}$ $R_{g1.83} \coloneqq 47.5 \cdot 10^{3} \Omega$ $C_{in.83} \coloneqq 2.2 \cdot 10^{-6} F$	$R_{c.83} := R_{c1.83}$ $R_{gg1.83} := 0.22 \cdot 10^{3} \Omega$ $C_{out.83} := 1 \cdot 10^{-6} F$
$R_{c1.83} \coloneqq 417\Omega$ $R_{S} \coloneqq 1 \cdot 10^{3}\Omega$ $R_{L} \coloneqq 1 \cdot 10^{6}\Omega$ $C_{L} \coloneqq 10 \cdot 10^{-12}F$	$R_{c2.83} \coloneqq R_{c1.83}$ $R_{g1.83} \coloneqq 47.5 \cdot 10^{3} \Omega$ $C_{in.83} \coloneqq 2.2 \cdot 10^{-6} F$ $C_{stray.83.1} \coloneqq 10 \cdot 10^{-12} F$	$R_{c.83} \coloneqq R_{c1.83}$ $R_{gg1.83} \coloneqq 0.22 \cdot 10^{3} \Omega$ $C_{out.83} \coloneqq 1 \cdot 10^{-6} F$ $C_{stray.83.2} \coloneqq 2 \cdot 10^{-12} F$

9.9.4 Calculation relevant data:

frequency range f for the below shown graphs: f := 10Hz, 20Hz.. 100000 Hz

9.9.5 Gain G_{aik.83.b.lo} :

$$\begin{split} R_{v2.lo} &\coloneqq r_{a.83} + \left(1 + \mu_{83}\right) \cdot R_{c\,1.83} \\ G_{aik,\,83.b.lo} &\coloneqq -g_{m.83} \cdot \left(\frac{1}{r_{a.83}} + \frac{1}{R_{v2.lo}}\right)^{-1} \end{split}$$

 $G_{aik.\,83.b.lo.e} \coloneqq 20 \cdot \log(\left|G_{aik.\,83.b.lo}\right|)$

$$\mathbf{G}_{aik.83.b.lo.eff} \coloneqq -\mathbf{g}_{m.83} \cdot \left(\frac{1}{\mathbf{r}_{a.83}} + \frac{1}{\mathbf{R}_{v2.lo}} + \frac{1}{\mathbf{R}_{L}}\right)^{-}$$

$$G_{aik.83.b.lo.eff.e} = 20 \cdot log(G_{aik.83.b.lo.eff})$$

9.9.6 Gain Gaik.83.u.lo:

$$\begin{split} & G_{aik, 83.u.b} \coloneqq -\frac{1}{2} \cdot g_{m, 83} \cdot r_{a, 83} \\ & G_{aik, 83.u.b.e} \coloneqq 20 \cdot \log(\left|G_{aik, 83.u.b}\right|) \\ & G_{aik, 83.u.b.eff} \coloneqq -g_{m, 83} \cdot \frac{r_{a, 83} \cdot R_L}{r_{a, 83} + (1 + \mu_{83}) \cdot R_{c, 83} + 2 \cdot R_L} \end{split}$$

$$G_{aik.83.u.lo.eff.e} = 20 \cdot log(|G_{aik.83.u.lo.eff}|)$$

9.9.7 Specific resistances:

$$\begin{split} & R_{o.a.v1.b} \coloneqq r_{a.v1} \\ & R_{o.aik.b.lo} \coloneqq \left(\frac{1}{R_{o.a.v1.b}} + \frac{1}{R_{v2.lo}}\right)^{-1} \\ & r_{c.v1.lo} \coloneqq \frac{r_{a.v1} + R_{v2.lo}}{1 + \mu_{v1}} \\ & R_{c.v1.lo} \coloneqq \left(\frac{1}{r_{c.v1.lo}} + \frac{1}{R_{c1.83}}\right)^{-1} \\ & R_{o.a.v1.u} \coloneqq r_{a.v1} + (1 + \mu_{v1}) \cdot R_{c1.83} \\ & R_{o.aik.u.lo} \coloneqq \left(\frac{1}{R_{o.a.v1.u}} + \frac{1}{R_{v2.lo}}\right)^{-1} \end{split}$$

h := 1000 ·Hz

$$R_{v2.lo} = 100.743 \times 10^{3} \Omega$$

 $G_{aik.83.b.lo} = -64.415 \times 10^{0}$ [dB]
 $G_{aik.83.b.lo.e} = 36.18 \times 10^{0}$ [dB]
 $G_{aik.83.b.lo.eff} = -62.128 \times 10^{0}$ [dB]
 $G_{aik.83.b.lo.eff.e} = 35.866 \times 10^{0}$ [dB]
 $G_{aik.83.u.lo} = -50.75 \times 10^{0}$
 $G_{aik.83.u.lo.e} = 34.109 \times 10^{0}$ [dB]
 $G_{aik.83.u.lo.eff} = -48.316 \times 10^{0}$ [dB]

$$G_{aik, 83, u, lo} = -50.75 \times 10^{\circ}$$

$$G_{aik, 83, u, lo, e} = 34.109 \times 10^{0} \quad [dB]$$

$$G_{aik, 83, u, lo, eff} = -48.316 \times 10^{0}$$

$$G_{aik.83.u.lo.eff.e} = 33.682 \times 10^{0} [dB]$$

$$R_{o.a.v1.b} = 58 \times 10^{3} \Omega$$

$$R_{o.aik.b.lo} = 36.808 \times 10^{3} \Omega$$

$$R_{c.v1.lo} = 1.549 \times 10^{3} \Omega$$

$$R_{c.v1.lo} = 328.539 \times 10^{0} \Omega$$

$$R_{o.a.v1.u} = 100.743 \times 10^{3} \Omega$$

$$R_{o.aik.u.lo} = 50.371 \times 10^{3} \Omega$$



➢ MCD Worksheet IX-1 AIK -



➢ MCD Worksheet IX-1

AIK -lo- calculations





Figure 9.14 Phase of V1 o/p network $\phi_{G,V1}(f) := -180 \text{deg}$

$$T_{tot.83.b.lo}(f) := T_{i.1.b.lo}(f) \cdot T_{c1.b.lo}(f) T_{o.1.b.lo}(f) \cdot G_{aik.83.b.lo}$$

$$T_{tot.83.b.lo.e}(f) \coloneqq 20 \cdot \log(|T_{tot.83.b.lo}(f)|)$$

$$T_{tot 83 h lo e}(h) = 35.684 \times 10^0 \text{ [dB]}$$

 $\phi_{\text{tot.83,b.b}}(f) := \phi_{i,1,b,10}(f) + \phi_{c,1,b,10}(f) + \phi_{o,1,b,10}(f) + \phi_{G,v1}(f)$





9.10 Example with ECC83 / 12AX7 (83 & hi):



Figure 9.19 AIK example circuitry with a high-Z current source plate load

9.10.1 Triode bias data:					
$I_{a1.83} = I_{a2.83} = 1.2 \cdot 10^{-3} A$	$V_{a1.83} = 100 V$	$V_{a2.83} = 100V$			
$V_{cc} = 268.5 V$	$V_{g1.83} = -0.5V$	$V_{g2.83} = 168V$			
9.10.2 Triode valve constants:					
$g_{m.83} := 1.75 \cdot 10^{-3} \cdot S$	$\mu_{83} := 101.5$	$r_{a.83} \coloneqq 58 \cdot 10^3 \Omega$			
$g_{m.v1} \coloneqq g_{m.83}$	$\mu_{v1}\coloneqq \mu_{83}$	$r_{a.v1} \coloneqq r_{a.83}$			
$g_{m.v2} \coloneqq g_{m.83}$	$\mu_{v2} \coloneqq \mu_{83}$	$r_{a.v2} := r_{a.83}$			
$C_{g.c.1.83} \coloneqq 1.65 \cdot 10^{-12} F$	$C_{g.a.1.83} \coloneqq 1.6 \cdot 10^{-12} F$	$C_{a.c.1.83} \coloneqq 0.33 \cdot 10^{-12} F$			
$C_{g.c.2.83} := 1.65 \cdot 10^{-12} F$	$C_{g.a.2.83} \coloneqq 1.6 \cdot 10^{-12} F$	$C_{a.c.2.83} \coloneqq 0.33 \cdot 10^{-12} F$			
9.10.3 Circuit variables:					
$R_{c1.83} := 417\Omega$	$R_{c2.1.83} \coloneqq R_{c1.83}$	$R_{c2.2.83} := 56.2 \cdot 10^3 \Omega$			
$R_{S} := 1 \cdot 10^{3} \Omega$	$R_{g1.83} := 47.5 \cdot 10^3 \Omega$	$R_{gg1.83} \coloneqq 0.22 \cdot 10^3 \Omega$			
$R_{L} := 5 \cdot 10^{6} \Omega$	$R_{g2.83} \coloneqq 1.10^6 \Omega$				
$C_{L} \coloneqq 2 \cdot 10^{-12} F$	$C_{stray.83.1} := 10 \cdot 10^{-12} F$	$C_{stray.83.2} \coloneqq 2 \cdot 10^{-12} F$			
	$C_{in.83} := 2.2 \cdot 10^{-6} F$	$C_{out.83} := 1 \cdot 10^{-6} F$			

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9.10.4 Calculation relevant data:

frequency range f for the below shown graphs: f := 10Hz, 20Hz.. 100000 Hz $h := 1000 \cdot Hz$ 9.10.5 Gain Gaik 83 h hi : $R_{p2.83} := \left(\frac{1}{R_{c2.2.83}} + \frac{1}{R_{p2.83}}\right)^{-1}$ $R_{v2.hi} \coloneqq r_{a.83} + (1 + \mu_{83}) \cdot (R_{c2.1.83} + R_{p2.83})$ $R_{p3.83} := \left(\frac{1}{R_{v2 \, hi}} + \frac{1}{R_{I}}\right)^{-1}$ $R_{v2 \text{ hi}} = 5.555 \times 10^6 \Omega$ $G_{aik.83.b.hi} := -g_{m.83} \left(\frac{1}{r_{a.83}} + \frac{1}{R_{v2.hi}} \right)^{-1}$ $G_{aik, 83.b.hi} = -100.451 \times 10^{0}$ $G_{aik 83 b hie} = 40.039 \times 10^{0}$ $G_{aik.83.b.hi.e} := 20 \cdot \log(|G_{aik.83.b.hi}|)$ $G_{aik.83.b.hi.eff} := -g_{m.83} \cdot \left(\frac{1}{r_{a.83}} + \frac{1}{R_{p3.83}}\right)^{-1}$ $G_{aik 83 b hi eff} = -99.311 \times 10^{0}$ $G_{aik 83 b hieff e} = 39.94 \times 10^0 [dB]$ $G_{aik, 83.b.hieff,e} = 20 \cdot \log(|G_{aik, 83.b.hieff}|)$ 9.10.6 Gain Gaik.83.u.hi: $G_{aik,83.u.hi} := -g_{m.83} \cdot \frac{r_{a.83} \cdot R_{v2.hi}}{r_{a.83} + (1 + \mu_{83}) \cdot R_{c1.83} + R_{v2.hi}}$ $G_{aik.83.u.hi} = -99.692 \times 10^{0}$ $G_{aik 83 \text{ u bie}} = 39.973 \times 10^{0}$ $G_{aik.83.u.hi.e} := 20 \cdot log(|G_{aik.83.u.hi}|)$ $G_{aik.83.u.hieff} := -g_{m.83} \cdot \frac{r_{a.83} \cdot R_{p3.83}}{r_{a.83} + (1 + \mu_{83}) \cdot R_{c1.83} + R_{p3.83}}$ $G_{aik 83 u hieff} = -97.757 \times 10^{0}$ $G_{aik, 83.u.hi.eff} = 39.803 \times 10^{0}$ $G_{aik,83.u,hi.eff.e} = 20 \cdot \log(|G_{aik,83.u,hi.eff}|)$

[dB]

[dB]

[dB]

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9.10.10 Specific input and output capacitances:

$$C_{i,v1,b,hi} \coloneqq (1 + |G_{aik,83,b,hi}|) \cdot C_{g,a,1,83} + C_{g,c,1,83} + C_{stray,83,1} + C_{i,v1,b,hi} = 173.972 \times 10^{-12} \text{ F}$$

$$C_{i,v1,u,hi} \coloneqq (1 + |G_{aik,83,u,hi}|) \cdot C_{g,a,1,83} + C_{g,c,1,83} + C_{stray,83,1} + C_{i,v1,u,hi} = 172.757 \times 10^{-12} \text{ F}$$

$$C_{o,v1,hi} \coloneqq C_{a,c,1,83} + C_{g,a,1,83} + C_{g,c,1,83} + C_{stray,83,1} + C_{o,v1,hi} = 1.93 \times 10^{-12} \text{ F}$$

$$C_{o,v2,hi} \coloneqq C_{a,c,2,83} + C_{stray,83,2} + C_{o,v2,hi} \equiv 2.33 \times 10^{-12} \text{ F}$$

9.10.11 Specific impedances:

$$\begin{aligned} X_{v2,hi}(f) &:= \left(\frac{1}{R_{c2.1.83} + R_{p2.83}} + 2j \cdot \pi \cdot fC_{g.c.2.83}\right)^{-1} & Y_{v2,hi}(f) &:= 2j \cdot \pi \cdot f(C_{g.a.2.83} + C_{stray.83.2}) \\ Z_{v2,hi}(f) &:= \left[\left[\left(\frac{1}{r_{a.v2}} + 2j \cdot \pi \cdot fC_{a.c.2.83}\right)^{-1} + (1 + \mu_{83}) \cdot X_{v2,hi}(f)\right]^{-1} + Y_{v2,hi}(f)\right]^{-1} \end{aligned}$$



Figure 9.21 Hi-current source impedance vs. frequency

$$\begin{split} & Z_{o.a.v1.b}(f) := \left(\frac{1}{R_{o.a.v1.b}} + 2j \cdot \pi \cdot f \cdot C_{o.v1.hi}\right)^{-1} \\ & Z_{o.aik.b.hi}(f) := \left(\frac{1}{Z_{o.a.v1.b}(f)} + \frac{1}{Z_{v2.hi}(f)}\right)^{-1} \\ & Z_{o.a.v1.u}(f) := \left(\frac{1}{R_{o.a.v1.u}} + 2j \cdot \pi \cdot f \cdot C_{o.v1.hi}\right)^{-1} \\ & Z_{o.aik.u.hi}(f) := \left(\frac{1}{Z_{o.a.v1.u}(f)} + \frac{1}{Z_{v2.hi}(f)}\right)^{-1} \end{split}$$

$$\begin{split} \left| Z_{v2,hi}(h) \right| &= 5.511 \times 10^{6} \Omega \\ \left| Z_{o.a.v1,b}(h) \right| &= 58 \times 10^{3} \Omega \\ \left| Z_{o.aik,b,hi}(h) \right| &= 57.401 \times 10^{3} \Omega \\ \left| Z_{o.a.v1,u}(h) \right| &= 100.742 \times 10^{3} \Omega \\ \left| Z_{o.aik,u,hi}(h) \right| &= 98.947 \times 10^{3} \Omega \end{split}$$

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MCD Worksheet IX-2









10.1 Circuit diagram



Figure 10.1 Basic design of the Cascoded Cathode Follower (CCF) gain stage



Figure 10.2 Constant current sink alternatives: a) = low-Z, b) = high-Z

10.2 Basic assumptions

The CCF is nothing else but a $CF2_u$ around V1 (improved CF version à la Chapter 3) with an actively loaded cathode by a constant current sink around V2 à la Chapters 5.2 or 5.4, thus, as mentioned in Chapter 3, producing a gain near 1 because of the very high internal resistance R_{v2} of the current sinks that replace the cathode resistor $R_{c.2}$ of Figure 3.4.

With this in mind and with the following assumptions the relevant equations become derivations of the equations given in the previous CF and CCG chapters:

- V1 does not need to equal V2
- $g_{m.v1} = or \neq g_{m.v2}$
- $r_{a.v1} = or \neq r_{a.v2}$
- $\mu_{v1} = or \neq \mu_{v2}$
- $R_{c1} = or \neq R_{c2.a}$
- $\bullet \qquad R_{c2.b} \qquad \geq \qquad R_{c2.a}$

But:

• plate current V1 I_{a1} = plate current V2 I_{a2}

10.3 Basic formulae (excl. stage load (R_L)-effect)¹

10.3.1 Gain of the low-Z version:

The V2 active AC resistance R_{v2.lo} becomes:

$$R_{v2.lo} = r_{a.v2} + (1 + \mu_{v2})R_{c2.a}$$
(10.1)

The gain G_{ccf.lo} of the low-Z loaded CCF_{lo} becomes:

$$G_{ccf,lo} = g_{m,v1} \frac{r_{a,v1} \| (R_{c1} + R_{v2,lo})}{1 + g_{m,v1} [r_{a,v1} \| (R_{c1} + R_{v2,lo})]}$$

$$= \mu_{v1} \frac{R_{c1} + R_{v2,lo}}{r_{a,v1} + (1 + \mu_{v1}) (R_{c1} + R_{v2,lo})}$$
(10.2)

rule of thumb:

1

with $R_{v2,lo} \gg r_{a,v1}$ and $R_{c2,a} \ge R_{c1} G_{ccf,lo,rot}$ becomes:

$$G_{\text{ccf.lo.rot}} = \frac{\mu_{\text{vl}}}{1 + \mu_{\text{vl}}} \tag{10.3}$$

For detailed derivations of the shown equations: please refer to Chapter 3

The V2 active AC impedance $Z_{v2.lo}(f)$ becomes:

$$Z_{v2.lo}(f) = \left[\left(r_{a.v2} \| C_{a.c2} \right) + \left(1 + \mu_{v2} \right) \left(R_{c2.a} \| C_{g.c2} \right) \right] \| C_{g.a2} \| C_{stray.2}$$
(10.4)

10.3.2 Input and output impedances of the low-Z version:

Input resistance $R_{i,g1,lo}$ and impedance $Z_{i,g1,lo}(f)$ at the grid of V1 become:

$$R_{i,g1,lo} = \frac{R_{g1}}{1 - G_{ccf,lo}}$$
(10.5)

$$Z_{i,g1,lo}(f) = R_{i,g1,lo} \| C_{i,tot,lo}$$
(10.6)

$$C_{i.tot.lo} = \frac{\left[C_{g.a1} \| C_{stray.1} \| (1 - G_{ccf.lo}) C_{g.c1} \right] \left[C_{g.a2} \| C_{stray.2} \right]}{\left[C_{g.a1} \| C_{stray.1} \| (1 - G_{ccf.lo}) C_{g.c1} \right] + \left[C_{g.a2} \| C_{stray.2} \right]}$$
(10.7)

The output resistance $R_{o.cl.lo}$ at the cathode of V1 becomes²:

$$R_{o.c1.lo} = r_{c.v1} \| (R_{c1} + R_{v2.lo})$$
(10.8)

$$r_{c.vl} = \frac{r_{a.vl}}{1 + \mu_{vl}}$$
(10.9)

10.3.3 Gain of the high-Z version:

The V2 active AC resistance R_{v2.hi} becomes:

$$R_{v2.hi} = r_{a.v2} + (1 + \mu_{v2}) R_{c2.b}$$
(10.10)

The gain G_{ccf.hi} of the low-Z loaded CCF_{hi} becomes:

$$G_{ccf.hi} = g_{m.v1} \frac{r_{a.v1} \| (R_{c1} + R_{v2.hi})}{1 + g_{m.v1} [r_{a.v1} \| (R_{c1} + R_{v2.hi})]}$$

$$= \mu_{v1} \frac{R_{c1} + R_{v2.hi}}{r_{a.v1} + (1 + \mu_{v1}) (R_{c1} + R_{v2.hi})}$$
(10.11)

rule of thumb:

with $R_{v2,hi} >> r_{a,v1}$ and $R_{c2,b} \ge R_{c1} G_{ccf,hi,rot}$ becomes:

 $^{^2}$ $$Because of the rather low 0/p resistance of V1 any valve related capacitance won't play a role in <math display="inline">B_{20k}$

$$G_{ccf.hi.rot} = \frac{\mu_{v1}}{1 + \mu_{v1}}$$
(10.12)

The V2 active AC impedance $Z_{v2.lo}(f)$ becomes:

$$Z_{v2.hi}(f) = \left[(r_{a.v2} \parallel C_{a.c2}) + (1 + \mu_{v2}) (R_{c2.b} \parallel C_{g.c2}) \right] \parallel C_{g.a2} \parallel C_{stray.2}$$
(10.13)

10.3.4 Input and output impedances of the high-Z version:

Input resistance $R_{i,g1,hi}$ and impedance $Z_{i,g1,hi}(f)$ at the grid of V1 become:

$$R_{i.gl.hi} = \frac{R_{gl}}{1 - G_{ccf.hi}}$$
(10.14)

$$Z_{i.g1.hi}(f) = R_{i.g1.hi} || C_{i.tot.hi}$$
 (10.15)

$$C_{i.tot.hi} = \frac{\left[C_{g.a1} \| C_{stray.1} \| (1 - Ghi) C_{g.c1}\right] \left[C_{g.a2} \| C_{stray.2}\right]}{\left[C_{g.a1} \| C_{stray.1} \| (1 - G_{ccf.hi}) C_{g.c1}\right] + \left[C_{g.a2} \| C_{stray.2}\right]}$$
(10.16)

The output resistance R_{o.c1.hi} at the cathode of V1 becomes³:

$$R_{o,cl,hi} = r_{c,vl} \| \left(R_{cl} + R_{v2,hi} \right)$$
(10.17)

$$r_{c.vl} = \frac{r_{a.vl}}{1 + \mu_{vl}}$$
(10.18)

10.3.5 Grid voltage divider of the high-Z version and grid capacitance Cg2:

$$V_{C,g2} = V_{R,c2,b} + V_{g2}$$

$$V_{R,c2,b} = I_{a2}R_{c2,b}$$
(10.19)

$$R_{g2.2} = R_{g2.1} \frac{V_{cc} - V_{C.g2}}{V_{C.g2}}$$
(10.20)

$$C_{g2} = \frac{1}{2\pi f_{c.opt} \left(R_{g2.1} \parallel R_{g2.2} \right)}$$
(10.21)

$$f_{c.opt} = 0.2 Hz$$
 (10.22)

 $^{^3}$ Because of the rather low 0/p resistance of V1 any valve related capacitance won't play a role in B_{20k}
10.4 Gain stage frequency and phase response calculations

10.4.1 Low-Z version⁴:



Figure 10.3 Simplified equivalent circuit of Figure 10.1 with the low-Z CCG as the cathode load - including all frequency and phase response relevant components

10.4.1.1 Gain stage input transfer function $T_{i,lo}(f)$ and phase $\varphi_{i,lo}(f)$ - including source resistance R_s and an oscillation preventing resistor $R_{ggl} \leq R_{gl}$:

$$T_{i,lo}(f) = \frac{v_{g1}}{v_0}$$
(10.23)

$$M_{i,lo}(f) = \frac{Z2_{lo}(f)}{R_{gg1} + Z2_{lo}(f)}$$
(10.24)

$$N_{i,lo}(f) = \frac{R_{i,g1,lo} \| (R_{gg1} + Z_{lo}(f))}{Zl(f) + [R_{i,g1,lo} \| (R_{gg1} + Z_{lo}(f))]}$$
(10.25)

$$O_{i,lo}(f) = \frac{R1 \| \left\{ Zl(f) + \left[R_{i,g1,lo} \| \left(R_{gg1} + Z2_{lo}(f) \right) \right] \right\}}{RS + \left[R1 \| \left\{ Zl(f) + \left[R_{i,g1,lo} \| \left(R_{gg1} + Z2_{lo}(f) \right) \right] \right\} \right]}$$
(10.26)

$$Zl(f) = (2j\pi f C_{in})^{-1}$$

$$Z2_{lo}(f) = (2j\pi f C_{i,tot,lo})^{-1}$$
(10.27)

$$T_{i,lo}(f) = M_{i,lo}(f) N_{i,lo}(f) O_{i,lo}(f)$$
 (10.28)

$$\varphi_{i,lo}(f) = \arctan\left\{\frac{\mathrm{Im}\left[T_{i,lo}(f)\right]}{\mathrm{Re}\left[T_{i,lo}(f)\right]}\right\}$$
(10.29)

⁴ As could be demonstrated in the following MCD worksheets to achieve a gain near 1 this type of CCF works sufficiently well with high μ (>50) V1 valves. Because of their rather high r_a these valves also produce comparatively high cathode output resistances.

10.4.1.2 Gain stage output transfer function $T_{o.lo}(f)$ and phase $\phi_{o.lo}(f)$:

$$Z3(f) = (2j\pi f C_{out})^{-1}$$
(10.30)

$$T_{o,lo}(f) = \frac{v_o}{v_{R,cl}} = \frac{R_L}{R_L + R_{o,cl,lo} + Z3(f)}$$
(10.31)

$$\varphi_{o,lo}(f) = \arctan\left\{\frac{\text{Im}\left[T_{o,lo}(f)\right]}{\text{Re}\left[T_{o,lo}(f)\right]}\right\}$$
(10.32)

10.4.1.3 Fundamental gain stage phase shift $\varphi_{G.ccf.lo}(f)$:

$$\varphi_{\text{G.ccf.lo}}(f) = 0^{\circ} \tag{10.33}$$

10.4.1.4 Gain stage transfer function $T_{tot.lo}$ (f) and phase $\varphi_{tot.lo}$ (f):

$$T_{tot.lo}(f) = T_{i.lo}(f) T_{o.lo}(f) G_{ccf.lo}$$
 (10.34)

$$\varphi_{\text{tot.lo}}(f) = \varphi_{i.lo}(f) + \varphi_{o.lo}(f) + \varphi_{G.ccf.lo}(f)$$
 (10.35)

10.4.2 High-Z version⁵:



Figure 10.4 Simplified equivalent circuit of Figure 10.1 with the high-Z CCG as the cathode load - including all frequency and phase response relevant components

 $\begin{array}{ll} 10.4.2.1 & \mbox{Gain stage input transfer function $T_{i,hi}(f)$ and phase $\phi_{i,hi}(f)$ - including source} \\ resistance R_s and an oscillation preventing resistor R_{ggl} << R_{gl}: } \end{array}$

$$T_{i,hi}(f) = \frac{v_{g1}}{v_0}$$
(10.36)

⁵ As could be demonstrated in the following MCD worksheets to achieve a gain near 1 this type of CCF works sufficiently well with low μ (<40) V1 valves. Because of their rather low r_a these valves also produce comparatively low cathode output resistances.

$$M_{i,hi}(f) = \frac{Z2_{hi}(f)}{R_{gg1} + Z2_{hi}(f)}$$
(10.37)

$$N_{i,hi}(f) = \frac{R_{i,g1,hi} \parallel (R_{gg1} + Z2_{hi}(f))}{Zl(f) + [R_{i,g1,hi} \parallel (R_{gg1} + Z2_{hi}(f))]}$$
(10.38)

$$O_{i,hi}(f) = \frac{R1 \| \left\{ Zl(f) + \left[R_{i,g1,hi} \| \left(R_{gg1} + Z2_{hi}(f) \right) \right] \right\}}{RS + \left[R1 \| \left\{ Zl(f) + \left[R_{i,g1,hi} \| \left(R_{gg1} + Z2_{hi}(f) \right) \right] \right\} \right]}$$
(10.39)

$$Z1(f) = (2j\pi f C_{in})^{-1}$$

$$Z2_{hi}(f) = (2j\pi f C_{i.tot.hi})^{-1}$$
(10.40)

$$T_{i,hi}(f) = M_{i,hi}(f) N_{i,hi}(f) O_{i,hi}(f)$$
(10.41)

$$\varphi_{i.hi}(f) = \arctan\left\{\frac{\text{Im}\left[T_{i.hi}\left(f\right)\right]}{\text{Re}\left[T_{i.hi}\left(f\right)\right]}\right\}$$
(10.42)

 $10.4.2.2 \qquad \mbox{Gain stage output transfer function $T_{o.hi}(f)$ and phase $\phi_{o.hi}(f)$:}$

$$Z3(f) = (2j\pi f C_{out})^{-1}$$
(10.43)

$$T_{o.hi}(f) = \frac{v_o}{v_{R.c1}} = \frac{R_L}{R_L + R_{o.c1.hi} + Z3(f)}$$
(10.44)

$$\varphi_{o,hi}(f) = \arctan\left\{\frac{\text{Im}\left[T_{o,hi}(f)\right]}{\text{Re}\left[T_{o,hi}(f)\right]}\right\}$$
(10.45)

10.4.2.3 Fundamental gain stage phase shift $\phi_{G.ccf.hi}(f)$:

$$\varphi_{\text{G.ccf.hi}}(f) = 0^{\circ} \tag{10.46}$$

 $10.4.4.4 \qquad \text{Gain stage transfer function } T_{tot,hi}\left(f\right) \text{ and phase } \phi_{tot,hi}\left(f\right):$

$$T_{tot,hi}(f) = T_{i,hi}(f) T_{o,hi}(f) G_{ccf,hi}$$

$$(10.47)$$

$$\varphi_{\text{tot,hi}}(f) = \varphi_{i,\text{hi}}(f) + \varphi_{o,\text{hi}}(f) + \varphi_{G,\text{ccf,hi}}(f)$$
(10.48)





10.5.1 Triodes bias data:

$I_{a1} := 1.2 \cdot 10^{-3} A$	$I_{a2} := I_{a1}$		
V _{cc} := 350V	$V_{Gen1} \coloneqq 100.5 V$	$V_{g1} \coloneqq -2.0V$	$V_{g2} \coloneqq -0.5V$
$V_{L1} := V_{cc} - V_{Gen1}$	$V_{L1} = 249.5 V$	$v_{R.c1} \coloneqq \left v_{g1} \right $	$V_{R.c2.a} \coloneqq V_{g2} $
$v_{a1} \coloneqq v_{L1} - v_{R.c1}$	$V_{a1} = 247.5 V$	$V_{a2} := V_{Gen1} - V_{R.c2.a}$	$V_{a2} = 100 V$
$V_{g1.grnd} \coloneqq V_{Gen1}$	$V_{g1.grnd} = 100.5 V$		

10.5.2. Triodes valve constants:

$g_{m.v1} := 1.6 \cdot 10^{-3} \cdot S$	$\mathbf{r}_{a.v1} \coloneqq 62.5 \cdot 10^3 \Omega$	$\mu_{v1} := 100$
$g_{m.v2} := 1.75 \cdot 10^{-3} S$	$r_{a.v2} \coloneqq 58 \cdot 10^3 \Omega$	$\mu_{v2} := 101.5$
$C_{g.c1.83} \coloneqq 1.65 \cdot 10^{-12} F$	$C_{g.a1.83} \coloneqq 1.6 \cdot 10^{-12} F$	$C_{a.c1.83} \coloneqq 0.33 \cdot 10^{-12} F$
$C_{g.c2.83} \coloneqq 1.65 \cdot 10^{-12} F$	$C_{g.a2.83} \coloneqq 1.6 \cdot 10^{-12} F$	$C_{a.c2.83} \coloneqq 0.33 \cdot 10^{-12} F$

10.5.3 Circuit variables:

$$\begin{split} & C_{stray,1} \coloneqq 10 \cdot 10^{-12} F & C_{stray,2} \coloneqq 10 \cdot 10^{-12} F \\ & R_{c1} \coloneqq \frac{V_{R,c1}}{I_{a1}} & R_{c1} = 1.667 \times 10^{3} \Omega & R_{gg1} \coloneqq 2.21 \cdot 10^{3} \Omega \\ & R_{c2,a} \coloneqq \frac{V_{R,c2,a}}{I_{a2}} & R_{c2,a} = 416.667 \ \Omega \\ & RS \coloneqq 1 \cdot 10^{3} \Omega & R_{g1} \coloneqq 1 \cdot 10^{6} \Omega & R_{L} \coloneqq 100 \cdot 10^{3} \Omega \\ & R1 \coloneqq 100 \cdot 10^{3} \Omega \end{split}$$

$$C_{in} := 0.1 \cdot 10^{-6} F$$
 $C_{out} := 100 \cdot 10^{-6} F$

10.5.4 Calculation relevant data:

frequency range f for the below shown graphs: f := 10Hz, 20Hz... 100000 Hzh := 1000Hz

10.5.5 Gain G_{ccf.lo} (frequency independent):

 $G_{ccf,lo.83,2} := \mu_{V1} \cdot \frac{R_{c1} + R_{V2,lo}}{r_{a,v1} + (1 + \mu_{V1}) \cdot (R_{c1} + R_{V2,lo})} \qquad G_{ccf,lo.83,2} = 0.984$ $G_{ccf,lo.83,1,e} := 20 \cdot \log(G_{ccf,lo.83,1}) \qquad G_{ccf,lo.83,1,e} = -0.139 \qquad [dB]$ $G_{ccf,lo.83,rot} := \frac{\mu_{V1}}{1 + \mu_{V1}} \qquad G_{ccf,lo.83,rot} = 0.99$ $G_{ccf,lo.83,rot,e} := 20 \cdot \log(G_{ccf,lo.83,rot}) \qquad G_{ccf,lo.83,rot,e} = -0.086 \qquad [dB]$

 $G_{ccf.lo.83.1.e} - G_{ccf.lo.83.rot.e} = -0.052$ [dB]

10.5.6 Gain $G_{ccf10}(f)$ (frequency dependent): $X_{v2.lo}(f) := 2j \cdot \pi \cdot f \cdot (C_{g.a2.83} + C_{stray.2})$ $Y_{v2.lo}(f) := \left[\left(\frac{1}{r_{a.v2}} + 2j \cdot \pi \cdot f \cdot C_{a.c2.83} \right)^{-1} + \left(1 + \mu_{v2} \right) \cdot \left(\frac{1}{R_{c2.a}} + 2j \cdot \pi \cdot f \cdot C_{g.c2.83} \right)^{-1} \right]^{-1}$ $Z_{v2.lo}(f) := \left[(Y_{v2.lo}(f)) + X_{v2.lo}(f) \right]^{-1}$ $Z_{v2.lo}(f) := \left[(Y_{v2.lo}(f)) + X_{v2.lo}(f) \right]^{-1}$ $Z_{v2.lo}(f) := \left[(Y_{v2.lo}(f)) + 1 \cdot 10^{6} \right]^{-1}$ $Z_{v2.lo}(f) := \left[(Y_{v2.lo}(f) + 1 \cdot 10^{6} \right]^{-1}$ $I \cdot 10^{4}$ $I \cdot 10^{6}$ $I \cdot 10^{6}$ I



$$\begin{split} G_{ccf,lo,83}(f) &:= \mu_{V1} \cdot \frac{R_{c1} + Z_{V2,lo}(f)}{r_{a,V1} + (1 + \mu_{V1}) \cdot (R_{c1} + Z_{V2,lo}(f))} & \left| G_{ccf,lo,83}(h) \right| = 0.984 \\ G_{ccf,lo,83,e}(f) &:= 20 \cdot \log\left(\left| G_{ccf,lo,83}(f) \right| \right) & G_{ccf,lo,83,e}(h) = -0.139 \quad [dB] \\ & \phi_{ccf,lo,83}(f) := \frac{Im(G_{ccf,lo,83}(f))}{Re(G_{ccf,lo,83}(f))} \end{split}$$







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Figure 10.11 Transfer of lo i/p network

$$T_{\text{tot.}b}(f) \coloneqq T_{i,b}(f) \cdot T_{o,b}(f) \cdot G_{\text{ccf.}b.83.1}$$

$$T_{\text{tot. lo. e}}(f) \coloneqq 20 \cdot \log(|T_{\text{tot. lo}}(f)|)$$

 $\phi_{\text{tot.lo}}(f) := \phi_{i,lo}(f) + \phi_{o,lo}(f) + \phi_{G.ccf.lo}(f)$



Figure 10.12 Transfer of lo o/p network

 $\phi_{G.ccf.lo}(f) \coloneqq 0$



Figure 10.13 Frequency response of the CCF-lo gain stage

$$T_{tot.lo.e}(h) := 20 \cdot log(|T_{tot.lo}(h)|)$$

 $T_{tot, lo, e}(h) = -0.279 [dB]$



Figure 10.14 Phase response of the CCF-lo gain stage

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Figure 10.15 CCF-hi example circuitry



Figure 10.16 DC voltage arrangement of Figure 10.15 - hi version

10.6.1 Triodes bias data:

 $\begin{array}{lll} I_{a1}\coloneqq 10\cdot 10^{-3} A & I_{a2}\coloneqq I_{a1} & V_{a1}\coloneqq 90V & V_{a2}\coloneqq 90V \\ V_{cc}\coloneqq 350V & V_{g1}\coloneqq -1.65V & V_{g2}\coloneqq -1.65V \\ V_{R,c1}\coloneqq \left|V_{g1}\right| & V_{Gen1}\coloneqq V_{cc}-\left(V_{a1}+V_{R,c1}\right) & V_{Gen1}= 258.35V \\ V_{R,c2,b}\coloneqq V_{Gen1}-V_{a2} & V_{R,c2,b}= 168.35V & R_{c2,b}\coloneqq \frac{V_{R,c2,b}}{I_{a2}} & R_{c2,b}= 1.684\times 10^{4}\Omega \\ V_{g1,grnd}\coloneqq V_{Gen1} & V_{g1,grnd}= 258.35V & V_{C,g2}\coloneqq V_{R,c2,b}+V_{g2} & V_{C,g2}= 166.7V \\ R_{g2,1}\coloneqq 1\cdot 10^{6}\Omega & R_{g2,2}\coloneqq R_{g2,1}\cdot \frac{\left(V_{cc}-V_{C,g2}\right)}{V_{C,g2}} & R_{g2,2}= 1.1\times 10^{6}\Omega \end{array}$

10.6

10.6.2. Triodes valve constants:

10.6.3 Circuit variables:

- $$\begin{split} & C_{stray,1} \coloneqq 10 \cdot 10^{-12} F & C_{stray,2} \coloneqq 10 \cdot 10^{-12} F \\ & R_{c1} \coloneqq \frac{V_{R,c1}}{I_{a1}} & R_{c1} = 165 \, \Omega & R_{gg1} \coloneqq 2.21 \cdot 10^{3} \Omega \\ & RS \coloneqq 1 \cdot 10^{3} \Omega & R_{g1} \coloneqq 1 \cdot 10^{6} \Omega & R_{L} \coloneqq 100 \cdot 10^{3} \Omega \\ & R1 \coloneqq 100 \cdot 10^{3} \Omega \end{split}$$
- $C_{in} := 0.1 \cdot 10^{-6} F$ $C_{out} := 100 \cdot 10^{-6} F$ $f_{c.opt} := 0.2 Hz$

$$C_{g2} := \frac{1}{2 \cdot \pi \cdot f_{c.opt} \left(\frac{1}{R_{g2.1}} + \frac{1}{R_{g2.2}} \right)^{-1}}$$
 $C_{g2} = 1.519 \times 10^{-6} F$

10.6.4 Calculation relevant data:

frequency range f for the below shown graphs: f := 10Hz, 20Hz...100000 Hzh := 1000Hz

10.6.5 Gain G_{ccf.hi} (frequency independent):

$$\begin{split} R_{v2,hi} &\coloneqq r_{a,v2} + \left(1 + \mu_{v2}\right) \cdot R_{c2,b} \\ G_{ccf,hi,188,1} &\coloneqq g_{m,v1} \cdot \frac{\left(\frac{1}{r_{a,v1}} + \frac{1}{R_{c1} + R_{v2,hi}}\right)^{-1}}{1 + g_{m,v1} \cdot \left(\frac{1}{r_{a,v1}} + \frac{1}{R_{c1} + R_{v2,hi}}\right)^{-1}} \end{split}$$

 $R_{v2.hi} = 5.587 \times 10^5 \Omega$

$$G_{\text{ccf bi } 188 \ 1} = 0.97$$

 $G_{ccf.hi.188.2} := \mu_{v1} \cdot \frac{R_{c1} + R_{v2.hi}}{r_{a.v1} + (1 + \mu_{v1}) \cdot (R_{c1} + R_{v2.hi})}$ $G_{ccf.hi.188.2} = 0.97$ $G_{ccf.hi.188.1.e} := 20 \cdot log(G_{ccf.hi.188.1})$ $G_{ccf,hi,188,1,e} = -0.267$ [dB] $G_{ccf.hi.188.rot} := \frac{\mu_{v1}}{1 + \mu_{v1}}$ $G_{ccf, hi, 188 rot} = 0.97$ $G_{ccf.hi.188.rot.e} \approx 20 \cdot \log(G_{ccf.hi.188.rot})$ $G_{ccf,hi,188,rot,e} = -0.267$ [dB] $G_{ccf.hi.188.1.e} - G_{ccf.hi.188.rot.e} = 5.101 \times 10^{-4} [dB]$ 10.6.6 Gain G_{ccf.hi}(f) (frequency dependent): $X_{v2.hi}(f) \coloneqq 2j \cdot \pi \cdot f \cdot \left(C_{g,a2.188} + C_{stray.2}\right)$ $Y_{v2.hi}(f) := \left[\left(\frac{1}{r_{a,v2}} + 2j \cdot \pi \cdot f \cdot C_{a,c2.188} \right)^{-1} + \left(1 + \mu_{v2} \right) \cdot \left(\frac{1}{R_{c2.b}} + 2j \cdot \pi \cdot f \cdot C_{g,c2.188} \right)^{-1} \right]^{-1} \right]^{-1}$ $|Z_{v2,hi}(h)| = 5.582 \times 10^5 \Omega$ $Z_{v2.hi}(f) := \left[\left(Y_{v2.hi}(f) \right) + X_{v2.hi}(f) \right]^{-1}$ 1.10^{6} Zv2.hi(f) 1.105 $1 \cdot 10^3$ 1.10^{4} 1.10^{5} 100 10 [Hz] Figure 10.17 Impedance of the high-Z constant current sink $R_{c1} + Z_{v2.hi}(f)$ (h) = 0.97

$$G_{ccf.hi.188}^{(r)} = \mu_{V} \Gamma_{r_{a.V1}} + (1 + \mu_{V1}) \cdot (R_{c1} + Z_{V2,hi}(f)) \qquad [G_{ccf.hi.188}^{(r)}] = 0.97$$

$$G_{ccf.hi.188}^{(r)} = 20 \cdot \log(|G_{ccf.hi.188}(f)|) \qquad G_{ccf.hi.188}^{(r)} = -0.269 \quad [dB]$$

$$Im(G_{ccf.hi.188}^{(r)} = 0.97$$

$$\phi_{ccf.hi.188}(f) := \frac{Im(G_{ccf.hi.188}(f))}{Re(G_{ccf.hi.188}(f))}$$







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Figure 10.21 Transfer of hi i/p network

$$T_{tot,hi}(f) := T_{i,hi}(f) \cdot T_{o,hi}(f) \cdot G_{ccf,hi,188,1}$$

 $T_{\text{tot. hi. e}}(f) := 20 \cdot \log(|T_{\text{tot. hi}}(f)|)$

$$\phi_{\text{tot.hi}}(f) := \phi_{i.hi}(f) + \phi_{o.hi}(f) + \phi_{G.ccf.hi}(f)$$





$$T_{\text{tot, hi, e}}(h) := 20 \cdot \log(|T_{\text{tot, hi}}(h)|)$$

 $T_{tot,hi,e}(h) = -0.362 [dB]$



Figure 10.24 Phase response of the CCF-hi gain stage



Figure 10.22 Phase of hi o/p network

 $\phi_{G.ccf.hi}(f) := 0$

11.1 Circuit diagram



Figure 11.1 Basic design of the White Cathode Follower gain stage (WCF)

11.2 Remarks and basic assumptions

The WCF's main aim is to achieve a very much lower output resistance than that of the CF or CCF - by keeping its gain (alike the CCF) close to 1.

The WCF is a CCF à la Chapter 10 (V1) with a positive feedback path from V1's plate via V2 back into the cathode of V1, thus, creating a rather small output resistance at the cathode of V1 - very much smaller than the output resistance of an ordinary CCF without that feedback loop.

The V2 – V1 sequence looks like a CAS gain stage à la Chapter 6. Hence, the whole design can also be described as a CCF with an additional CAS gain stage as feedback loop. V2's grid plays the input of the CAS. Cutting-off the feedback loop (eg. $R_{a1} = 0R$ or no C_{g2}) will automatically lead to a CCF.

Because, in principle, the gain of the whole stage never exceeds the 0dB line the positive feedback should not be able to force the stage into oscillation.

Equal DC operation of V1 and V2 should ensure rather symmetrical signal output voltage into any load R_L . To avoid clipping maximal signal output voltage and current should be based on the current delivery possibilities of the output of the gain stage! In addition, at the grid of V2 any signal peak voltage that is bigger than the grid's DC voltage for proper operation of the valve will bring V2 into a cut-off state.

To enable easy calculations the following assumptions have to be taken into account:

•	V1 equals V2 (ideal case:	double triode)		
•	plate current V1	= plate current V2	(I _{a1}	$= I_{a2})$
•	plate-cathode voltage V1	= plate cathode voltage V2	$(V_{a1}$	$= V_{a2})$
•	g _m	$= g_{m.v1}$		$= g_{m.v2}$
•	r _a	$= r_{a.vl}$		$= r_{a.v2}$
•	μ	$= \mu_{v1}$		$=\mu_{v2}$
•	bypassed version (b):	R_{c2} = bypassed by C_{c2}		
•	un-bypassed version (u):	$R_{c2} = un-bypassed$		

11.3 Basic formulae for both versions (excl. and incl. stage load (R_L)-effect)

$$R_{a1.eff} = R_{a1} \| R_{g2}$$
(11.1)

11.3.1 Gain G_{wcf.b.nL} excl. output load (nL) (bypassed version):

$$G_{wcf.b.nL} = \frac{\mu(r_a + \mu R_{a1.eff})}{r_a(\mu + 2) + R_{a1.eff}(\mu^2 + \mu + 1)}$$
(11.2)

11.3.2 Gain G_{wcf.b.L} incl. output load (L) (bypassed version):

$$G_{\text{wcf.b.L}} = \frac{\mu(r_a + \mu R_{a1.eff})}{\frac{r_a(r_a + \mu R_{a1.eff})}{R_L} + r_a(\mu + 2) + R_{a1.eff}(\mu^2 + \mu + 1)}$$
(11.3)

11.3.3 Output resistance R_{0.b} (bypassed version):

$$R_{o.b} = \frac{r_a \left(r_a + R_{a1.eff} \right)}{r_a \left(\mu + 2 \right) + R_{a1.eff} \left(\mu^2 + \mu + 1 \right)}$$
(11.4)

Rule of thumb¹:

$$R_{o.b.rot} \approx \frac{r_{c1}}{|G_{cas.b.rot}|} \\ \approx \left(\frac{r_a}{\mu R_{a1}}\right) \left(\frac{r_a + R_{a1}}{\mu + 1}\right)$$
(11.5)

11.3.4 Gain G_{wcf.u.nL} excl. output load (nL) (un-bypassed version):

$$G_{wcf.u.nL} = \frac{\mu r_a + \mu^2 R_{a1.eff} + (\mu^2 + \mu) R_{c2}}{(\mu + 2) r_a + (\mu^2 + \mu + 1) R_{a1.eff} + (\mu^2 + 2\mu + 1) R_{c2}}$$
(11.6)

11.3.5 Gain G_{wcf.u.L} incl. output load (L) (un-bypassed version):

$$G_{\text{wcf.u.L}} = \frac{\mu r_{a} + \mu^{2} R_{a1.\text{eff}} + (\mu^{2} + \mu) R_{c2}}{\left(\frac{A}{R_{L}} + B\right)}$$
(11.7)

¹ to get $G_{cas.b.rot}$ see Chapter 6

$$A = r_{a} \left[r_{a} + R_{a1.eff} + (\mu + 1) R_{c2} \right] + (\mu + 1) R_{c2} R_{a1.eff}$$

$$B = (\mu + 2) r_{a} + (\mu^{2} + \mu + 1) R_{a1.eff} + (\mu^{2} + 2\mu + 1) R_{c2}$$
(11.8)

11.3.6 Output resistance R_{0.u} (un-bypassed version):

$$R_{o.u} = \frac{(r_a + R_{a1.eff})[r_a + R_{c2}(\mu + 1)]}{(\mu + 2)r_a + (\mu^2 + \mu + 1)R_{a1.eff} + (\mu^2 + 2\mu + 1)R_{c2}}$$
(11.9)

Rule of thumb: n.a.

11.3.7 Specific resistances and capacitances²:

11.3.7.1 Both versions - input resistance R_i & impedance $Z_i(f)$, input & output capacitance C_{in} & C_{out} , grid 2 capacitance C_{g2} :

$$\mathbf{R}_{i} = \mathbf{R}\mathbf{1} \| \mathbf{R}_{g1.1} \| \mathbf{R}_{g1.2} \tag{11.10}$$

$$Z_i(f) = R_i || C_i$$
 (11.11)

$$C_{in} = \frac{1}{2\pi f_{c.opt} \left(R_{g1} \| R_{g2} \right)}$$
(11.12)

$$C_{\text{out}} = \frac{1}{2\pi f_{\text{c.opt}} R_{\text{L}}}$$
(11.13)

$$C_{g2} = \frac{1}{2\pi f_{c.opt} R_{g2}}$$
(11.14)

$$f_{c.opt} = 0.2 Hz$$
 (11.15)

11.3.7.2 version (b) only - cathode capacitance
$$C_{c2}$$
:

$$C_{c2} = \frac{1}{2\pi f_{c.opt} \left(r_{c2} \parallel R_{c2} \right)}$$
(11.16)

$$r_{c2} = \frac{R_{a1.eff} + 2r_a}{\mu + 1}$$
(11.17)

² For C_i see previous Chapters

11.4 Derivations



Figure 11.2 Equivalent circuit of Figure 11.1

11.4.1 Bypassed version:

11.4.1.1 Gains $G_{wcf.b}$ (output loaded with R_L or non-loaded):

$$G_{wcf.b} = \frac{v_o}{v_i}$$
(11.18)

sum of currents at the top node:

$$i_0 = i_1 + i_2 + i_3 - i_5 - i_6$$

set $i_0 = 0$ (11.19)
 $\Rightarrow i_1 = \frac{v_0}{R_1} = i_5 + i_6 - i_2 - i_3$

hence,

$$\frac{v_{o}}{R_{L}} = g_{m}v_{g1.c1} + \frac{v_{a1.c1}}{r_{a}} - g_{m}v_{g2.c2} - \frac{v_{a2.c2}}{r_{a}}$$

$$= \begin{pmatrix} g_{m}(v_{i} - v_{o}) - \frac{2v_{o} + v_{R.a1.eff}}{r_{a}} \\ + g_{m}R_{a1.eff} \left(g_{m}(v_{i} - v)_{o} - \frac{v_{o} + v_{R.a1.eff}}{r_{a}} \right) \end{pmatrix}$$
(11.20)

with:

$$v_{a2.c2} = v_{o}$$

 $v_{g2.c2} = -v_{R.a1.eff}$
 $v_{g1.c1} = v_{i} - v_{o}$
 $v_{a1.c1} = -v_{o} - v_{R.a1.eff}$
(11.21)

and:

$$v_{R.a1.eff} = i_7 R_{a1.eff}$$

$$= (i_5 + i_6) R_{a1.eff}$$

$$= R_{a1.eff} \left(g_m v_{g1.c1} + \frac{v_{a1.c1}}{r_a} \right)$$
(11.22)

we'll get:

$$v_{R.a1.eff} = R_{a1.eff} \frac{\mu v_i - (\mu + 1) v_o}{r_a + R_{a1.eff}}$$
 (11.23)

and - after a lot of rearrangements - we'll get the gain $G_{wef.b.L}$ that includes the output load $R_L\!\!:$

$$G_{\text{wcf.b.L}} = \frac{\mu(r_a + \mu R_{a1.eff})}{\frac{r_a(r_a + R_{a1.eff})}{R_L} + r_a(\mu + 2) + R_{a1.eff}(\mu^2 + \mu + 1)}$$
(11.24)

and - with $R_L \to {}_{\infty}$ the gain $G_{wcf.b.nL}$ for the non-loaded output becomes:

$$G_{\text{wcf.b.nL}} = \frac{\mu(r_a + \mu R_{a1.eff})}{r_a(\mu + 2) + R_{a1.eff}(\mu^2 + \mu + 1)}$$
(11.25)

11.4.1.2 Output resistance R_{o.b}:

At the gain $G_{wcf.b.L}$ = 0.5* $G_{wcf.b.nL}$ the output resistance $R_{o.b}$ equals the load resistance $R_L.$ Hence,

$$0.5G_{wcf.b.nL} = G_{wcf.b.L} = \frac{\mu(r_a + \mu R_{a1.eff})}{\frac{r_a(r_a + R_{a1.eff}) + r_a(\mu + 2) + R_{a1.eff}(\mu^2 + \mu + 1)}{\frac{R_{o.b}}{\frac{\mu(r_a + \mu R_{a1.eff})}{r_a(\mu + 2) + R_{a1.eff}(\mu^2 + \mu + 1)}}$$
(11.26)

rearrangement leads to R_{o.b}:

$$R_{o,b} = \frac{r_a \left(r_a + R_{a1.eff} \right)}{r_a \left(\mu + 2 \right) + R_{a1.eff} \left(\mu^2 + \mu + 1 \right)}$$
(11.27)

11.4.2 Un-bypassed version:

11.4.1.1 Gains G_{wcf.u} (output loaded with R_L or non-loaded):

$$G_{wcf.u} = \frac{v_o}{v_i}$$
(11.28)

sum of currents at the top node:

$$i_0 = i_1 + i_2 + i_3 - i_5 - i_6$$

set $i_0 = 0$ (11.29)
 $\Rightarrow i_1 = \frac{v_0}{R_L} = i_5 + i_6 - i_2 - i_3$

hence,

$$\frac{v_o}{R_L} = g_m v_{g1.c1} + \frac{v_{a1.c1}}{r_a} - g_m v_{g2.c2} - \frac{v_{a2.c2}}{r_a}$$
(11.30)

with:

$$v_{a2,c2} = v_{o} - v_{R,c2}$$

$$v_{g2,c2} = -v_{R,a1.eff} - v_{R,c2}$$

$$v_{g1,c1} = v_{i} - v_{o}$$

$$v_{a1,c1} = -v_{o} - v_{R,a1.eff}$$
(11.31)

and:

$$v_{R.c2} = R_{c2} (i_2 + i_3)$$

$$v_{R.c2} = R_{c2} \frac{v_0 - v_{R.a1.eff} \mu}{(r_a + R_{c2} + \mu R_{c2})}$$
(11.32)

$$v_{R.a1.eff} = i_7 R_{a1.eff}$$

= (i_5 + i_6) R_{a1.eff} (11.33)
= R_{a1.eff} \left(g_m v_{g1.c1} + \frac{v_{a1.c1}}{r_a} \right)

we'll get:

$$v_{R.a1.eff} = R_{a1.eff} \frac{\mu v_i - (\mu + 1) v_o}{r_a + R_{a1.eff}}$$
 (11.34)

and - after a lot of rearrangements - we'll get the gain $G_{wcf.u.L}$ that includes the output load $R_L\!\!:$

$$G_{wcf.u.L} = \frac{\mu r_{a} + \mu^{2} R_{a1.eff} + (\mu^{2} + \mu) R_{c2}}{\left(\frac{A}{R_{L}} + B\right)}$$
(11.35)

$$A = r_{a} \left[r_{a} + R_{a1.eff} + (\mu + 1) R_{c2} \right] + (\mu + 1) R_{c2} R_{a1.eff}$$

$$B = (\mu + 2) r_{a} + (\mu^{2} + \mu + 1) R_{a1.eff} + (\mu^{2} + 2\mu + 1) R_{c2}$$
(11.36)

and - with $R_L \to {}_{\infty}$ the gain $G_{wcf.b.nL}$ for the non-loaded output becomes:

$$G_{wcf.u.nL} = \frac{\mu r_a + \mu^2 R_{a1.eff} + (\mu^2 + \mu) R_{c2}}{(\mu + 2) r_a + (\mu^2 + \mu + 1) R_{a1.eff} + (\mu^2 + 2\mu + 1) R_{c2}}$$
(11.37)

11.4.1.2 Output resistance R_{o.u}:

At the gain $G_{wcf.u.L}$ = 0.5* $G_{wcf.u.nL}$ the output resistance $R_{o.u}$ equals the load resistance $R_L.$ Hence,

$$0.5G_{wcf.u.nL} = G_{wcf.u.L}$$
(11.38)

rearrangement leads to Rout

$$R_{o.u} = \frac{r_a \left(r_a + R_{a1.eff} \right) \left[r_a + (\mu + 1) R_{c2} \right]}{(\mu + 2) r_a + (\mu^2 + \mu + 1) R_{a1.eff} + (\mu^2 + 2\mu + 1) R_{c2}}$$
(11.39)

11.5 Gain stage frequency and phase response calculations

I abstain from going through the calculation course to get the frequency and phase response. All these calculations can be derived from the respective paragraphs of the previous chapters.

As long as C_{c2} , C_{g2} , C_{in} and C_{out} are chosen of such values that do not hurt the flat frequency and phase response in B_{20k} , than, only the gain stage input frequency and phase response calculations with V1 related input capacitances are of further interest. Because of the rather low output resistance valve related output capacitances - other than the DC voltage blocking C_{out} - won't play a response flatness hurting role.

As could be demonstrated in the CAS gain stage chapter (6) the input capacitance (Miller-C!) of V2 in conjunction with the output resistance of V1 won't hurt the flat frequency and phase response in B_{20k} as well.

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$$\begin{array}{cccc} u_1 & u_2 & u_1 & u_1 & u_2 & u_1 & u_2 & u_$$

$$\begin{split} & R_{c2} \coloneqq \frac{V_{R.c2}}{I_{a2}} & R_{c2} = 165 \times 10^{0} \Omega \\ & R_{a1.eff} \coloneqq \left(\frac{1}{R_{a1}} + \frac{1}{R_{g2}}\right)^{-1} & R_{a1.eff} = 11.858 \times 10^{3} \Omega \\ & V_{cc} \coloneqq V_{a1} + V_{a2} + I_{a1} \cdot (R_{a1} + R_{c2}) & V_{cc} = 301.65 \times 10^{0} V \\ & V_{R.a1} \coloneqq I_{a1} \cdot R_{a1} & V_{R.a1} = 120 \times 10^{0} V \\ & V_{g1.grnd} \coloneqq V_{cc} - V_{a1} - V_{R.a1} - |V_{g1}| & V_{g1.grnd} = 90 \times 10^{0} V \\ & R_{g1.2} \coloneqq R_{g1.1} \cdot \frac{(V_{cc} - V_{g1.grnd})}{V_{g1.grnd}} & R_{g1.2} = 2.352 \times 10^{6} \Omega \end{split}$$

11.6.2. Triodes valve constants:

$g_{\rm m} := 10.4 \cdot 10^{-3} {\rm S}$	$r_a := 3.1 \cdot 10^3 \Omega$	$\mu \coloneqq g_{m} \cdot r_{a}$	$g_{\rm m} \cdot r_{\rm a} = 32.24 \times 10^{\circ}$
$g_{m1} \coloneqq g_m$	$\mathbf{r}_{a1} \coloneqq \mathbf{r}_{a}$	$\mu_1 \coloneqq \mu$	
$g_{m2} \coloneqq g_m$	$r_{a2} \coloneqq r_a$	$\mu_2 := \mu$	

11.6.3 Gains G_{wcf.b.L} and G_{wcf.u.L}:

$$\begin{split} R_{L} &:= 10 \cdot 10^{3} \Omega \\ G_{wcf.b.L} &:= \frac{\mu \left(r_{a} + \mu R_{a1.eff} \right)}{\frac{r_{a}^{2} + r_{a} \cdot R_{a1.eff}}{R_{L}} + r_{a} \cdot (\mu + 2) + R_{a1.eff} (\mu^{2} + \mu + 1)} \\ G_{wcf.b.L} &= 968.434 \times 10^{-3} \\ A &:= r_{a} \left[r_{a} + R_{a1.eff} + (\mu + 1) \cdot R_{c2} \right] + (\mu + 1) \cdot R_{c2} \cdot R_{a1.eff} \\ B &:= (\mu + 2) \cdot r_{a} + (\mu^{2} + 2\mu + 1) \cdot R_{c2} + (\mu^{2} + \mu + 1) \cdot R_{a1.eff} \\ G_{wcf.u.L} &:= \frac{\mu (r_{a} + \mu R_{a1.eff}) + (\mu^{2} + \mu) \cdot R_{c2}}{\frac{A}{R_{L}} + B} \\ G_{wcf.u.L} &:= \frac{\mu (r_{a} + \mu R_{a1.eff}) + (\mu^{2} + \mu) \cdot R_{c2}}{\frac{A}{R_{L}} + B} \\ G_{wcf.b.I}(R_{L}) &:= \frac{\mu (r_{a} + \mu R_{a1.eff})}{\frac{r_{a}^{2} + r_{a} \cdot R_{a1.eff}}{R_{L}} + r_{a} \cdot (\mu + 2) + R_{a1.eff} (\mu^{2} + \mu + 1)} \\ \end{split}$$

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Figure 11.5 Gains $G_{wcf.b.L}$ and $G_{wcf.u.L}$ vs. R_L with fixed $R_{al.eff}$

 $R_{L} := 1 \cdot 10^{3} \Omega$

```
R_{a1.eff} \coloneqq 10\Omega, 20\Omega ... 10000 \Omega
```

$$G_{wcf.b.L}(R_{a1.eff}) := \frac{\mu(r_a + \mu \cdot R_{a1.eff})}{\frac{r_a^2 + r_a \cdot R_{a1.eff}}{R_L} + r_a \cdot (\mu + 2) + R_{a1.eff}(\mu^2 + \mu + 1)}$$

$$\begin{split} & A(R_{a1.eff}) \coloneqq r_a \cdot \left[r_a + R_{a1.eff} + (\mu + 1) \cdot R_{c2} \right] + (\mu + 1) \cdot R_{c2} \cdot R_{a1.eff} \\ & B(R_{a1.eff}) \coloneqq (\mu + 2) \cdot r_a + (\mu^2 + 2\mu + 1) \cdot R_{c2} + (\mu^2 + \mu + 1) \cdot R_{a1.eff} \end{split}$$

$$G_{\text{wcf.u.I}} \left(R_{a\,1.e\,\text{ff}} \right) \coloneqq \frac{\mu \cdot \left(r_a + \mu \cdot R_{a\,1.e\,\text{ff}} \right) + \left(\mu^2 + \mu \right) \cdot R_{c\,2}}{\frac{A \left(R_{a\,1.e\,\text{ff}} \right)}{R_I} + B \left(R_{a\,1.e\,\text{ff}} \right)}$$



Figure 11.6 Gains $G_{wcf.b.L}$ and $G_{wcf.u.L}$ vs. $R_{al.eff}$ with fixed R_L

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WCF calculations

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$$R_{o,b,rot} := \frac{r_{a}}{\mu R_{a1}} \cdot \frac{R_{a1} + r_{a}}{1 + \mu} \qquad R_{o,b,rot} = 3.64 \times 10^{0} \Omega$$

$$R_{a1} := 100\Omega, 110\Omega .. 10000\Omega$$

$$R_{o,b}(R_{a1}) := r_{a} \cdot \frac{r_{a} + \left(\frac{1}{R_{a1}} + \frac{1}{R_{g2}}\right)^{-1}}{(\mu + 2) \cdot r_{a} + (\mu^{2} + \mu + 1) \cdot \left(\frac{1}{R_{a1}} + \frac{1}{R_{g2}}\right)^{-1}}$$

$$R_{o,b,rot}(R_{a1}) := \frac{r_{a}}{\mu R_{a1}} \cdot \frac{R_{a1} + r_{a}}{1 + \mu}$$

$$\frac{\overline{E}}{2} \cdot \frac{R_{o,b}(R_{a1})}{1 + \mu} \int_{0}^{10} \int_{0}$$

Figure 11.8 Comparison between exact and rule-o-thumb $R_{\rm o,b}$ calculation

Conclusion: for an error <10% calculation of $R_{\rm o.b.rot}\;$ makes sense for R $_{\rm al}$ > 1k only

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$$R_{o.u} \coloneqq \frac{\left(r_{a} + R_{a1.eff}\right) \cdot \left[r_{a} + (\mu + 1) \cdot R_{c2}\right]}{(\mu + 2) \cdot r_{a} + \left(\mu^{2} + 2\mu + 1\right) \cdot R_{c2} + \left(\mu^{2} + \mu + 1\right) \cdot R_{a1.eff}} \qquad \qquad R_{o.u} = 9.872 \times 10^{0} \Omega$$

 $R_{a1.eff} := 10\Omega, 20\Omega...10000\Omega$

$$R_{o,b}(R_{a1.eff}) \coloneqq \frac{r_a \cdot (r_a + R_{a1.eff})}{(\mu + 2) \cdot r_a + (\mu^2 + \mu + 1) \cdot R_{a1.eff}}$$

$$R_{o,u}(R_{a1.eff}) \coloneqq \frac{\left(r_a + R_{a1.eff}\right) \left[r_a + (\mu + 1) \cdot R_{c2}\right]}{(\mu + 2) \cdot r_a + \left(\mu^2 + 2\mu + 1\right) \cdot R_{c2} + \left(\mu^2 + \mu + 1\right) \cdot R_{a1.eff}}$$

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$$r_{c2} \coloneqq \frac{R_{a1.eff} + 2 \cdot r_{a}}{\mu + 1} \qquad r_{c2} = 543.252 \times 10^{0} \text{ G}$$

$$C_{c2} \coloneqq \frac{1}{2 \cdot \pi \cdot f_{c.opt} \cdot \left(\frac{1}{r_{c2}} + \frac{1}{R_{c2}}\right)^{-1}} \qquad C_{c2} = 6.288 \times 10^{-3} \text{ F}$$

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11.6.7 Voltage $v_{R,al,eff}$ at the grid of V2 as function of R_L for a specific rms input voltage vi: $R_{a1 eff} = 10 \cdot 10^3 \Omega$ $R_L := 10\Omega$, 20Ω .. 10000Ω $v_{i,b,p} = 1.414 \times 10^{0} V$ $v_i := 1V$ $v_{i,b,p} := v_i \sqrt{2}$ $v_{i,u,p} := v_{i,b,p}$ $v_{o.b.p}(R_L) := v_{i.b.p} \cdot G_{wcf.b.L}(R_L)$ $v_{R.a1.eff} = R_{a1.eff} \frac{\mu \cdot v_i - v_0 \cdot (1 + \mu)}{r_a + R_{a1.eff}}$ $v_{o.u.p}(R_L) := v_{i.u.p} \cdot G_{wcf.u.L}(R_L)$ $\mathbf{v}_{b.R.a1.eff.p}(\mathbf{R}_{L}) \coloneqq \mathbf{R}_{a1.eff} \frac{\mu \cdot \mathbf{v}_{i.b.p} - \mathbf{v}_{o.b.p}(\mathbf{R}_{L}) \cdot (1+\mu)}{\mathbf{r}_{a} + \mathbf{R}_{a1.eff}}$ $v_{u.R.a1.eff.p}(R_L) := R_{a1.eff} \frac{\mu \cdot v_{i.u.p} - v_{o.u.p}(R_L) \cdot (1+\mu)}{r_a + R_{a1.eff}}$ 3.5 $\sum_{\substack{n=1\\m \in I}} \frac{v_{b.R.a1.eff.p}(R_L)}{v_{u.R.a1.eff.p}(R_L)} \frac{2.5}{1.5}$ 0.5 0 1.10^{3} 1.10^{4} 10 100 RL [ohm] Figure 11.10 V2 grid peak AC voltage vs. R_L Conclusions for 90% |V₉₂|: (b) version: $R_{L,b}$ should be >190R (u) version: $R_{L,u}$ should be >430R 11.6.8 output current check (should be < app. 90% of I_{a1}): $R_{L,b} := 190\Omega$ $R_{L,u} := 430 \Omega$ $i_{out.b.p} \coloneqq \frac{v_{o.b.p}(R_{L.b})}{R_{L.b}}$ $i_{out, b, p} = 6.915 \times 10^{-3} A$ $i_{out.u.p} \coloneqq \frac{v_{o.u.p}(R_{L.u})}{R_{L.u}}$ $i_{out.\,u.p} = 3.052 \times 10^{-3} A$

12.1 Circuit diagram



Figure 12.1 Two triodes in parallel operation

12.2 Equivalent circuit plus resulting component and valve figures

It is obvious that the DC current conditions of two equally configured triodes (top 2/3 of Figure 12.1) must get doubled when putting them in parallel operation à la bottom 1/3 of Figure 12.1. Assumed that the power supply voltages do not change plate and cathode resistors must be halved. While there is practically no grid current the grid resistor R_{2g} doesn't need to get halved. It can be set to a value that is right for the output of the preceding stage.



Figure 12.2 Equivalent circuit of the parallel operation of two triodes

With Figure 12.2 and the comprehension of the derivation course of Chapter 1 the following formulae can be developed.

According to Figure 12.2 all important figures for the calculation of the parallel operation ("2") can be defined as:

•	r _{a.2t}	$= r_{a.t}/2$
•	R _{2a}	$= R_a/2$
•	R _{2c}	$= R_c/2$
•	$g_{m.2t} * v_{g.c}$	$= 2 * g_{m.t} * v_{g.c}$
•	g _{m.2t}	$= 2*g_{m.t}$
•	μ_{2t}	$= \mu_t$

12.3 Basic formulae (excl. stage load (R_L)-effect)

12.3.1 Gain G_{2t} of the new triode in parallel operation

becomes in terms of gm.t:

$$G_{2t} = -g_{m.2t} \frac{r_{a.2t} R_{2a}}{r_{a.2t} + R_{2a} + R_{2c} (1 + g_{m.2t} r_{a.2t})}$$
(12.1)

becomes in terms of μ_t :

$$G_{2t} = -\mu_t \frac{R_{2a}}{r_{a.2t} + R_{2a} + R_{2c} (1 + \mu_t)}$$
(12.2)

thus, compared with the single triode operation the gain of the parallel operation does not change

12.3.2 Grid input impedance Z_{i.2g.eff}:

$$Z_{i.2g.eff} = R_g \parallel C_{2i.tot}$$
(12.3)

12.3.3 Plate output impedance Z_{0.2a.eff}:

$$Z_{o.2a.eff} = R_{2a} \| \left[r_{a.2t} + (1 + \mu_t) R_{2c} \right] \| (C_{2o})$$
(12.4)

this is 1/2 of the respective figure of the single triode gain stage

12.3.4 Cathode output resistance R_{0.2c}:

$$R_{o.2c} = R_{2c} \parallel \frac{R_{2a} + r_{a.2t}}{1 + \mu_t}$$
(12.5)

this is 1/2 of the respective figure of the single triode gain stage

- 12.3.5 Total input capacitance C_{2i.tot} and output capacitance C_{2o.tot}:
 - with plate-cathode capacitance C_{a.c.1t}
 - with grid-cathode capacitance C_{g.c.1t} for one triode
 - with grid-plate capacitance Cg.a.lt for one triode
 - with grid input Miller capacitance effect $[(1+|G_{1t}|)*C_{g.a.1t}]$ for one triode
 - with plate output Miller capacitance effect [C_{a.c.lt} ||C_{g.a.lt}] for one triode
 - with a guessed stray capacitance C_{stray.1t} for 1 triode

the total input capacitance for two paralleled triodes becomes two times the total input capacitance for one triode:

$$C_{2i.tot} = 2\left[\left(1 + |G_{2t}|\right)C_{g.a.1t} + C_{g.c.1t} + C_{stray.1t}\right]$$
(12.6)

the respective output capacitance C20 becomes

$$C_{20,tot} = 2C_0 = 2(C_{a,c,1t} + C_{g,a,1t})$$
 (12.7)

12.3.6 Bypassing the cathode resistor with a capacitor means that in the above given equations the term R_{2c} has to be set to zero. The capacitor should be of a size¹ that does not hurt a flat frequency and phase response in B_{20k} .

12.4 n triodes in parallel operation

12.4.1 According to Figure 12.2 all important figures for the calculation of the parallel operation $\binom{m}{n}$ can be defined as:

•	r _{a.nt}	$= r_{a.t}/n$
•	R _{na}	$= R_a/n$
•	R _{nc}	$= R_c/n$
•	$g_{m.nt}^*v_{g.c}$	$= n^* g_{m.t}^* v_{g.c}$
•	g _{m.nt}	$= n^* g_{m.t}$
•	μ_{nt}	$= \mu_t$

12.4.2 The gain G_{nt} of the new triode in parallel operation

becomes in terms of gm.t:

$$G_{nt} = -g_{m.nt} \frac{r_{a.nt} R_{na}}{r_{a.nt} + R_{na} + R_{nc} (1 + g_{m.nt} r_{a.nt})}$$
(12.8)

becomes in terms of µt:

$$G_{nt} = -\mu_t \frac{R_{na}}{r_{a.nt} + R_{na} + R_{nc} (1 + \mu_t)}$$
(12.9)

thus, compared with the single triode operation the gain of the parallel operation does not change

12.4.3 Grid input impedance Z_{i.ng.eff}:

$$Z_{i.ng.eff} = R_g \parallel C_{ni.tot}$$
(12.10)

¹ see Chapter 2

12.4.4 Plate output impedance Z_{o.na.eff}:

$$Z_{o.na.eff} = R_{na} \| [r_{a.nt} + (1 + \mu_t) R_{nc}] \| C_{no}$$
(12.11)

this is 1/n of the respective figure of the single triode gain stage

12.4.5 Cathode output resistance R_{o.nc}:

$$R_{o.nc} = R_{nc} \parallel \frac{R_{na} + r_{a.nt}}{1 + \mu_t}$$
(12.12)

this is 1/n of the respective figure of the single triode gain stage

12.4.6 Total input capacitance C_{ni.tot} and output capacitance C_{no.tot}:

$$C_{ni.tot} = n \left[\left(1 + |G_{nt}| \right) C_{g.a.1t} + C_{g.c.1t} + C_{stray.1t} \right]$$
(12.13)

$$C_{no.tot} = n C_o = n \left(C_{a.c.1t} + C_{g.a.1t} \right)$$
 (12.14)

12.4.7 Bypassing the cathode resistor with a capacitor means that in the above given equations the term R_{nc} has to be set to zero. The capacitor should be of a size² that does not hurt a flat frequency and phase response in B_{20k} .

² see Chapter 2
12.5 Advantages of the parallel operation of n triodes

•	in case of a CF configuration:	decreasing output impedance: multiplication with factor 1/n
•	in case of a typical gain stage:	deacreasing noise voltage: multiplication with factor $(1/\sqrt{n})$

12.6 Disadvantages of the parallel operation of n triodes

- growing current consumption (n times)
- total input capacitance C_{ni.tot} grows with factor n
- total output capacitance C_{no.tot} grows with factor n

12.7 Gain stage frequency and phase response calculations

• In consideration of the number of triodes in parallel operation all these calculations can be derived from the respective paragraphs of the previous chapters³.

³ see also Chapter 15 "Design Example"

Chapter 13 Balanced (Differential) Gain Stage (BAL)

13.1 Circuit diagram



Figure 13.1 Two triodes configured as a balanced (differential) gain stage for AC signal amplification purposes

13.2 Basic assumptions

To ensure correct work of a differential gain stage the following assumption have to be made:

$$R_{a} = R_{a1} = R_{a2}$$

$$R_{g} = R_{g1} = R_{g2}$$
(13.1)

$$V1 = V2 = \text{double triode}$$

$$\mu_{t} = \mu_{1} = \mu_{2}$$

$$g_{m.t} = g_{m.1} = g_{m.2}$$

$$r_{a.t} = r_{a.1} = r_{a.2}$$

(13.2)

$$I_{c} = I_{c1} + I_{c2} = I_{a1} + I_{a2}$$
(13.3)

DC current I_c keeps constant in any case of changing input voltages, that means that a change of v_{i1} creates a certain change of I_{a1} , thus, creating exactly the same amount of current change of I_{a2} with the opposite polarity. Therefore, in the equivalent circuit environment Gen1 works as short circuit between cathode and the ground level of the circuitry. Hence, as of Figure 13.2 V1 and V2 can be treated as two CCS gain stages with grounded cathodes, each amplifying half of the differential input voltage.

13.3 Amplification variants

With the generic gain stage of Figure 13.1 and the phase polarization of the in- and output voltages as indicated the respective gains G_{xyz} and the following amplification variants can be chosen:

13.3.1 Gain for balanced (b) input via i.1 and i.2 – balanced output via o.1 and o.2:

$$G_{b.b} = \frac{V_{0.b}}{V_{i,b}}$$
(13.4)

$$\mathbf{G}_{b,b} = -\mathbf{g}_{m,t} \left(\mathbf{r}_{a,t} \parallel \mathbf{R}_{a} \right) \tag{13.5}$$

13.3.2 Gain for balanced input via i.1 and i.2 – unbalanced (u) output via 0.1 or 0.2:

13.3.2.1 with 180° phase shift via output o.1 only:

$$G_{b,u,o1} = \frac{v_{o,1}}{v_{i,b}} = -\frac{1}{2}g_{m,t}(r_{a,t} || R_a)$$
(13.6)

13.3.2.2 without phase shift via output 0.2 only:

$$G_{b.u.o2} = \frac{v_{o.2}}{v_{i.b}} = \frac{1}{2} g_{m.t} \left(r_{a.t} \parallel R_a \right)$$
(13.7)

13.3.3 Gain for unbalanced input via input i.1 and input i.2 grounded – balanced output via o.1 and o.2:

$$G_{u,i1,b} = \frac{V_{o,b}}{V_{i,1}} = -2g_{m,t} \left(r_{a,t} \parallel R_a \right)$$
(13.8)

13.3.4 Gain for unbalanced input via input i.2 and input i.1 grounded – balanced output via o.1 and o.2:

$$G_{u,i2,b} = \frac{v_{o,b}}{v_{i,2}} = 2 g_{m,t} \left(r_{a,t} \parallel R_a \right)$$
(13.9)

13.3.5 Gain for unbalanced input via i.1 and input i.2 grounded – unbalanced output via o.1 only:

$$G_{u,i1.u,o1} = \frac{v_{o,1}}{v_{i,1}} = -g_{m,t} \left(r_{a,t} \parallel R_a \right)$$
(13.10)

13.3.6 Gain for unbalanced input via i.1 and input i.2 grounded – unbalanced output via o.2 only:

$$G_{u.i1.u.o2} = \frac{v_{o.2}}{v_{i.1}} = g_{m.t} \left(r_{a.t} \parallel R_a \right)$$
(13.11)

13.3.7 Gain for unbalanced input via i.2 and input i.1 grounded – unbalanced output via o.2 only:

$$G_{u.i2.u.o2} = \frac{v_{o.2}}{v_{i.2}} = -g_{m.t} \left(r_{a.t} \parallel R_a \right)$$
(13.12)

13.3.8 Gain for unbalanced input via i.2 and input i.1 grounded – unbalanced output via o.1 only:

$$G_{u,i2,u,o1} = \frac{v_{o,1}}{v_{i,2}} = g_{m,t} \left(r_{a,t} \parallel R_a \right)$$
(13.13)

13.4 Derivations



Figure 13.2 Simplified equivalent circuits for each part of the differential (balanced) input voltage $v_{i,b}$ of Figure 13.1

Differential gain $G_{b.b}$ for a differential input voltage $v_{i.b}$:

$$G_{b,b} = \frac{v_{o,b}}{v_{i,b}}$$
(13.14)

gain G_{v1} of V1 and gain G_{v2} of V2:

$$\mathbf{v}_{i,b} = \mathbf{v}_{i,1} - \mathbf{v}_{i,2} \tag{13.15}$$

$$\mathbf{v}_{i,2} = -\mathbf{v}_{i,1} \tag{13.16}$$

$$G_{v1} = -\frac{v_{o.1}}{v_{i.b}}$$
(13.17)
$$G_{v2} = \frac{v_{o.2}}{v_{i.b}}$$

$$G_{t} = G_{v1} = -G_{v2} = -\frac{1}{2}\mu_{t} \frac{R_{a}}{r_{a} + R_{a}}$$

$$G_{t} = -\frac{1}{2}g_{m,t} (r_{a,t} || R_{a})$$
(13.18)

thus, G_{b.b} becomes:

$$v_{o,1} = -G_t v_{i,b}$$

$$v_{o,2} = G_t v_{i,b}$$

$$v_{o,b} = v_{o,1} - v_{o,2}$$
(13.19)

$$\Rightarrow G_{b,b} = \frac{v_{o,b}}{v_{i,b}} = -2G_t = -g_{m,t} \left(r_{a,t} \parallel R_a \right)$$
(13.20)

All other gain expressions are included in the above given equations.

13.5 Impedances

13.5.1 Balanced input impedance Z_{i,b} between i.1 and i.2 (C_i includes Miller-C of each triode):

$$Z_{i,b} = (2R_g) || (0.5C_i)$$
(13.21)

$$C_i = C_{i,v1} = C_{i,v2} = (1 + G_t)C_{g,a} + C_{g,c} + C_{stray}$$
 (13.22)

13.5.2 Unbalanced input impedance Z_{i,u} between i.1 or i.2 and ground

$$\mathbf{Z}_{\mathbf{i},\mathbf{u}} = \mathbf{R}_{\mathbf{g}} \parallel \mathbf{C}_{\mathbf{i}} \tag{13.23}$$

13.5.3 Balanced output impedance Z_{o.b} between o.1 and o.2:

$$Z_{o.b} = \left[2 \left(r_a \| R_a \right) \right] \| \left(0.5 C_o \right)$$
(13.24)

$$C_0 = C_{a.c} \tag{13.25}$$

13.5.4 Unbalanced output impedance Z_{0.u} between 0.1 or 0.2 and ground:

$$Z_{o.u} = (r_a || R_a) || C_o$$
(13.26)

13.6 Common mode gain G_{com} for a common mode input voltage v_{i.com}

Common mode means that with reference to the ground level of the circuitry the input voltages at i1 and i2 are totally equal concerning phase, frequency and amplitude. The respective equivalent circuit looks as follows:



Figure 13.3 Equivalent circuit for the common mode input voltage situation of V1 and V2 respectively

$$v_{i,com} = v_{i,1,com} + v_{i,2,com}$$
 (13.27)

The common mode gain $G1_{com}$ becomes the gain of a CCS gain stage with a cathode resistance of 2 times the internal resistance of the current generator Gen1 of Figure 13.1 (see Figure 13.4):

$$Gl_{com} = \frac{v_{o.1.com}}{v_{i.com}} = -\frac{1}{2}\mu_t \frac{R_a}{r_{a.t} + R_a + (1 + \mu_t)2r_c}$$
(13.28)

$$G2_{com} = Gl_{com}$$

$$\Rightarrow G_{com} = Gl_{com} + G2_{com}$$
(13.29)

$$G_{com} = -\mu_t \frac{R_a}{r_{a.t} + R_a + (1 + \mu_t) 2r_c}$$
(13.30)

rule of thumb for G_{com}:

$$G_{\rm com} = -\frac{R_{\rm a}}{2r_{\rm c}} \tag{13.31}$$

The derivation of the cathode resistance $2*r_c$ via equivalent circuit modelling looks as follows:



Figure 13.4 Derivation of the term "2*rc"

13.7 CMRR - Common mode rejection ratio

13.7.1 Derivation:

$$CMRR = \frac{G_{b.b}}{G_{com}}$$
(13.32)

with equations (13.20) and (13.30) CMRR becomes:

$$CMRR = 1 + \frac{2r_{c}}{r_{a.t} + R_{a}} + \mu_{t} \frac{2r_{c}}{r_{a.t} + R_{a}}$$
(13.33)

$$CMRR_{e} = 20 \log (CMRR)$$
(13.34)

Rule of thumb:

since

$$\mu_{t} \frac{2r_{c}}{r_{a,t} + R_{a}} >> \frac{2r_{c}}{r_{a,t} + R_{a}} >> 1$$
(13.35)

and

$$\mathbf{r}_{a,t} \approx \mathbf{R}_a \tag{13.36}$$

CMRR approximately becomes (without big error):

$$CMRR_{rot} \approx \mu_t \frac{2r_c}{r_{a,t} + R_a}$$
(13.37)

$$\text{CMRR}_{\text{rot}} \approx \text{g}_{\text{m.t}} \text{ r}_{\text{c}}$$
 (13.38)

$$CMRR_{rot e} = 20 \log(CMRR_{rot})$$
 (13.39)

13.7.2 Sources of friction:

In theory - with an excellent current generator at the cathode - CMRR should become rather high margins. To achieve this the following facts are the real challenging ones:

- difference in the plate resistances R_{a1} and R_{a2}
- rather low value of the current generator's internal resistance r_c
- rather low value of g_{m.t}
- not perfectly matched valve gain μ_t
- differences in the valve capacitances



Low frequency (\leq 1kHz) gain differences of V1 vs. V2 can be balanced by the inclusion of P1 as shown in the following Figure 13.5 - or by its alternative around P2:

Figure 13.5 Improvements of Figure 13.1 to get equal gains of V1 and V2

A disadvantage of the Figure 13.5 P1 approach is the fact that the mutual conductance $g_{m,t}$ got reduced to a lower sized $g_{m,t,red}$, thus, changing $r_{a,t}$ as well, hence, with a constant μ_t the respective figures for V1 will become:

$$g_{m.1.red} = \frac{g_{m.1}}{1 + g_{m.1}R_{c1}}$$
(13.40)

$$r_{a.1.red} = \frac{\mu_t}{g_{m.1.red}}$$
 (13.41)

V2 has to be treated the same way! Depending on the size of R_{c1} and R_{c2} (should be as small as possible) the result will be a smaller gain of the stage. P2 doesn't produce these problems.

In any case, to sum up the CMRR story: because of the many unbalanced components / active device values in a balanced valve gain stage it's a rather heavy task to exactly calculate CMRR.

13.7.3 One additional question keeps open:

Despite the gain reduction by a reduced $g_{m,t}$: how to increase the gain of a differential gain stage?

Answer: Replacement of the plate resistors $R_{a,1}$ and $R_{a,2}$ by an active approach with valves that are configured as current generators, eg. like the top valves in the μ -Follower circuitry or as gain producing top devices like the ones in the cascoded gain stage will lead to higher gains and - in case of the μ -Follower only - to lower output impedances. The gain and impedance calculation courses are described in the respective chapters.

Taking into account the tiny gain reduction of the top section of a SRPP gain stage this would also work to produce lower output impedances - but with a bit less potential of overall gain increase.

It must be pointed out that, because of the inclusion of a cathode resistance, in any gain calculation V1 and V2 must be treated like CCS gain stages, thus $G_{b.b.red}$ becomes:

$$G_{b.b.red} = - \begin{pmatrix} \frac{1}{2} g_{m.1.red} & \frac{r_{a.1.red} R_a}{r_{a.1.red} + R_a + (1 + \mu_t) R_{c1}} \\ + \frac{1}{2} g_{m.2.red} & \frac{r_{a.2} R_a}{r_{a.2.red} + R_a + (1 + \mu_t) R_{c2}} \end{pmatrix}$$
(13.42)

13.7.4 Rule of thumb:

With

$$R_{c1} \approx R_{c2}$$

$$r_{a.1.red} = r_{a.2.red} = r_{a.t.red}$$
(13.43)

G_{b.b.red} becomes the following rule of thumb:

$$G_{b.b.red.rot} \approx -g_{m.t.red} \frac{r_{a.t.red}R_a}{r_{a.t.red} + R_a + (1 + \mu_t)0.5 \times P1}$$
(13.44)

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 $C_{\text{stray. 1.188}} \coloneqq 10 \cdot 10^{-12} \text{F} \qquad C_{\text{in.1}} \coloneqq 1 \cdot 10^{-6} \text{F} \qquad C_{\text{out. 1}} \coloneqq 1 \cdot 10^{-6} \text{F}$ $C_{\text{stray. 2.188}} \coloneqq C_{\text{stray. 1.188}} \qquad C_{\text{in.2}} \coloneqq C_{\text{in.1}} \qquad C_{\text{out. 2}} \coloneqq C_{\text{out. 1}}$

13.8.4 Calculation relevant data:

frequency range f for the below shown graphs:

13.8.5 Gain variants:

 $G_{b.b} := -g_{m.188} \cdot \left(\frac{1}{r_{a.188}} + \frac{1}{R_a}\right)^{-1}$ $G_{h,h} = -10.298 \times 10^{0}$ $G_{h,h,a} = 20.255 \times 10^{0}$ $G_{b.b.e} \coloneqq 20 \cdot \log(|G_{b.b}|)$ [dB] $G_{b.u.o1} := -\frac{1}{2} \cdot g_{m.188} \cdot \left(\frac{1}{r_{a.188}} + \frac{1}{R_a}\right)^{-1}$ $G_{h,u,o1} = -5.149 \times 10^{0}$ $G_{hu01e} = 14.234 \times 10^{0}$ $G_{b.u.o1.e} \coloneqq 20 \cdot \log(|G_{b.u.o1}|)$ [dB] $G_{h u o 2} = 5.149 \times 10^{0}$ $G_{b.u.o2} \coloneqq -G_{b.u.o1}$ $G_{u,i1,b} := -2 \cdot g_{m,188} \cdot \left(\frac{1}{r_{a,188}} + \frac{1}{R_a}\right)^{-1}$ $G_{u,i1,b} = -20.595 \times 10^{0}$ $G_{u,i2,b} = 20.595 \times 10^{0}$ $G_{u.i2.b} \coloneqq -G_{u.i1.b}$ $G_{u.i1.u.o1} := -g_{m.188} \cdot \left(\frac{1}{r_{a\ 188}} + \frac{1}{R_a}\right)^{-1}$ $G_{u,i1,u,o1} = -10.298 \times 10^{0}$ $G_{u,i1,u,o2} = 10.298 \times 10^{0}$ $G_{u,i1,u,o2} \coloneqq -G_{u,i1,u,o1}$ $G_{u,12,u,02} := -g_{m,188} \cdot \left(\frac{1}{r_{a,188}} + \frac{1}{R_{a}}\right)^{-1}$ $G_{u i2 u o2} = -10.298 \times 10^{0}$ $G_{u,i2} = 10.298 \times 10^{0}$ $G_{u.i2.u.o1} := -G_{u.i2.u.o2}$

variation of R_{a1} will lead to the desired gain G_{b.b}, e.g a gain of 10 requires $R_{a1} = R_{a2} = 2k11535$

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f := 10Hz, 20Hz, 20000 Hz

 $h := 1000 \cdot Hz$





13.8.7 Gain stage frequency and phase response for the balanced input and balanced ouput case only:



MCD Worksheet XIII

BAL calculations



MCD Worksheet XIII

BAL calculations

0 2 -0.025 1.25 degrees •_{0.b}(f) ∰ T_{o.b.e}(f) −0.05 0.5 deg -0.075 -0.25 -1 -0.1 $100 \ 1.10^3 \ 1.10^4 \ 1.10^5$ $100 \ 1.10^3 \ 1.10^4 \ 1.10^5$ 10 10 [Hz] [Hz] Figure 13.13 Transfer of output network Figure 13.14 Phase of output network $G_{\text{tot, b, b, e}}(f) \coloneqq 20 \cdot \log(|G_{\text{tot, b, b}}(f)|)$ $G_{tot,b,b}(f) := T_{i,b}(f) T_{o,b}(f) \cdot G_{b,b,eff}$ $\phi_{\text{tot,b,b}}(f) \coloneqq \phi_{i,b}(f) + \phi_{o,b}(f) + \phi_{G,b,b}(f)$ $\phi_{G b b}(f) := -180 \text{deg}$ 20.5 20.4 20.3 g G_{tot.b.b.e}(f) 20.2 20.1 20 1.104 Figure 13.15 Frequency 1.10^{3} 1.10^{5} 100 10 response of the whole gain [Hz] stage -175 -177.5 degrees] $\phi_{tot.b.b}(f)$ -180 deg -182.5

 1.10^{4}

 1.10^{5}

 1.10^{3}

[Hz]

100

Figure 13.16 Phase response of the whole gain stage

 $G_{tot.b.b.e}(20Hz) = 20.168 \times 10^0$ [dB]

-185

10

 $G_{\text{tot. b.b.}e}(10^3 \text{Hz}) = 20.17 \times 10^0 \text{ [dB]}$

 $G_{\text{tot. b.b.e}}(20.10^3 \text{Hz}) = 20.17 \times 10^0 \text{ [dB]}$

$$\frac{\Phi_{\text{tot}\,b,b}(20H2)}{\deg} = -178.588 \times 10^{0}$$

$$\frac{\Phi_{\text{tot}\,b,b}(10^{3}\text{Hz})}{\deg} = -179.974 \times 10^{0}$$

$$\Phi_{\text{tot}\,b,b}(20\cdot10^{3}\text{Hz})$$

$$\frac{\Phi_{\text{tot.b.b}}(20\cdot10 \text{ Hz})}{\text{deg}} = -180.049 \times 10^0$$

13.9 CMRR:

In a first example calculation it is assumed that the current generator Gen.1 is built-up by solid state active components, thus, the value of its internal resistance $r_{c,1}$ can be expected in the region of app. 1 - 2 M Ω .

A second example calculation uses a valve driven current generator with a much lower valued internal resistance of r_{e.2} in the region of app. 150 k Ω . To enable the inclusion of this kind of solution the supply voltages have to be adapted: either very much higher V_c or a rather high V_{ce}.

- 1

$$r_{c.1} \coloneqq 1.5 \cdot 10^{6} \Omega$$

$$G_{com} = -\mu_{188} \cdot \frac{R_{a}}{r_{a.188} + R_{a} + (1 + \mu_{188}) \cdot 2 \cdot r_{c}}$$

$$r_{c.2} \coloneqq 150 \cdot 10^{3} \Omega$$

 $R_{a,com}$ includes the frequency dependent effects of the whole output network:

$$R_{a.com}(f) := \left[\begin{array}{c} \frac{1}{R_a} + \frac{1}{R_{L1} + R_{L2} + \frac{1}{2j \cdot \pi \cdot f \left(\frac{1}{C_{out,1}} + \frac{1}{C_{out,2}}\right)^{-1}} \end{array} \right]$$

$$G_{\text{com.eff.}1}(f) \coloneqq -\mu_{188} \cdot \frac{R_{a.com}(f)}{r_{a.188} + R_{a.com}(f) + (1 + \mu_{188}) \cdot 2 \cdot r_{c.1}}$$

$$G_{\text{com.eff.2}}(f) \coloneqq -\mu_{188} \cdot \frac{R_{a.com}(f)}{r_{a.188} + R_{a.com}(f) + (1 + \mu_{188}) \cdot 2 \cdot r_{c.2}}$$

$$CMRR = \frac{G_{b.b}}{G_{com}} \qquad CMRR_1(f) := \frac{G_{tot.b.b}(f)}{G_{com.eff.}(f)} \qquad CMRR_2(f) := \frac{G_{tot.b.b}(f)}{G_{com.eff.}(f)}$$

$$\operatorname{CMRR}_{1,e}(f) := 20 \cdot \log(\operatorname{CMRR}_{1}(f))$$
 Cl



$$CMRR_{2e}(f) := 20 \cdot log(CMRR_{2}(f))$$

Figure 13.17 CMRR of the balanced gain stage with two different types of current generators

$\begin{vmatrix} CMRR_{1.e}(10^{3}Hz) \end{vmatrix} = 83.123 \times 10^{0} \quad [dB] \qquad \begin{vmatrix} CMRR_{2.e}(10^{3}Hz) \end{vmatrix} = 63.128 \times 10^{0} \quad [dB] \end{vmatrix}$ Application of the rule of thumb (rot): $CMRR_{1.rot} \coloneqq g_{m.188} \cdot r_{c.1} \qquad CMRR_{2.rot} \coloneqq g_{m.188} \cdot r_{c.2}$ $CMRR_{1.rote} \coloneqq 20 \cdot \log(CMRR_{1.rot}) \qquad CMRR_{2.rote} \coloneqq 20 \cdot \log(CMRR_{2.rot})$ $CMRR_{1.rote} = 80.424 \times 10^{0} \qquad [dB] \qquad CMRR_{2.rote} = 60.424 \times 10^{0} \qquad [dB]$

Note: Any tiny unbalance of the two halves of a balanced gain stage will create additional CMRR reductions

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14.1 On Feedback: a very short story by simple means

Usually, any system with input and output, whether it's technological or biological, reacts to signals that are arriving at the system's input sensors. The system's reaction shown at its output is based on these signals that are summed up with other system input signals generated by the system itself. To change the system output signal in a specific way a portion of the output signal can be fed back to the input and got summed up with all the other input signals, thus, influencing the input signals in a way that the whole system produces a corrected or controlled new output signal. This is a typical feedback controlled system.

In other words: no feedback means no controlled system inherent influence over the input / output signals, feedback means influence! Whereas technological systems in nearly 100% of the cases¹ react in a definite mathematical / physical manner on feedback - human beings or nations or any other group of people sometimes don't².

Two different types of feedback are used in electronic circuits: positive or negative feedback or both together. Positive means that a fraction of the output signal got summed up with the input signal without 180° phase change of the respective fraction of the output signal. Negative means that a 180° phase changed fraction of the output signal got summed up with the input signal.

Compared with an output signal without feedback positive feedback will lead to an increase of the output signal - sometimes up to a controlled or wild oscillation. Basically, negative feedback will lead to a decreased output signal. Very positive effects of negative feedback will occur as well, like eg. predictable performance and accuracy of a gain stage, decrease of its distortion, linearization of the frequency and phase response, compensation of temperature and component ageing effects, etc..

To precisely control gain the following paragraphs will deal with negative feedback only.

¹ Are there exceptions? maybe Schrödingers cat problem? Or any other phenomena of quantum physics?

² Worth reading: Stanislaw Lem's "Fiasco", ISBN 0-15-630630-1

14.2 Electronic model of negative feedback

We've seen in Chapters 1 and 2 that the same basic circuit around one valve will drastically change its transfer characteristic when inserting only one capacitance at the right place: C_c parallel to R_c . Besides a lot of other positive and negative effects this measure cuts off the feedback path via R_c and it increases the gain of the stage in the CCS+Cc case. How does this work? The following op-amp based Figure 14.1 explains the whole correlations between input and output of a feedback controlled system. It will lead to the basic feedback factor β and the basic equation for the gain of a feedback system. Absolutely equal mechanics apply to valve amp stages (see paragraph 14.3 and MCD worksheet XIV-2). I will discuss two different cases. The first case works without any output resistance R_o of the amplifier ($R_o = 0R$), the second case offers an output resistance $R_o > 0R$.



Figure 14.1 General feedback circuitry

14.2.1 Case 1:
$$R_0 = 0R$$

Assumed that the output resistance R_o of the amp V1 in Figure 14.1 is zero the derivation of the feedback equation looks as follows (G_o is the open loop gain of V1, G1 will be the gain of the Figure 14.1 gain stage after application of negative feedback from the output of V1 to its (-)-input):

$$v_{o} = G_{o} v_{D}$$

$$v_{o} = G_{o} (v_{i} - v_{Z1})$$

$$v_{o} = G_{o} \left(v_{i} - v_{o} \frac{Z1}{Z1 + Z2} \right)$$
(14.1)

$$\beta = \frac{Z1}{Z1 + Z2} \tag{14.2}$$

$$\frac{v_0}{v_i} = Gl \tag{14.3}$$

$$G1 = \frac{G_0}{1 + \beta G_0}$$
(14.4)

If G_o becomes nearly infinite the feedback controlled gain G1 of the stage will change to the well known equation for the gain of an op-amp gain stage:

$$G1=1+\frac{Z2}{Z1}$$
 (14.5)

14.2.2 Case 2: $R_0 > 0R$

Assumed that the output resistance R_o of V1 is >0R, than, the above shown equations will change the following way (G_o is the open loop gain of V2, G2 will be the gain of the Figure 14.2 gain stage after application of negative feedback from the output of V1 to its (-)-input):



Figure 14.2 Feedback system with output resistance R_o bigger than zero

$$v_{o.R.o} = v_D G_o$$

$$v_o = v_D G_o - v_{R.o}$$

$$v_{R.o} = v_{o.R.o} \frac{R_o}{R_o + Z1 + Z2}$$

$$v_o = v_D G_o \left(1 - \frac{R_o}{R_o + Z1 + Z2} \right)$$

$$v_D = v_i - v_{Z1}$$

$$v_{Z1} = v_o \beta 1$$

$$\beta 1 = \frac{Z1}{Z1 + Z2}$$

$$\beta 2 = \frac{R_o}{R_o + Z1 + Z2}$$
(14.7)

$$\Rightarrow v_0 = (v_1 - v_0 \beta 1) G_0 (1 - \beta 2)$$
(14.8)

$$\frac{v_{o}}{v_{i}} = G2$$

$$\Rightarrow G2 = \frac{G_{o}(1-\beta 2)}{1+G_{o}\beta I(1-\beta 2)}$$
(14.9)

With $\beta 2 = 0$ and $G_o =$ infinite the feedback controlled gain G2 of the stage becomes:

$$G2 = 1 + \frac{Z2}{Z1}$$
(14.10)

14.3 Feedback factor $\beta 1$ for the CCS and CCS+Cc gain stage case of Chapters 1 & 2^3

 $\begin{array}{ll} \mbox{Gain of the CCS:} & \mbox{G1}_u & (\mbox{see equation (1.2)}) \\ \mbox{Gain of the CCS+Cc:} & \mbox{G1}_b & (\mbox{see equation (2.2)}) \end{array}$

Thus, the feedback factor $\beta 1$ becomes⁴:

$$Gl_{u} = \frac{Gl_{b}}{1 + (1 + \mu)\frac{R_{c}}{r_{a} + R_{a}}}$$
(14.11)

$$\Rightarrow (1+\mu)\frac{R_c}{r_a+R_a} = \beta I G l_b$$
(14.12)

$$\Rightarrow \beta 1 = -\left(\frac{1}{\mu} + 1\right) \frac{R_c}{R_a}$$
(14.13)

Rule of thumb:

With $\mu >>1 \beta 1_{rot}$ becomes:

$$\beta l_{\text{rot}} = -\frac{R_c}{R_a} \tag{14.14}$$

³ Details see MCD worksheet XIV-2 on the following pages

⁴ R_c and R_a : see Chapter 2, Figure 2.1

MCD Worksheet XIV-1 FB calculations

14.4 Feedback with zero output resistance R₀:







with $G_0 = \infty$ G1 becomes:

$$G1 = \frac{1}{\frac{1}{G_0} + \beta 1} = \frac{1}{\beta 1} = \frac{Z1 + Z2}{Z1} = 1 + \frac{Z2}{Z1}$$

MCD Worksheet XIV-1 FB calculations





MCD Worksheet XIV-2 FB calculations Page 1 \triangleright Feedback factor B1 of CCS (u) vs. CCS +Cc (b): 14.7 $Gl_u = -\mu \cdot \frac{R_a}{r_a + R_a + (1 + \mu) \cdot R_c}$ $G1_b = -\mu \cdot \frac{R_a}{r_a + R_a}$ $\frac{Gl_u}{Gl_b} = \frac{\left[-\mu \cdot \frac{R_a}{r_a + R_a + (1 + \mu) \cdot R_c}\right]}{\left(-\mu \cdot \frac{R_a}{r_a + R_a}\right)}$ $\frac{\text{Gl}_{u}}{\text{Gl}_{b}} = \frac{1}{1 + (1 + \mu)\frac{\text{R}_{c}}{r + \mu}}$ $\frac{Gl_u}{Gl_h} = \frac{r_a + R_a}{r_a + R_a + R_c + R_c \cdot \mu}$ $G1_{u} = \frac{G1_{b}}{\left[1 + (1 + \mu)\frac{R_{c}}{r_{c} + R_{c}}\right]}$ $(1+\mu)\frac{R_c}{r_a+R_a} = \beta \cdot G1_b$ $\beta 1 = \frac{(1+\mu)\frac{R_c}{r_a + R_a}}{-\mu \frac{R_a}{r_a + R_a}}$ $\beta 1 = -(1+\mu) \cdot \frac{R_c}{\mu R_c} = -\left(\frac{1}{\mu} + 1\right) \cdot \frac{R_c}{R_c}$ $G = \frac{G_0}{1 + \beta \cdot G_0}$ $G1_{u} = \frac{G1_{b}}{1 + \beta 1 \cdot G1_{b}}$ 14.7.1 Example: $\mu := 100$ $R_c := 1.2 \cdot 10^3 \Omega$ $R_a := 100 \cdot 10^3 \Omega$ $r_a := 62.5 \cdot 10^3 \Omega$ $\beta 1 = -12.12 \times 10^{-3}$ $\frac{R_c}{R_a} = 12 \times 10^{-3}$ $\beta 1 := -\left(\frac{1}{\mu} + 1\right) \cdot \frac{R_c}{R_a}$ $G1_b := -\mu \cdot \frac{R_a}{r_a + R_a}$ $G1_b = -61.538$ $G1_{u} \coloneqq \frac{G1_{b}}{1 + \beta 1 \cdot G1_{b}}$ $G1_{11} = -35.249$ 14.7.2 Test:

$$G1_t := -\mu \cdot \frac{R_a}{r_a + R_a + (1 + \mu) \cdot R_c}$$
 $G1_t = -35.249$

Design goal: Development of a 3 stage RIAA-equalized and a 3 stage nonequalized pre-amp, each working alternately with overall and local feedback

15.1 Introduction

The aim of this rather complex example is the following one:

I want to check if there are differences that can be heard or otherwise detected between various feedback or non-feedback driven versions of two types of pre-amps -

- with equally biased valves in each version
- with no change of the DC environment of each valve
- with no change in overall gain at 1kHz (= 50 = +34dB) for the 4 differently designed RIAA equalized pre-amps
- with no change in overall gain at 1kHz (= 500 = +54dB) for the 4 differently designed pre-amps with a flat frequency response producing equalization

The pre-amp versions should look as follows:

- ➤ A: 4 different pre-amps à la Figures 15.1 and 15.4 with a non-equalized (flat) frequency response to be tested with test sequence 1 à la Figure 15.3:
- B: 4 different pre-amps à la Figures 15.1 and 15.4 with a RIAA equalized (r = RIAA equalized) frequency response to be tested with test sequence 2 à la Figure 15.6:

The 4 different sub-versions cc ... oo should look as follows:

- cc = overall feedback plus local feedback around each valve
- co = overall feedback plus no local feedback for V2 only
- oc = no overall feedback plus local feedback for V1 and V2
- oo = no overall feedback plus no local feedback for V1 and V2
- ▶ as CF1 in all versions V3||V4 keep their current feedback via the cathode
- Version subscripts cc, co, oc, oo:
 - 1st letter of the subscript indicates "overall"
 - 2nd letter of the subscript indicates "local"
 - c means: closed loop
 - o means: open loop



Figure 15.1 Basic pre-amp design with overall feedback - including the alternative to change V2's gain and local feedback situation



Figure 15.2 Simplified circuit diagram of Figure 15.1 including all calculation relevant active and passive circuit blocks



Figure 15.3 A-versions and test sequence 1



Figure 15.4 Basic pre-amp design without overall feedback - including the alternative to change V1's and V2's gain and local feedback situation



Figure 15.5 Simplified circuit diagram of Figure 15.4 including all calculation relevant active and passive circuit blocks



Figure 15.6 B-versions and test sequence 2

15.2 Description of the pre-amps

The purpose of this chapter is to demonstrate the usage of this reference book by going through the whole calculation course for the pre-amps (see MCD Worksheets XV-1 ... 3 on the following pages). The design goal will be to get pre-amps with a reasonable frequency and phase response in B_{20k} as well as - in the overall feed-back cases - an open loop gain G_o of approximately 1400 ... 1600, but not taking into account any feedback nor RIAA equalization. In the non-overall feed-back cases the overall gain should be 50 in the RIAA case and 500 in the flat frequency response case.

After inclusion of a suitable Z2(f) forming resistor into the feedback path - or by adequately changing the plate resistors - the A-version pre-amps should produce $1V_{rms}$ output voltage with a $2mV_{rms}$ input signal at 1kHz. A deviation from a flat frequency response of max. -0.25 dB at the ends of the frequency band should be a result as well.

After inclusion of a suitable RIAA network¹ as Z2(f) into the feedback path or as passive networks between V1 ... V3 the B-version pre-amps should produce $250V_{rms}$ output voltage with a $5mV_{rms}$ input signal at 1kHz. A deviation of max. \pm 0.25 dB from the exact RIAA transfer should be the outcome.

The basic pre-amp consists of three active gain stages V1 ... V3,4 with respective gains G1 ... G3. The gains for V1 and V2 are set by - from version to version - different cathode and plate component arrangements. The plate and cathode DC currents as well as the plate and cathode DC voltages do not change throughout all versions! The DC plate voltages are kept constant by adequate split of the plate resistors. They always sum up to 100k. That's why the upper resistor needs an AC voltage blocking capacitance whereas the lower one defines the gain of that valve.

At the inputs and outputs of V1 ... V3,4 we find different stage separating passive networks. They serve for DC decoupling and valve bias setting as well as for frequency (also passive RIAA) and phase influencing purposes. AC voltage short-cutting cathode capacitances are also included into the calculation course (see Figures 15.2 & 15.5)

Some additional remarks on the components of the circuit diagrams:

- V1,2: ECC83 paired versions for stereo operation
- V3,4: ECC83 both systems in parallel operation
- non electrolytic capacitances C_{in} , $C1 \dots 3^2$ could be Wima MKP types or Epcos B32520 \dots B32529³ (best case); they all have to fulfil the requirements of the rather high DC voltages. C2, C3 should be paired for both channels

¹ for detailed calculations of RIAA networks see Chapters 8 & 9 of TSOS

² for C2 = C_x, C3 = C_y see MCD Worksheet XV-1 on one of the following pages

 ³ for extremely low distortion types see Cyril Bateman's articles on "Understanding Capacitors" in Electronics World (EW) 12-1997 ... 08-1998 and "Capacitor Sounds" in EW 05 ... 11-2002

- the electrolytic capacitances⁴ C4, C11, C12 could be low ESR 450V types
- C13, C14 could be 10V Panasonic FC
- C5 could be a 100V Panasonic FC
- all resistors should be metal types 1% E96 and should fulfil all kinds of specific power requirements; there is no need to take high price bulk foil resistors for R5, R10: the Signal-to-Noise-ratio improvement would be max. 0.2dB only
- for MM phono pre-amps of the shown types there is no need to include C_{in} into the circuitry, nevertheless I've done it to demonstrate its influence on frequency and phase response
- to make things a bit more difficult
 - I didn't take C4 and Z2 in a sequence and C5 direct connected to the cathodes of V3,4: the effect would be a simpler calculation approach and C4 would become a smaller size
 - I've included R2 and R7 to demonstrate the influence of these resistors quite often used by designers to stop any kind of wild oscillation
 - I've also included a third wild oscillation preventing resistor R13 into the calculation course it's not shown in Figures 15.1 & 15.4 between plate of V2 and grids of V3,4 but we never know ...

⁴ Test circuit for the selection of electrolytic capacitors by sound differences: see Figure 6.5 of TSOS plus: worth to read the debate on electrolytic capacitors inside the audio chain: letters from Douglas Self and others in EW 04, 06, 10-1988

15.3 MathCad (MCD) worksheets for the Design Example - given on the following pages:

MCD Worksheet XV-1

This worksheet offers the complete calculation course for the pre-amp type (with overall feedback) that serves for 4 different versions: two for the versions with a actively produced flat frequency response, two for the actively RIAA equalized versions.

MCD Worksheet XV-2

This worksheet offers the complete calculation course for the pre-amp type (with local feedback only) that serves for 2 different versions that produce a flat frequency response.

MCD Worksheet XV-3

This worksheet offers the complete calculation course for the pre-amp type (with local feedback only) that serves for 2 different versions that produce a passively RIAA equalized frequency response.

MCD Worksheet XV-1 overall feedback versions

15.4 Example calculations for a 3-stage pre-amp with flat frequency response (versions $A_{cc}+A_{co}$) and a 3-stage MM phono pre-amp (versions $B_{cc}+B_{co}$)

15.4.1 Circuit diagram and components:



Figure 15.7 Basic pre-amp design with overall feedback (= Fig. 15.1)





15.4.1.1 Valve constants and data sheet figures:

V1 4: 1/2 ECC83-12AX7		
$I_{a1} = I_{a2} = I_{a3} = I_{a4} = I_{a}$		$I_a := 1.7 \cdot 10^{-3} A$
$V_{cc1.cc} = V_{cc1.co} = V_{cc2.cc} = V_{cc2.cc}$	cc2.co = 420V	$V_{cc3} = 420 V$
$V_{a.1} = 250V$	$V_{a.2} = 250 V$	$V_{a.3} = V_{cc3}$
$g_{m.v1} = g_{m.v2} = g_{m.v3} = g_{m.v4} =$	$g_{\rm m} := 1.9 \cdot 10^{-3} {\rm S}$	
$\mu_{v1} = \mu_{v2} = \mu_{v3} = \mu_{v4} = \mu$		μ := 101
$r_{a.v1} = r_{a.v2} = r_{a.v3} = r_{a.v4} = r_a$		$r_a := 53 \cdot 10^3 \Omega$
$C_{g.a.83} \coloneqq 1.6 \cdot 10^{-12} F$	$C_{a.c.83} \coloneqq 0.33 \cdot 10^{-12} F$	$C_{g.c.83} \coloneqq 1.65 \cdot 10^{-12} F$

page 1

MCD Worksheet XV-1 overall feedback versions \geq

page 2

15.4.1.2 **Component figures:** $R0 := 1 \cdot 10^3 \Omega$ $R_{1a} := 523 \cdot 10^{3} \Omega$ $R1b := 475 \cdot 10^{3} \Omega$ $R3 := 1 \cdot 10^3 \Omega$ $R2 := 100\Omega$ $R6 := 1000 \cdot 10^3 \Omega$ $R8 := 1 \cdot 10^3 \Omega$ $R7 := 100 \Omega$ $R11 := 75 \cdot 10^3 \Omega$ R12 := $47.5 \cdot 10^3 \Omega$ $R13 := 100 \Omega$ $R4_{cc} := 100 \cdot 10^{3} \Omega - R5_{cc} \qquad R4_{cc} = 0 \times 10^{0} \Omega$ $R5_{cc} \coloneqq 100 \cdot 10^3 \Omega$ $R4_{c0} := 100 \cdot 10^{3} \Omega - R5_{c0}$ $R4_{c0} = 0 \times 10^{0} \Omega$ $R5_{co} := R5_{cc}$ $R10_{cc} := 100 \cdot 10^{3} \Omega$ $R9_{cc} := 100 \cdot 10^{3} \Omega - R10_{cc}$ $R9_{cc} = 0 \times 10^{0} \Omega$ $R10_{co} \approx 34 \cdot 10^3 \Omega$ $R9_{c0} := 100 \cdot 10^{3} \Omega - R10_{c0}$ $R9_{c0} = 66 \times 10^{3} \Omega$ $C_{in} := 2.2 \cdot 10^{-6} F$ $C1 := 470 \cdot 10^{-9} F$ $C4 := 22 \cdot 10^{-6} F$ $C5 := 22 \cdot 10^{-6} F$ $C11 = 10 \cdot 10^{-6} F$ C12 = C11 $C_{strav.3} := 4 \cdot 10^{-12} F$ $C_{strav 1} := 10 \cdot 10^{-12} F$ $C_{\text{stray 2}} := 5 \cdot 10^{-12} \text{F}$

15.4.2 Gain calculations (Z1, Z2 purely resistive)

Z1 := R3

$$Gl_{cc} := -\mu \cdot \frac{\left(\frac{1}{R5_{cc}} + \frac{1}{R6}\right)^{-1}}{r_{a} + \left(\frac{1}{R5_{cc}} + \frac{1}{R6}\right)^{-1} + (1+\mu) \cdot R3}$$

 $G1_{co} := G1_{cc}$

$$G2_{cc} \coloneqq -\mu \cdot \frac{R10_{cc}}{r_a + R10_{cc} + (1+\mu) \cdot R8}$$

$$G2_{co} := -\mu \cdot \frac{R10_{co}}{r_a + R10_{co}}$$
$$r_{a.v3.4} := \frac{r_a}{2}$$
$$G3 := \mu \cdot \frac{R11}{r_{a.v3.4} + (1 + \mu) \cdot R11}$$
$$A_{cc} := G1_{cc} \cdot G2_{cc} \cdot G3$$

 $A_{co} := G1_{co} \cdot G2_{co} \cdot G3$

 $Z2 := 0.8 \cdot 10^{6} \Omega$

 $G1_{cc} = -37.338 \times 10^{0}$

$$G1_{co} = -37.338 \times 10^{0}$$

 $G2_{cc} = -39.608 \times 10^{0}$

$$G2_{co} = -39.471 \times 10^{0}$$

$$G3 = 986.778 \times 10^{-5}$$

 $A_{cc} = 1.459 \times 10^{-5}$

 $A_{co} = 1.454 \times 10^3$

MCD Worksheet XV-1



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➢ MCD Worksheet XV-1 o[™]

overall feedback versions

$$T1(f) = \frac{v_{o,1}(f)}{v_0(f)} \qquad M_{cc}(f) \coloneqq \frac{Z2_{1,cc}(f)}{R2 + Z2_{1,cc}(f)} \qquad \left(\frac{1}{R1a} + \frac{1}{R1b}\right)^{-1} = 47.113 \times 10^3 \Omega$$

$$N_{cc}(f) \coloneqq \frac{\left(\frac{1}{R1b} + \frac{1}{R2 + Z2_{1,cc}(f)}\right)^{-1}}{Z1_1(f) + \left(\frac{1}{R1b} + \frac{1}{R2 + Z2_{1,cc}(f)}\right)^{-1}}$$

$$O_{cc}(f) \coloneqq \frac{\left[\frac{1}{R1a} + \frac{1}{\left[Z1_1(f) + \left(\frac{1}{R1b} + \frac{1}{R2 + Z2_{1,cc}(f)}\right)^{-1}\right]\right]^{-1}}{R0 + \left[\frac{1}{R1a} + \frac{1}{\left[Z1_1(f) + \left(\frac{1}{R1b} + \frac{1}{R2 + Z2_{1,cc}(f)}\right)^{-1}\right]\right]^{-1}}$$

 $\mathrm{Tl}_{\mathrm{cc}}(\mathrm{f}) \coloneqq \mathrm{M}_{\mathrm{cc}}(\mathrm{f}) \cdot \mathrm{N}_{\mathrm{cc}}(\mathrm{f}) \cdot \mathrm{O}_{\mathrm{cc}}(\mathrm{f})$

 $T1_{co}(f) := T1_{cc}(f)$









Figure 15.12 Phases of T1(f)


MCD Worksheet XV-1 overall feedback versions \triangleright

$$\begin{split} v_{R6}(\theta) &= v_{Z,1,2}(\theta) \cdot \frac{\left(\frac{1}{R6} + \frac{1}{R7 + Z3_{2}(\theta)}\right)^{-1}}{Z2_{2}(\theta) + \left(\frac{1}{R6} + \frac{1}{R7 + Z3_{2}(\theta)}\right)^{-1}} \\ v_{0,2}(\theta) &= v_{R6}(\theta) \cdot \frac{Z3_{2}(\theta)}{R7 + Z3_{2}(\theta)} \\ T2_{1,cc}(\theta) &:= \frac{\left[\frac{1}{Z1_{2,cc}(\theta)} + \frac{1}{Z2_{2}(\theta) + \left(\frac{1}{R6} + \frac{1}{Z3_{2,cc}(\theta)}\right)^{-1}}\right]^{-1}}{R_{0,a,1,cc} + \left[\frac{1}{Z1_{2,cc}(\theta)} + \frac{1}{Z2_{2}(\theta) + \left(\frac{1}{R6} + \frac{1}{Z3_{2,cc}(\theta)}\right)^{-1}}\right]^{-1}} \\ T2_{1,co}(\theta) &:= \frac{\left[\frac{1}{Z1_{2,co}(\theta)} + \frac{1}{Z2_{2}(\theta) + \left(\frac{1}{R6} + \frac{1}{Z3_{2,cc}(\theta)}\right)^{-1}}\right]^{-1}}{R_{0,a,1,cc} + \left[\frac{1}{Z1_{2,co}(\theta)} + \frac{1}{Z2_{2}(\theta) + \left(\frac{1}{R6} + \frac{1}{Z3_{2,cc}(\theta)}\right)^{-1}}\right]^{-1}} \\ T2_{1,co}(\theta) &:= \frac{\left(\frac{1}{R6} + \frac{1}{R7 + Z3_{2,cc}(\theta)}\right)^{-1}}{R_{0,a,1,cc} + \left[\frac{1}{Z1_{2,co}(\theta)} + \frac{1}{Z2_{2}(\theta) + \left(\frac{1}{R6} + \frac{1}{Z3_{2,cc}(\theta)}\right)^{-1}}\right]^{-1}} \\ T2_{2,cc}(\theta) &:= \frac{\left(\frac{1}{R6} + \frac{1}{R7 + Z3_{2,cc}(\theta)}\right)^{-1}}{Z2_{2}(\theta) + \left(\frac{1}{R6} + \frac{1}{R7 + Z3_{2,cc}(\theta)}\right)^{-1}} \cdot \frac{Z3_{2,cc}(\theta)}{R7 + Z3_{2,co}(\theta)} \\ T2_{2,co}(\theta) &:= \frac{\left(\frac{1}{R6} + \frac{1}{R7 + Z3_{2,co}(\theta)}\right)^{-1}}{Z2_{2}(\theta) + \left(\frac{1}{R6} + \frac{1}{R7 + Z3_{2,co}(\theta)}\right)^{-1}} \cdot \frac{Z3_{2,co}(\theta)}{R7 + Z3_{2,co}(\theta)} \end{split}$$



 $C_{0,2 \text{ co tot}} = 1.93 \times 10^{-12} \text{F}$ $C_{0.2.co.tot} := C_{a.c.83} + C_{g.a.83}$ $Z2_{3}(f) := \frac{1}{2j \cdot \pi \cdot f \cdot C_{j,3,tot}}$ $Z1_3(f) := \frac{1}{2j \cdot \pi \cdot f \cdot C_{0,2,tot}}$ $Z1_{3.co}(f) := \frac{1}{2j \cdot \pi \cdot f \cdot C_0 \cdot 2 \cdot co \cdot tot}$ $Z2_{3}(f) := \frac{1}{2j \cdot \pi \cdot f \cdot C_{j-3} \cot}$ v.i3 v.Z1.3 Z1.3 Z2.3 v.o.3 Figure 15.16 T3(f) network $v_{0.3}(f) = v_{Z.1.3}(f) \cdot \frac{Z2_3(f)}{Z2_3(f) + R13}$ $v_{Z1,3}(f) = v_{1,3}(f) \cdot \frac{\left(\frac{1}{Z1_3(f)} + \frac{1}{R13 + Z2_3(f)}\right)^{-1}}{R_{0,a,2} + \left(\frac{1}{Z1_2(f)} + \frac{1}{R13 + Z2_2(f)}\right)^{-1}}$ $T3(f) = \frac{v_{0.3}(f)}{v_{1.3}(f)}$ $T3_{cc}(f) \coloneqq \frac{\left(\frac{1}{Z1_3(f)} + \frac{1}{R13 + Z2_3(f)}\right)^{-1}}{R_{o.a.2.cc} + \left(\frac{1}{Z1_3(f)} + \frac{1}{R13 + Z2_2(f)}\right)^{-1}} \cdot \frac{Z2_3(f)}{Z2_3(f) + R13}$ $T3_{c0}(f) \coloneqq \frac{\left(\frac{1}{Z1_{3,c0}(f)} + \frac{1}{R13 + Z2_{3}(f)}\right)^{-1}}{R_{o.a.2,c0} + \left(\frac{1}{Z1_{2,c0}(f)} + \frac{1}{R12 + Z2_{3}(f)}\right)^{-1}} \frac{Z2_{3}(f)}{Z2_{3}(f) + R13}$ $\phi 3_{cc}(f) := \operatorname{atan}\left(\frac{\operatorname{Im}(T3_{cc}(f))}{\operatorname{Re}(T3_{cc}(f))}\right)$ $T3_{cc.e}(f) := 20 \cdot log(\left|T3_{cc}(f)\right|)$ $\phi_{3_{c0}}(f) := \operatorname{atan}\left(\frac{\operatorname{Im}(T_{3_{c0}}(f))}{\operatorname{Re}(T_{3_{c0}}(f))}\right)$ $T3_{co.e}(f) := 20 \cdot \log(|T3_{co}(f)|)$





15.4.3.5 T4: $r_{c.3} \coloneqq \frac{r_{a.v3.4}}{\mu + 1}$ $r_{c,3} = 259.804 \times 10^{0} \Omega$ $R_{0.c.3} := \left(\frac{1}{r_{c.3}} + \frac{1}{R11}\right)^{-1}$ $R_{0,c,3} = 258.907 \times 10^{0} \Omega$ $r_{c.1} \coloneqq \frac{r_a}{\mu + 1}$ $r_{c.1} = 519.608 \times 10^{0} \Omega$ $R_{ff} := Z2 + \left(\frac{1}{R3} + \frac{1}{r_{c.1}}\right)^{-1}$ $R_{\rm ff} = 800.342 \times 10^3 \Omega$ $Z1_4(f) := \frac{1}{2j \cdot \pi \cdot f \cdot C4}$ $Z2_4(f) := \frac{1}{2j \cdot \pi \cdot f \cdot C5}$ R.o.c.3 C5 C4 v.i.4 R.ff v.R.ff R12 v.o.4 Figure 15.19 T4(f) network $v_{0.4}(f) = v_{R.ff} \frac{R12}{R12 + Z2_4(f)}$

15.4.4 Total gains $A_{xy,tot}(f)$ and phases $\phi_{xy,tot}(f)$ for the "flat" pre-amps:

 $Z1(f) := 10^3 \Omega$

 $A_{cc}(f) \coloneqq T1_{cc}(f) \cdot T2_{cc}(f) \cdot T3_{cc}(f) \cdot T4(f) \cdot A_{cc}$

 $Z2(f) := 0.8 \cdot 10^{6} \Omega$

$$\beta(\mathbf{f}) \coloneqq \frac{Z1(\mathbf{f})}{Z1(\mathbf{f}) + Z2(\mathbf{f})}$$

 $A_{co}(f) := T1_{co}(f) \cdot T2_{co}(f) \cdot T3_{co}(f) \cdot T4(f) \cdot A_{co}$

$$\begin{split} \mathsf{A}_{\mathsf{cc.tot}}(\mathfrak{f}) &\coloneqq \frac{\mathsf{A}_{\mathsf{cc}}(\mathfrak{f})}{1 + \beta(\mathfrak{f}) \cdot \mathsf{A}_{\mathsf{cc}}(\mathfrak{f})} & \mathsf{A}_{\mathsf{cc.tot.e}}(\mathfrak{f}) &\coloneqq 20 \cdot \log(\left|\mathsf{A}_{\mathsf{cc.tot}}(\mathfrak{f})\right|) \\ \mathsf{A}_{\mathsf{co.tot}}(\mathfrak{f}) &\coloneqq \frac{\mathsf{A}_{\mathsf{co}}(\mathfrak{f})}{1 + \beta(\mathfrak{f}) \cdot \mathsf{A}_{\mathsf{co}}(\mathfrak{f})} & \mathsf{A}_{\mathsf{co.tot.e}}(\mathfrak{f}) &\coloneqq 20 \cdot \log(\left|\mathsf{A}_{\mathsf{co.tot}}(\mathfrak{f})\right|) \end{split}$$











Figure 15.28 Input impedance for the 4 different versions

$$\left| Z_{\text{in},A,B,xy} (10^{3} \text{Hz}) \right| = 47.102 \times 10^{3} \Omega \qquad \qquad \left| Z_{\text{in},A,B,xy} (20 \cdot 10^{3} \text{Hz}) \right| = 43.233 \times 10^{3} \Omega$$

15.4.7 Final remarks:

- 15.4.7.1 Varying f_{opt} will lead to drastic changes in the low frequency range of the D $_{co.r}(f)$ plot shown in Figure 15.27
- 15.4.7.2 To get lowest deviation from the exact RIAA transfer only Rx and Ry need further trimming assumed that Cx and Cy got fixed values that were calculated with the respective formulae given in my book "The Sound of Silence"
- 15.4.7.3 A +/- 50% change of C_{in} will also lead to tiny changes in the low frequeny range of $D_{xy,r}(f)$ plot shown in Figure 15.27

MCD Worksheet XV-2 local feedback versions (flat)

15.5 Example calculations for a 3-stage pre-amp ($A_{oc}+A_{oo}$ versions) with flat frequency response in B_{20k} and no overall feedback

15.5.1 Circuit diagram and components:







Figure 15.30 Simplified equivalent circuit of Figure 15.29 (= Fig. 15.5)

15.5.1.1 Valve constants and data sheet figures:

V1 ... 4: 1/2 ECC83-12AX7

$$\begin{split} I_{a1} &= I_{a2} = I_{a3} = I_{a4} = I_{a} & I_{a} := 1.7 \cdot 10^{-3} \text{A} \\ V_{cc1.oc} &= V_{cc1.oo} = V_{cc2.oc} = V_{cc2.oo} = 420 \text{V} & V_{cc3} = 420 \text{V} \\ V_{a.1} &= 250 \text{V} & V_{a.2} = 250 \text{V} & V_{a.3} = V_{cc3} \\ g_{m.v1} &= g_{m.v2} = g_{m.v3} = g_{m.v4} = g_{m} & g_{m} := 1.9 \cdot 10^{-3} \text{S} \\ \mu_{v1} &= \mu_{v2} = \mu_{v3} = \mu_{v4} = \mu & \mu := 101 \\ r_{a.v1} &= r_{a.v2} = r_{a.v3} = r_{a.v4} = r_{a} & r_{a} := 53 \cdot 10^{3} \Omega \\ C_{g.a.83} := 1.6 \cdot 10^{-12} \text{F} & C_{a.c.83} := 0.33 \cdot 10^{-12} \text{F} & C_{g.c.83} := 1.65 \cdot 10^{-12} \text{F} \end{split}$$

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15.5.1.2 Component figures:

 $R0 := 1 \cdot 10^3 \Omega$ R1a := $52.3 \cdot 10^3 \Omega$ $R1b = 475 \cdot 10^{3} \Omega$ $R2 := 100\Omega$ $R3 := 1 \cdot 10^3 \Omega$ $R6 := 1000 \cdot 10^3 \Omega$ $R8 := 1 \cdot 10^{3} \Omega$ $R7 := 100\Omega$ $\begin{aligned} R12 &:= 47.5 \cdot 10^{3} \Omega & R13 &:= 100 \Omega \\ R4_{oc} &:= 100 \cdot 10^{3} \Omega - R5_{oc} & R4_{oc} &= 75.668 \times 10^{3} \Omega \end{aligned}$ R11 := $75 \cdot 10^3 \Omega$ $R5_{0C} \coloneqq 24.332 \cdot 10^3 \Omega$ $R4_{00} := 100 \cdot 10^{3} \Omega - R5_{00}$ $R4_{00} = 85 \times 10^{3} \Omega$ $R5_{00} := 15 \cdot 10^3 \Omega$ $R10_{00} := 100 \cdot 10^{3} \Omega$ $R9_{0C} := 100 \cdot 10^{3} \Omega - R10_{0C}$ $R9_{0C} = 0 \times 10^{0} \Omega$ $R10_{00} = 16.5 \cdot 10^3 \Omega$ $R9_{00} := 100 \cdot 10^{3} \Omega - R10_{00}$ $R9_{00} = 83.5 \times 10^{3} \Omega$ $C_{in} := 2.2 \cdot 10^{-6} F$ $C4 := 22 \cdot 10^{-6} F$ $C1 := 470 \cdot 10^{-9} F$ $C5 := 22 \cdot 10^{-6} F$ $C11 = 100 \cdot 10^{-6} F$ C12 = C11 $C_{\text{stray 1}} := 10 \cdot 10^{-12} \text{F}$ $C_{strav,2} := 5 \cdot 10^{-12} F$ $C_{strav,3} := 4 \cdot 10^{-12} F$

15.5.2 Gain calculations



MCD Worksheet XV-2 local feedback versions (flat)



local feedback versions (flat)

$$\begin{split} \mathsf{M}_{00}(\mathfrak{h}) &\coloneqq \frac{Z2_{1,00}(\mathfrak{h})}{\mathsf{R}2 + Z2_{1,00}(\mathfrak{h})} \\ \mathsf{N}_{00}(\mathfrak{h}) &\coloneqq \frac{\left(\frac{1}{\mathsf{R}1\mathfrak{h}} + \frac{1}{\mathsf{R}2 + Z2_{1,00}(\mathfrak{h})}\right)^{-1}}{Z1_1(\mathfrak{h} + \left(\frac{1}{\mathsf{R}1\mathfrak{h}} + \frac{1}{\mathsf{R}2 + Z2_{1,00}(\mathfrak{h})}\right)^{-1}} \\ \mathsf{O}_{00}(\mathfrak{h}) &\coloneqq \frac{\left[\frac{1}{\mathsf{R}1\mathfrak{a}} + \frac{1}{\mathsf{Z}1_1(\mathfrak{h} + \left(\frac{1}{\mathsf{R}1\mathfrak{h}} + \frac{1}{\mathsf{R}2 + Z2_{1,00}(\mathfrak{h})}\right)^{-1}\right]\right]^{-1}}{\mathsf{R}0 + \left[\frac{1}{\mathsf{R}1\mathfrak{a}} + \frac{1}{\mathsf{Z}1_1(\mathfrak{h} + \left(\frac{1}{\mathsf{R}1\mathfrak{h}} + \frac{1}{\mathsf{R}2 + Z2_{1,00}(\mathfrak{h})}\right)^{-1}\right]\right]^{-1}} \\ \mathsf{T}1_{1,00}(\mathfrak{h}) &\coloneqq \mathsf{M}_{00}(\mathfrak{h}\cdot\mathsf{N}_{00}(\mathfrak{h}\cdot\mathsf{O}_{00}(\mathfrak{h})) \\ \mathsf{T}1_{0,0}(\mathfrak{h}) &\coloneqq \mathsf{M}_{00}(\mathfrak{h}\cdot\mathsf{N}_{00}(\mathfrak{h})\circ\mathsf{O}_{00}(\mathfrak{h})) \\ \mathsf{T}1_{0,0}(\mathfrak{h}) &\coloneqq \mathsf{M}_{00}(\mathfrak{h}\cdot\mathsf{N}_{00}(\mathfrak{h}\circ\mathsf{O}_{00}(\mathfrak{h})) \\ \mathsf{T}1_{0,0}(\mathfrak{h}) &\coloneqq \mathsf{M}_{00}(\mathfrak{h}\cdot\mathsf{N}_{00}(\mathfrak{h}\circ\mathsf{O}_{00}(\mathfrak{h})) \\ \mathsf{T}1_{0,0}(\mathfrak{h}) &\coloneqq \mathsf{T}1_{0,0}(\mathfrak{h}) \\ \mathsf{T}1_{0,0}(\mathfrak{h}) \\ \mathsf{T}1_{0,0}(\mathfrak{h}) &\coloneqq \mathsf{T}1_{0,0}(\mathfrak{h}) \\ \mathsf{T}1_{0,0}(\mathfrak{h}) &\coloneqq \mathsf{T}1_{0,0}(\mathfrak{h}) \\ \mathsf{T}$$





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$$\begin{aligned} Z_{32,\infty}(\theta) &:= \frac{1}{2j \cdot \pi \cdot \Gamma C_{12,00,101}} & Z_{32,\infty}(\theta) &:= \frac{1}{2j \cdot \pi \cdot \Gamma C_{12,00,101}} \\ & V_{21,2}(\theta) &= v_{1,2}(\theta) - \left[\frac{\left[\frac{1}{2l_2(\theta)} + \frac{1}{2l_2(\theta)} + \frac{1}{\left(\frac{1}{2d_2(\theta)} + \frac{1}{2d_3(\theta)} \right)^{-1}} \right]^{-1}}{R_{0,\alpha,1} + \left[\frac{1}{2l_2(\theta)} + \frac{1}{\pi \cdot 7 + Z_{32}(\theta)} \right]^{-1}} \\ & v_{R6}(\theta) &= v_{Z,1,2}(\theta) - \frac{\left(\frac{1}{2d_2(\theta)} + \frac{1}{\pi \cdot 7 + Z_{32}(\theta)} \right)^{-1}}{Z_{22}(\theta) + \left(\frac{1}{2d_2(\theta)} + \frac{1}{\pi \cdot 7 + Z_{32}(\theta)} \right)^{-1}} \\ & v_{0,2}(\theta) &= v_{R6}(\theta) - \frac{\left[\frac{1}{2l_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} \right]^{-1}}{R_{0,\alpha,1,\infty} + \left[\frac{1}{2l_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} \right]^{-1} \\ & T_{21,\infty}(\theta) &= \frac{\left[\frac{1}{2l_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} \right]^{-1}}{R_{0,\alpha,1,\infty} + \left[\frac{1}{2l_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} \right]^{-1} \\ & T_{21,\infty}(\theta) &= \frac{\left(\frac{1}{2d_2(\theta)} + \frac{1}{\pi \cdot d} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} \right]^{-1}}{R_{0,\alpha,1,\infty} + \left[\frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} + \frac{1}{2d_{2,\infty}(\theta)} \right]^{-1} \\ & T_{22,\infty}(\theta) &= \frac{\left(\frac{1}{R6} + \frac{1}{R7 + Z_{2,\infty}(\theta)} \right)^{-1}}{2d_{2,\infty}(\theta) + \left(\frac{1}{R6} + \frac{1}{Z_{2,\infty}(\theta)} \right)^{-1} } \\ & T_{22,\infty}(\theta) &= \frac{\left(\frac{1}{R6} + \frac{1}{R7 + Z_{2,\infty}(\theta)} \right)^{-1}}{2d_{2,\infty}(\theta) + \left(\frac{1}{R6} + \frac{1}{Z_{2,\infty}(\theta)} \right)^{-1} } \\ & T_{22,\infty}(\theta) &= \frac{\left(\frac{1}{R6} + \frac{1}{R7 + Z_{2,\infty}(\theta)} \right)^{-1}}{2d_{2,\infty}(\theta) + \left(\frac{1}{R6} + \frac{1}{R7 + Z_{2,\infty}(\theta)} \right)^{-1} } \\ & T_{22,\infty}(\theta) &= \frac{\left(\frac{1}{R6} + \frac{1}{R7 + Z_{2,\infty}(\theta)} \right)^{-1}}{2d_{2,\infty}(\theta) + \left(\frac{1}{R6} + \frac{1}{R7 + Z_{2,\infty}(\theta)} \right)^{-1} } \\ & T_{22,\infty}(\theta) &= \frac{\left(\frac{1}{R6} + \frac{1}{R7 + Z_{2,\infty}(\theta)} \right)^{-1}}{2d_{2,\infty}(\theta) + \left(\frac{1}{R6} + \frac{1}{R7 + Z_{2,\infty}(\theta)} \right)^{-1} } \\ & T_{22,\infty}(\theta) \\ & T_{22,\infty}(\theta) + \left(\frac{1}{R6} + \frac{1}{R7 + Z_{2,\infty}(\theta)} \right)^{-1} \\ & T_{22,\infty}(\theta) + \left(\frac{1}{R6} + \frac{1}{R7 + Z_{2,\infty}(\theta)} \right)^{-1} \\ & T_{22,\infty}(\theta) \\ & T_{22,\infty}($$



Figure 15.36 Phases of T2(f)







v.o.4

Figure 15.40 T4(f) network (= Fig. 15.19)

$$r_{c.3} \coloneqq \frac{r_{a.v3.4}}{\mu + 1} \qquad r_{c.3} = 259.804 \times 10^{0} \Omega$$
$$R_{o.c.3} \coloneqq \left(\frac{1}{r_{c.3}} + \frac{1}{R11}\right)^{-1} \qquad R_{o.c.3} = 258.907 \times 10^{0} \Omega$$





Figure 15.43 Frequency responses of both pre-amps





 $\begin{array}{ll} A_{\text{oc.tot.}e}(10^{3}\text{Hz}) = 53.984 \times 10^{0} & \frac{\phi_{\text{A.oc.tot}}(20\text{Hz})}{\text{deg}} = 2.239 \times 10^{0} \\ A_{\text{oo.tot.}e}(10^{3}\text{Hz}) = 53.989 \times 10^{0} & \frac{\phi_{\text{A.oc.tot}}(20\text{Hz})}{\text{deg}} = 3.4 \times 10^{0} \\ A_{\text{oc.tot.}e}(20 \cdot 10^{3}\text{Hz}) = 53.815 \times 10^{0} & \frac{\phi_{\text{A.oc.tot}}(20 \cdot 10^{3}\text{Hz})}{\text{deg}} = -14.402 \times 10^{0} \\ A_{\text{oo.tot.}e}(20 \cdot 10^{3}\text{Hz}) = 53.959 \times 10^{0} & \frac{\phi_{\text{A.oc.tot}}(20 \cdot 10^{3}\text{Hz})}{\text{deg}} = -5.926 \times 10^{0} \end{array}$

MCD Worksheet XV-2 local feedback versions (flat)







MCD Worksheet XV-3 local feedback versions (RIAA)

15.6 Example calculations for a 3-stage MM phono pre-amp ($B_{oc}+B_{oo}$ versions)

15.6.1 Circuit diagram and components:



Figure 15.46 Basic pre-amp design with passive RIAA equalization and without overall feedback (= Fig. 15.4)



Figure 15.47 Simplified equivalent circuit of Figure 15.46 (= Fig. 15.5)

15.6.1.1 Valve constants and data sheet figures:

V1 ... 4: 1/2 ECC83-12AX7 $I_a := 1.7 \cdot 10^{-3} A$ $I_{a1} = I_{a2} = I_{a3} = I_{a4} = I_{a}$ $V_{cc3} = 420V$ $V_{cc1.oc} = V_{cc1.oo} = V_{cc2.oc} = V_{cc2.oo} = 420V$ $V_{a,1} = 250V$ $V_{a,2} = 250V$ $V_{a,3} = V_{cc3}$ $g_{m} := 1.9 \cdot 10^{-3} S$ $g_{m,v1} = g_{m,v2} = g_{m,v3} = g_{m,v4} = g_m$ $\mu := 101$ $\mu_{v1} = \mu_{v2} = \mu_{v3} = \mu_{v4} = \mu$ $r_a := 53 \cdot 10^3 \Omega$ $r_{a.v1} = r_{a.v2} = r_{a.v3} = r_{a.v4} = r_a$ $C_{g.c.83} := 1.65 \cdot 10^{-12} F$ $C_{ga83} := 1.6 \cdot 10^{-12} F$ $C_{ac83} := 0.33 \cdot 10^{-12} F$

local feedback versions (RIAA)

page 2

15.6.1.2 **Component figures:** $R0 := 1 \cdot 10^3 \Omega$ $R_{1a} := 52.3 \cdot 10^{3} \Omega$ $R1b := 475 \cdot 10^{3} \Omega$ $R3 := 1 \cdot 10^3 \Omega$ $R2 := 100\Omega$ $R6 \coloneqq 1000 \cdot 10^3 \Omega$ $R8 := 1 \cdot 10^3 \Omega$ $R7 := 100 \Omega$ R11 := $75 \cdot 10^3 \Omega$ $R12 := 47.5 \cdot 10^3 \Omega$ $R13 := 0.1\Omega$ $R5_{\Omega C} := 47 \cdot 10^3 \Omega$ $R4_{oc} := 100 \cdot 10^{3} \Omega - R5_{oc}$ $R4_{oc} = 53 \times 10^{3} \Omega$ $R5_{00} \coloneqq 15 \cdot 10^3 \Omega$ $R4_{00} := 100 \cdot 10^{3} \Omega - R5_{00}$ $R4_{00} = 85 \times 10^{3} \Omega$ $R10_{\Omega\Omega} := 47.5 \cdot 10^3 \Omega$ $R9_{0c} := 100 \cdot 10^{3} \Omega - R10_{0c}$ $R9_{0c} = 52.5 \times 10^{3} \Omega$ $R10_{00} := 16.5 \cdot 10^3 \Omega$ $R9_{00} := 100 \cdot 10^{3} \Omega - R10_{00}$ $R9_{00} = 83.5 \times 10^{3} \Omega$ $C_{in} := 2.2 \cdot 10^{-6} F$ $C4 := 22 \cdot 10^{-6} F$ $C1 := 470 \cdot 10^{-9} F$ $C5 := 22 \cdot 10^{-6} F$ $C_{11} = 10.10^{-6} F$ C12 = C11 $C_{stray, 1} := 10 \cdot 10^{-12} F$ $C_{strav,2} := 5 \cdot 10^{-12} F$ $C_{strav,3} := 4 \cdot 10^{-12} F$

15.6.2 Gain calculations

$$\begin{split} & G1_{0c} := -\mu \cdot \frac{\left(\frac{1}{R_{5_{0c}}} + \frac{1}{R_{6}}\right)^{-1}}{r_{a} + \left(\frac{1}{R_{5_{0c}}} + \frac{1}{R_{6}}\right)^{-1} + (1 + \mu) \cdot R3} & G1_{0c} = -22.682 \times 10^{0} \\ & G1_{0o} := -\mu \cdot \frac{\left(\frac{1}{R_{5_{0o}}} + \frac{1}{R_{6}}\right)^{-1}}{r_{a} + \left(\frac{1}{R_{5_{0o}}} + \frac{1}{R_{6}}\right)^{-1}} & G1_{0o} = -22.022 \times 10^{0} \\ & G2_{0c} := -\mu \cdot \frac{R10_{0c}}{r_{a} + R10_{0c} + (1 + \mu) \cdot R8} & G2_{0c} = -23.691 \times 10^{0} \\ & G2_{0o} := -\mu \cdot \frac{R10_{0o}}{r_{a} + R10_{0o}} & G2_{0o} = -23.978 \times 10^{0} \\ & G3 := \mu \cdot \frac{R11}{r_{a,v3,4} + (1 + \mu) \cdot R11} & G3 = 986.778 \times 10^{-3} \end{split}$$



local feedback versions (RIAA)

$$\begin{split} \mathbf{M}_{00}(\mathbf{f}) &\coloneqq \frac{Z2_{1.00}(\mathbf{f})}{R2 + Z2_{1.00}(\mathbf{f})} \\ \mathbf{N}_{00}(\mathbf{f}) &\coloneqq \frac{\left(\frac{1}{R1b} + \frac{1}{R2 + Z2_{1.00}(\mathbf{f})}\right)^{-1}}{Z1_1(\mathbf{f}) + \left(\frac{1}{R1b} + \frac{1}{R2 + Z2_{1.00}(\mathbf{f})}\right)^{-1}} \\ \mathbf{O}_{00}(\mathbf{f}) &\coloneqq \frac{\left[\frac{1}{R1a} + \frac{1}{\left[Z1_1(\mathbf{f}) + \left(\frac{1}{R1b} + \frac{1}{R2 + Z2_{1.00}(\mathbf{f})}\right)^{-1}\right]\right]^{-1}}{R0 + \left[\frac{1}{R1a} + \frac{1}{\left[Z1_1(\mathbf{f}) + \left(\frac{1}{R1b} + \frac{1}{R2 + Z2_{1.00}(\mathbf{f})}\right)^{-1}\right]\right]^{-1}} \end{split}$$

 $T1_{1.00}(f) := M_{00}(f) \cdot N_{00}(f) \cdot O_{00}(f)$



By varying R_A and by keeping C2 fixed at a certain value we'll get app. the 75µs time constant. The final time constant can be determined with the help of Figure 15.60 :

$$R_{A,oc} := 6.34 \cdot 10^3 \Omega$$
 $C2_{oc} := 1.8 \cdot 10^{-9} F$

local feedback versions (RIAA)

$$\begin{split} & \left(\mathrm{C2}_{00}+\mathrm{C_{12}}_{2\mathrm{c}0,10}\right) \left(\frac{1}{\mathrm{R_{0,a,1,0}}+\mathrm{R_{A,00}}}+\frac{1}{\mathrm{R_{0}}}\right)^{-1} = 75.1 \times 10^{-6} \mathrm{s} \\ & \mathrm{R_{A,00}} = 62.10^{3} \Omega \qquad \mathrm{C2}_{00} = 3.7.10^{-9} \mathrm{F} \\ & \left(\mathrm{C2}_{00}+\mathrm{C_{12}}_{2\mathrm{c}0,01}\right) \left(\frac{1}{\mathrm{R_{0,a,1,00}}+\mathrm{R_{A,00}}}+\frac{1}{\mathrm{R_{0}}}\right)^{-1} = 73.018 \times 10^{-6} \mathrm{s} \\ & \mathrm{Z1}_{2,\infty}(0) = \frac{1}{2\mathrm{j}\pi} \cdot \mathrm{fC}_{0,1,0,101} \qquad \mathrm{Z2}_{2,\infty}(0) = \frac{1}{2\mathrm{j}\pi} \cdot \mathrm{fC}_{1} + \mathrm{R_{A,00}} \\ & \mathrm{Z1}_{2,\infty}(0) = \frac{1}{2\mathrm{j}\pi} \cdot \mathrm{fC}_{0,1,0,101} \qquad \mathrm{Z2}_{2,\infty}(0) = \frac{1}{2\mathrm{j}\pi} \cdot \mathrm{fC}_{1} + \mathrm{R_{A,00}} \\ & \mathrm{Z3}_{2,\infty}(0) = \frac{1}{2\mathrm{j}\pi} \cdot \mathrm{fC}_{1,2,0,0101} \qquad \mathrm{Z4}_{2,\infty}(0) = \left(2\mathrm{j}\pi \cdot \mathrm{fC}_{2,00} + \frac{1}{\mathrm{R_{0}}}\right)^{-1} \\ & \mathrm{Z3}_{2,\infty}(0) = \frac{1}{2\mathrm{j}\pi} \cdot \mathrm{fC}_{1,2,0,0101} \qquad \mathrm{Z4}_{2,\infty}(0) = \left(2\mathrm{j}\pi \cdot \mathrm{fC}_{2,00} + \frac{1}{\mathrm{R_{0}}}\right)^{-1} \\ & \mathrm{Z3}_{2,\infty}(0) = \frac{1}{2\mathrm{j}\pi} \cdot \mathrm{fC}_{1,2,0,0101} \qquad \mathrm{Z4}_{2,\infty}(0) = \left(2\mathrm{j}\pi \cdot \mathrm{fC}_{2,00} + \frac{1}{\mathrm{R_{0}}}\right)^{-1} \\ & \mathrm{T2}_{1,\infty,r}(0) = \frac{\left[\frac{1}{\mathrm{Z1}_{2,\infty}(0)} + \frac{1}{\mathrm{Z2}_{2,\infty}(0) + \left(\frac{1}{\mathrm{Z4}_{2,\infty}(0)} + \frac{1}{\mathrm{Z3}_{2,\infty}(0)}\right)^{-1}\right]^{-1} \\ & \mathrm{T2}_{1,\infty,r}(0) = \frac{\left[\frac{1}{\mathrm{Z1}_{2,\infty}(0)} + \frac{1}{\mathrm{Z2}_{2,\infty}(0) + \left(\frac{1}{\mathrm{Z4}_{2,\infty}(0)} + \frac{1}{\mathrm{Z3}_{2,\infty}(0)}\right)^{-1}\right]^{-1} \\ & \mathrm{T2}_{1,\infty,r}(0) = \frac{\left[\frac{1}{\mathrm{Z1}_{2,\infty}(0)} + \frac{1}{\mathrm{Z1}_{2,\infty}(0)} + \frac{1}{\mathrm{Z2}_{2,\infty}(0) + \left(\frac{1}{\mathrm{Z4}_{2,\infty}(0) + \frac{1}{\mathrm{Z3}_{2,\infty}(0)}\right)^{-1}\right]^{-1} \\ & \mathrm{T2}_{1,\infty,r}(0) = \frac{\left[\frac{1}{\mathrm{Z1}_{2,\infty}(0)} + \frac{1}{\mathrm{Z1}_{2,\infty}(0)}\right]^{-1} \\ & \mathrm{T2}_{2,\infty,r}(0) = \frac{\left(\frac{1}{\mathrm{Z4}_{2,\infty}(0)} + \frac{1}{\mathrm{R7}+\mathrm{Z3}_{2,\infty}(0)}\right)^{-1} \\ & \mathrm{T2}_{2,\infty,r}(0) = \frac{\left(\frac{1}{\mathrm{Z4}_{2,\infty}(0)} + \frac{1}{\mathrm{R7}+\mathrm{Z3}_{2,\infty}(0)}\right)^{-1} \\ & \mathrm{T2}_{2,\infty,r}(0) = \frac{\left(\frac{1}{\mathrm{Z4}_{2,\infty}(0)} + \frac{1}{\mathrm{R7}+\mathrm{Z3}_{2,\infty}(0)}\right)^{-1} \\ & \mathrm{R0}_{2,0,0}(0) = \frac{1}{\mathrm{Z2}_{2,\infty}(0) + \left(\frac{1}{\mathrm{Z4}_{2,\infty}(0)} + \frac{1}{\mathrm{R7}+\mathrm{Z3}_{2,\infty}(0)}\right)^{-1} \\ & \mathrm{R0}_{2,0,0}(0) = \frac{1}{\mathrm{R0}_{2,0}(0) +$$



$$R_{o.a.2.00} \coloneqq \left[\frac{1}{R10_{00}} + \frac{1}{r_{a} + (1 + \mu)R8} \right]^{-1} \qquad R_{o.a.2.00} = 14.913 \times 10^{3} \Omega$$

$$C_{i.3.tot} \coloneqq C_{g.a.83} + C_{stray.3} + (1 - |G3|) \cdot C_{g.c.83} \qquad C_{i.3.tot} = 5.622 \times 10^{-12} F$$

$$C_{o.2.0c.tot} \coloneqq C_{a.c.83} + C_{g.a.83} \qquad C_{o.2.0c.tot} = 1.93 \times 10^{-12} F$$

 $C_{o.2.oo.tot} \coloneqq C_{o.2.oc.tot}$

By varying R_B and keeping C3 and R_C fixed at certain values we'll get app. the time constants 318 μs and 3180 μs . The final time constants can be determined with the help of Figure 15.60 :

$$\begin{split} & R_{B,oc} \coloneqq 249 \cdot 10^{3} \Omega + 0.825 \cdot 10^{3} \Omega & R_{C} \coloneqq 31.6 \cdot 10^{3} \Omega + 200\Omega & C3 \coloneqq 10 \cdot 10^{-9} F \\ & R_{B,oo} \coloneqq 270 \cdot 10^{3} \Omega + 1.3 \cdot 10^{3} \Omega & C3 \cdot R_{C} = 318 \times 10^{-6} s \\ & C3 \cdot (R_{B,oe} + R_{C} + R_{o,a,2,oe}) = 3.18 \times 10^{-3} s \\ & C3 \cdot (R_{B,oo} + R_{C} + R_{o,a,2,oe}) = 3.18 \times 10^{-3} s \\ & Z1_{3,oe}(f) \coloneqq \frac{1}{2j \cdot \pi \cdot fC_{0,2,oe,tot}} & Z2_{3}(f) \coloneqq \frac{1}{2j \cdot \pi \cdot fC_{1,3,tot}} \\ & Z1_{3,oo}(f) \coloneqq \frac{1}{2j \cdot \pi \cdot fC_{0,2,oe,tot}} & Z2_{3}(f) \coloneqq \frac{1}{2j \cdot \pi \cdot fC_{1,3,tot}} \\ & Z3_{3}(f) \coloneqq R_{C} + \frac{1}{2j \cdot \pi \cdot fC_{1,3,tot}} \\ & Z3_{3}(f) \coloneqq R_{C} + \frac{1}{2j \cdot \pi \cdot fC_{1,3,tot}} \\ & Z3_{3}(f) \coloneqq R_{C} + \frac{1}{2j \cdot \pi \cdot fC_{1,3,tot}} \\ & Z3_{3}(f) \coloneqq V_{Z3,3}(f) \underbrace{\left(\frac{1}{23_{3}(f)} + \frac{1}{R_{3} + Z2_{3}(f)}\right)^{-1}} \\ & V_{Z,1,3}(f) = V_{1,3}(f) \cdot \frac{\left(\frac{1}{2j \cdot \pi \cdot fC_{0,2,tot}} + \left[R_{B} + \left(\frac{1}{Z3_{3}(f)} + \frac{1}{R_{3} + Z2_{3}(f)}\right)^{-1}\right]^{-1}\right]^{-1}}{R_{o,a,2} + \left[2j \cdot \pi \cdot fC_{0,2,tot} + \left[R_{B} + \left(\frac{1}{Z3_{3}(f)} + \frac{1}{R_{3} + Z2_{3}(f)}\right)^{-1}\right]^{-1}\right]^{-1} \end{split}$$









MCD Worksheet XV-3 local feedback versions (RIAA)

15.6.4 Total gains B_{xv.rtot}(f) of both pre-amp versions



15.5.5 Deviation $D_{xv,r}(f)$ from the exact RIAA transfer $R_0(f)$:

$$B_{oc.r.tot.dif.e}(f) := B_{oc.r.tot.e}(f) - B_{oc.r.tot.e}(10^{3} Hz)$$

 $B_{oo.r.tot.dif.e}(f) := B_{oo.r.tot.e}(f) - B_{oo.r.tot.e}(10^{3} Hz)$



Figure 15.59 RIAA transfers ref. 0dB/1kHz



Figure 15.60 Deviations from the exact RIAA transfer

MCD Worksheet XV-3 local feedback versions (RIAA)



Figure 15.61 Input impedances of the two versions

15.6.7 Final remarks:

- 15.6.7.1 Varying f_{opt} will lead to drastic changes in the low frequency range of the B $_{oor}(f)$ plot shown in Figure 15.60
- $\begin{array}{ll} 15.6.7.2 & \mbox{To compensate the losses of the passive networks between V1 ... 3 gains B_{oc} and B_{oo} must be set > 500. Trimming of $R5$, 10 will lead to gains of $+34dB of $B_{oc.r.tot.e}(f)$ and $B_{oo.r.tot.e}(f)$ shown in Figure 15.58 } \end{array}$
- 15.6.7.3 To get lowest deviation from the exact RIAA transfer only R_A and R_B need trimming assumed that R_C and C2, C3 got fixed values that were guessed with the respective formulae given in my book "The Sound of Silence"

Given is a selection of data sheet characteristic charts of valves used in the example calculations. As long as there exist no other sources (like in the solid state world) to simulate valves for calculation purposes these types of charts are the only sources to get the valve constants at certain plate-cathode voltages.

	EU	US	valves with equal data but heater differences	
16.1	E188C ²	7308	ECC88 ³ 6DJ8 E88CC ⁴ 6922 PCC88 ⁵ 7DJ8 UCC88 ⁶	CCa
16.2	EC92	6AB4		
16.3	ECC83	12AX7	6AX7	

¹ Data concerning valve related capacitances are not given in this chapter because they can easily be found in valve data hand books like eg. "Röhren Taschentabelle" (valve pocket table), Franzis-Verlag 1963, Munich, Germany,

or in the internet: "http://frank.pocnet.net/sheetsE1.html" heater voltage and current: 6.3V, 325 mA 2

³ heater voltage and current: 6.3V, 365 mA

⁴ heater voltage and current: 6.3V, 300 mA

⁵ heater voltage and current: 7.0V, 300 mA

⁶

heater voltage and current: 21.0V, 100 mA
16.1 E188CC / 7308 ⁷



Figure 16.2 E188CC / 7308 valve constants vs. plate current at 150V plate-cathode voltage

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 $^{^{7}}$ characteristic charts taken from the 1968 Philips Data Handbook on Electronic Components and Materials; S=g_m, R_i=r_a



Figure 16.3 E188CC / 7308 grid voltage vs. plate current and plate-cathode voltage





Figure 16.5 EC92 / 6AB4 grid voltage vs. plate current and plate-cathode voltage

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characteristic charts taken from the 1956 General Electric data sheet



Figure 16.6 ECC83 / 12AX7 valve constants vs. plate current at 100V plate-cathode voltage



Figure 16.7 ECC83 / 12AX7 valve constants vs. plate current at 250V plate-cathode voltage

⁹ characteristic charts taken from the 1968 MAZDA-BELVU data sheet



Figure 16.8 ECC83 / 12AX7 grid voltage vs. plate current and plate-cathode voltage

- 17.1 Abbreviations
- 17.2 Subscripts
- 17.3 List of figures
- 17.4 Index
- 17.5 Epilogue

17.1 Abbreviations:

А	= auxiliary term of a function or equation
А	= example version of Chapter 15
AC	= alternating current, stands also for small signal
AIK	= Aikido gain stage
amp	= amplifier
atan	= arctan in MCD
В	= bandwidth
В	= auxiliary term of a function or equation
В	= example version of Chapter 15
BAL	= balanced gain stage
B _{20k}	= in a bandwidth of 20 Hz 20 kHz = audio band
CFx	= type of cathode follower
С	= capacitance
Cg.a	= capacitance between grid and plate
C _{g.c}	= capacitance between grid and cathode
C _{a.c}	= capacitance between plate and cathode
Ci	= input capacitance
Cin	= i/p capacitor that keeps DC voltage from the previous stage off the
	gate
Ci.tot	= total input capacitance
Co	= output capacitance
Cout	= o/p capacitor that keeps DC voltage off R_L
C _{stray}	= stray capacitances
CAS	= cascode amp stage
CCF	= cascaded cathode follower
CF	= cathode follower
CM	= Miller capacitance
CMRR	= common mode rejection ratio
CCS	= common cathode stage
CCS+Cc	= common cathode stage with cathode AC grounded
CGS	= common grid stage
CSi	= current sink
CSo	= current source
DC	= direct current
deg	= degrees
DS	= data sheet(s)
EX	= example
f	= page plus the following one
(f)	= a frequency dependent function (eg. $T(f)$)
ff	= page plus following ones
g _{m.t}	= triode's mutual conductance (t = triode's specific indication)
G	= gain factor of a gain stage
Gen	= Generator
hp	= high-pass

i	= AC current
ia	= anode or plate AC current
i _c	= cathode AC current
i/p	= input
Ī	= DC current
Im	= imaginary component of an equation
k	= kilo decimal point of a resistor, eg. $5k62 = 5.62 k\Omega$
lp	= low-pass
M	= Mega decimal point of a resistor, eg. $5M62 = 5.62 M\Omega$
М	= auxiliary term of a function or equation
MCD	= MathCad
MM	= Moving Magnet cartridge
n	= nano decimal point of a capacitance, eg. $22n1 = 22.1nF$
N	= auxiliary term of a function or equation
o/n	
0	= auxiliary term of a function or equation
n	= nico decimal point of a capacitance eq. $22n1 = 22.1nF$
P	= auxiliary term of a function or equation
PAR	= valves in paralleled operation
PEN	= pentode
0	= auxiliary term of a function or equation
v r	= plate or anode resistance (= triode's internal resistance)
r a.t	= cathode resistance (= triode's internal resistance)
rot	= rule of thumb
r	= riid input resistance (= triode's internal resistance)
D	= grid input resistance (= triode s internal resistance)
К D	= desimal point of a resistor, eq. 5P62 = 5.62 O
К D	= decinital point of a resistor, eg. $5RO2 = 5.02.52$
К D	- auxiliary term of a function of equation
к _а р	- plate loading resistor
κ _c Do	= real component of an equation
ле D	- real component of an equation
К _{i.c}	- cathode input resistance
К _{0.а} р	- plate output resistance
К _{0.0}	- canode output resistance
K _g	= bias resistance for the grid = grid resistor
K _{gg}	= oscillation prevention resistor at the grid
K _L	= gain stage load resistance = input resistance of next stage
(R_L)	= a R_L dependent function (eg. $G(R_L)$)
K _S	= source impedance
SKPP	= shunt regulated push-pull gain stage
I	= transfer function
1808	= The Sound of Silence (ISBN $9/8-3-540-76883-8$)
V	= AC voltage
V	= DC voltage
V _{a.t}	= DC voltage between plate and ground $(0V)$ -level
$V_{ax.t}$	= DC voltage between plate and cathode in a multi (x) valve
	arrangement
V _{c.t}	= DC voltage between cathode and ground $(0V)$ -level
V _{g.t}	= DC voltage between grid and ground $(0V)$ -level
V _{gx.t}	= DC voltage between grid and ground $(0V)$ -level in a multi (x) valve
	arrangement or between grid and cathode as specifically indicated in the
	respective illustration
Vx	= valve number x
V _{a.c}	= AC voltage between plate and cathode = plate-cathode AC voltage

V _{g.c}	= AC voltage between grid and cathode = grid-cathode AC voltage
V _{R.c}	= AC voltage across R_c
Vi	= AC input voltage of the gain stage
Vo	= AC output voltage of gain stage
V_{cc}	= positive gain stage DC supply voltage
V _{ee}	= negative gain stage DC supply voltage
Vx	= valve x
\mathbf{v}_0	= idle voltage of a source (0=zero)
WCF	= White cathode follower
μ	= micro decimal point of a capacitance, eg. $22\mu 1 = 22.1\mu F$
μ_t	= triode gain (assumption: plate loading resistance R _a is infinite high
μ-F	$= \mu$ -follower gain stage
Ζ	= impedance
Z _{i.c}	= cathode input impedance of the gain stage
Z _{i.g}	= grid input impedance of the gain stage
Z _{o.a.eff}	= effective plate output impedance of gain stage
Z _{o.c.eff}	= effective cathode output impedance of gain stage
φ	= phase angle in rad (in MCD)
φ/deg	= phase angle in degrees (in MCD)

17.2 Subscripts:

а	= anode = plate
a.c	= anode/plate-cathode
aik	= Aikido gain stage
app	= approximation, approximated
b	= bypassed
b	= balanced operation
c	= cathode
cas	= cascode amp
c.t	= cathode of a specific triode t
cc	= positive
cc	= overall feedback plus local feedback around each valve
ccf	= cascoded cathode follower
cf	= cathode follower
cfl	= cf simple version
cf2	= cf improved version
co	= overall feedback plus no local feedback for V2 only
e	= logarithmic expression (e.g. $H_e = 20\log(H)$)
ee	= negative
eff	= effective
g	= for grid bias purposes
gg	= oscillation prevention component via grid
g.a	= grid-plate
g.c	= grid-cathode
gx	= grid of valve x in a multi valve $(x = 1 n)$ arrangement
g1	= grid 1 of pentode
g2	= grid 2 of pentode
g3	= grid 3 of pentode
hi	= high-Z (current source or sink)
i	= in
in	= in
i.t	= i/p of a specific triode t
lo	= low-Z (current source or sink)
L	= load
m	= mutual
n	= new
n	= n times
0	= out
o.a	= plate or anode o/p
oc	= no overall feedback plus local feedback for V1 and V2
0.C	= cathode o/p
00	= no overall feedback plus no local feedback for V1 and V2
opt	= optimal
o.t	= o/p of a specific triode t
out	= out
р	= peak
р	= pentode
par	= parallel operation
r	= RIAA equalized
rot	= rule of thumb

R	= resistor
red	= reduce, reduced
srpp	= SRPP gain stage
stray	= stray capacitance
S	= source
t	= stands for triode
tot	= total
u	= un-bypassed
u	= unbalanced operation
μ.F	$= \mu$ -Follower gain stage
VX	= valve number x (Vx)
wcf	= White cathode follower
0	= source voltage number 0
1	= one (times)
2	= two (times)
20k	= 20Hz 20 kHz
83	= short form identification for ECC83 / 12AX7 in calculations
92	= short form identification for EC92 / 6AB4 in calculations
188	= short form identification for E188CC / 7308 in calculations
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17.5 Epilogue

The whole thing started after I've finished writing my book¹ on noise in audio pre-amps in September 2007. I tried to calculate the noise of a moving magnet RIAA gain stage that is based on the SRPP concept, developed 1969 by Mr Anzai from Japan. His recommendation to take a ECC81 / 12AT7 as the first stage valve was not followed by Elektor Electronics in their 1993 book on high-end audio². Their proposed solution for the first valve was a ECC83 / 12AX7. This triggered my intention to find out the difference - especially on noise. To calculate the noise of these two-stage SRPP designs we need to know the gains of the stages as well as the loss of the RIAA networks.

I discovered that the gain formulae I could find in many sources (books, internet, magazines, etc. - my own university papers got teared to pieces long time ago) where not satisfying enough to calculate things with the precision I wanted to get. Most descriptions were too complicate. Or they were rather distorted and hidden in a lot of hobby blah-blah. Or they offered too many simplifications. In addition, many formulae where simply wrong and I couldn't find a source that offers the broad range of triode gain stage possibilities on one spot - in a manner I was dreaming of. No source gave easy to handle formulae to calculate transfer functions - from input source to output load - of complete gain stages covering only one or several valves in a sequence.

Finally, for my own purposes, I decided to start to develop all formulae that are capable to describe the behaviour of many different triode gain stages in a way that makes calculation life for me - and later on for the audio enthusiast, developer and / or - not only young - engineer much more easy - with the help of a mathematical software and the respective worksheets, thus, virtually producing a kind of simulation approach. And, most important of all my efforts, one should be able to follow the derivation course. Despite the many subscripts and abbreviations one should get a better understanding of the whole matter. The credo I was following up became: "calculate first and do the roundings not before the end".

But I must point out that the calculation examples I'm presenting on MathCad worksheets are examples to show one possible calculation path only! They do not represent the top result of all development efforts one could imagine. It will be the task of the user to find out the best results by eg. changing the circuit variables and bias data - on a strictly own development basis.

Coming back to the results of my comparative SRPP calculations: from a noise point of view the Signal-to-Noise-Ratio (SN) of the ECC81 / 12AT7 1st stage approach is approximately 2dB better in a 20Hz ... 20kHz frequency band than the ECC83 / 12AX7 solution. It was calculated with a 1k input load and with A-weighting. A second calculation with a Shure V15 V MM cartridge as the input load ended up with nearly no difference in SN, hence, for low impedance cartridges the ECC81 / 12AT7 input device is the better solution. This is also valid for input

¹ TSOS (see Section 17.1)

² "High-end Audio Equipment", Elektor Electronics UK, 1993, ISBN 0-905-70540-8

step-up transformers for MC cartridge puposes. The price to pay is the nearly doubled 1st stage DC current, meanwhile the overall gain doesn't change significantly.

At the end of this reference book I wish all readers a lot of fun with triodes - despite the nasty math! Old-timers never die! They reflect a certain emotional value and for many connoisseurs the sound of eg. a 1976 "911" triggers the equivalent emotions like the soft glow of valves in the background of a living room and the right music that enchant ones ears.

I guess that's what many valve enthusiasts are living for!