Hi Fi Component

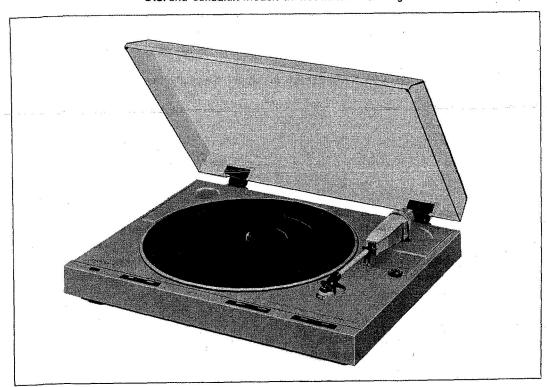
DENON

SERVICE MANUAL

FULLY AUTOMATIC DIRECT DRIVE TURNTABLE SYSTEM

MODEL DP-21F SERIES

U.S. and Canadian models do not include cartridge.



NIPPON COLUMBIA CO., LTD.

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WARNING:

1. Component parts

Parts marked with \triangle and/or shading in this service manual have special characteristics important to safety. Be sure to use the specified parts for replacement.

2. Leakage current

Before returning the appliance to customer, test the leakage current when the power plug is connected. Use a calibrated (with an error of not more than 5%) leakage current tester and measure the leakage current from any exposed metal to the earth ground. Reverse the power plug polarity and test the above again.

Any current measured MUST NOT EXCEED 0.5 miliamps. Corrective measure must be taken if it exceeds the limit.

FEATURES

Silent, fully automatic operations with the use of a microprocessor controlled contactless servo tonearm.

An innovative microprocessor controlled, contactless servo tonearm ensures safe, easy to use automatic operations with little loss in sound quality.

Low mass straight arm

This arm is fully capable of maximizing the performance of high compliance cartridges with outstanding tracing ability. Even with the newest, high grade records, its tracing ability is outstanding.

DENON Quartz

The turntable speed is controlled by the "DENON Quartz" which is the combination of the "High Precision Magnetic Pulse Detection Method", the most sophisticated method of FG detection, and the "Quartz Lock".

SPECIFICATIONS

Phonomotor section

Drive system: Servo controlled direct drive

33-1/3, 45 rpm Turntable speeds:

Wow & flutter: Below 0.02% wrms (servo system)

Below 0.03% wrms (JIS)

S/N ratio: Over 75 dB (DIN-B)

Rise time: Normal speed within 2 seconds (at 33-1/3 rpm)

Platter: Aluminum die-cast; 300 mm diameter

Motor: Linear drive motor

Speed control system: Speed servo by frequency detection, phase servo control

Speed deviation: Below 0.002%

Load characteristics: 0% (80 g stylus force; outermost groove)

General

Power supply: $50\sim60$ Hz, Voltage is shown on rating label

Power consumption: 7 W

Dimensions: $105 \times 434 \times 360 \text{ mm} (H \times W \times D)$

Weight: Approximately 5 kg

Tonearm section

Arm type: Dynamically balance, semi-integrated straight arm

Effective length: 220 mm Overhang: 16 mm

Within 3° Tracking error:

Automatic mechanism: Electronically controlled, fully automatic Adjustable stylus force range: $0\sim3.0 \text{ g (1 scale}=0.1 \text{ g)}$

Suitable cartridge weight range: Approximately 4.0~6.0 g (including screws, nuts)

Cartridge section (Only for those models with attached cartridge)

DL-60

Moving magnet (MM) Type:

Output voltage: 2.5 mV 20~30 kHz Frequency response:

Stylus force: 1.8±0.3 g

Above specifications and outward appearance may be altered in future for improvement

U.S. and Canadian models do not include cartridge.

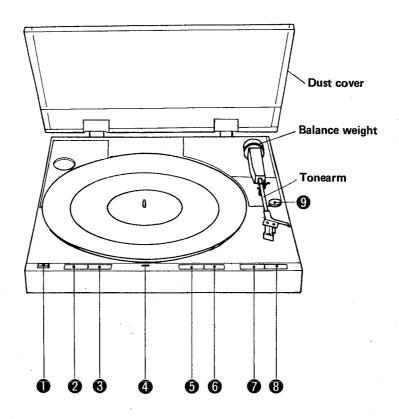
BLOCK DIAGRAM

Rotational speed detection Lock indication Rotation Power amplifier Reference voltage control Phonomotor F/V output Magnetic polarity Compare/ Motor control detection Amplify microprocessor Memorize IR3T02 Magnetic polarity Speed selector P.D. output detection (33/45)Stop control Rotation Power amplifier control Xtal 4.5MHz Start/stop command Stylus force Memorize adjustment Repeat o Arm up/down command Speed detection Memorize Vertical motor (Lifter motor) Power Compare/ amplifier amplify Stop o Reference voltage 17/30 Position Accelaration detection input Arm control Size selector (30/17) microprocessor IR3T03 Compare/ amplify Accelaration output Memorize Compare/ amplify Rest/end detection killer Anti skate command Horizontal voltage End Mid-point detection detection Amplify Anti skate voltage Reference voltage Compare/ amplify Horizontal motor Power amplifier

Note: indicates an analog switch.

Speed detection

PART NAMES AND FUNCTION



1 POWER (Power switch)

This switch turns the power supply on (—) and off (—). When turning the power off, always return the tonearm to the arm rest and hold it in place with the clamp.

(2) SIZE (Record size selector switch)

3 SPEED (Speed selector switch)

(4) LOCK (Lock indicator)

When the power is turned on, the lamp will light up. During play, the lamp will flicker until the proper turntable speed is reached. Once the proper speed is obtained, the lamp will, again, stay lit.

5 REPEAT (Repeat switch)

When playing the records repeatedly, switch it on (lamp lit).

(6) ARM LIFTER (Arm lifter switch)

This switch is used to raise and lower the arm during play or when playing the records manually. The lamp is lit when arm is up.

(7) START (Start switch)

Press this switch when starting the records automatically.

8 STOP (Stop switch)

Press this switch when stopping the record during play.

(9) STYLUS FORCE (Stylus force adjustment knob)

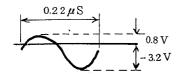
This knob is used to adjust the stylus force.

EXPLANATION OF THE MICROPROCESSOR

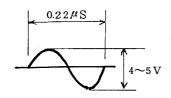
Motor Control IC . . . IR3T02 (at standard revolution of 33 rpm)

The numbers on the left hand side indicates the terminal number.

2. 4.5MHz OSC



3. 4.5MHz OSC



4. rpm selector

H: 45 rpm L: 33 rpm

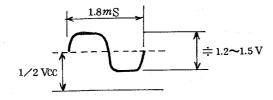
5. power source input

Vcc: 5V ±0.5V

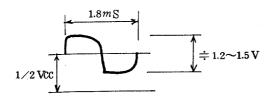
6. FG I bypass terminal

E6 ≒ ½Vcc

7. FG I lowpass terminal



8. FG I output



9. FG I inverse input

The gain set element is connected. E9 = ½Vcc

10. FG I non-inverse input

 $10 \text{mVpp} \sim 100 \text{mVpp}$ E10 = $\frac{1}{2} \text{Vcc}$

14. ground terminal

15. F/V output

slower than normal revolution: 2 \sim 4.5V

normal revolution: ≒ 2V

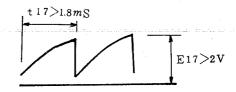
faster than normal revolution: 0 ~ 2V

16. F/V hold terminal

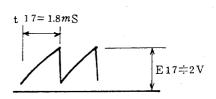
same as terminal 15

17. F/V triangular wave

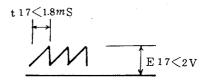
slower than normal revolution



normal revolution



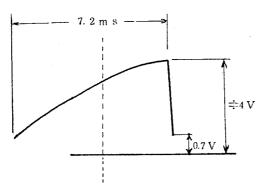
faster than normal revolution



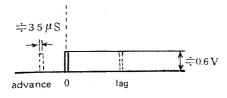
18. timing pulse width-set terminal

E18 = 0.6V

19. PD triangular wave



20. sample pulse monitor terminal



Monitor for phase-lock:

Waveforms at Pins 19 and 20 to be observed with a dual trace oscilloscope when GND is common. (See "Lock adjustment.")

21 PD hold terminal

slow phase: $2 \sim 4V$ normal phase: = 2Vadvanced phase: $1 \sim 3V$

22. PD output

same as terminal 21

23. Lock detector time set terminal

during lock: 0.6V lock disengaged: 0V

25. Revolution detector

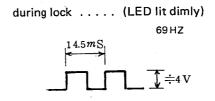
during revolution: ________ = 4V

stop: 0V

26. START/STOP terminal

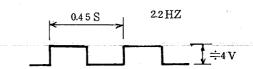
H → START L → STOP

28. Lock indicator



stop (LED lit)

during transition . . (LED flashes)



Arm Control IC IR3T03

The numbers on the left side indicates the terminal number of the IR3T03.

1. Accelaration input

Except for the matching range of the lead-in detector (E7 \leq | \pm 0.6V |), it will recognize the situation and control the acceleration during automatic tonearm operation.

2. Accelaration output

E1 \leq | ± 2.37 V ± 0.1 V | open (will not control the acceleration within the matching range)

 $E1 \ge |\pm 2.3V \pm 0.1V|$ $E2 = \pm 3.95V$

-3.95V: will accelarate toward the inside from rest.

+3.95V: will accelarate toward rest from the inside.

3. UP/DOWN selection of the arm lifter

When E9 is H, the control output for lifting the arm will be made at E3 = -Vcc.

When E9 is L, the control output for lowering the arm will be made at E3 = +Vcc.

4. Detection of the rest position

 $E4 \le -2.64V$ will be recognized as the arm being at rest.

5. Detection of the END position

When E5 \geq 2.64V, it will be recognized to be within the END detection range.

 $E5 \ge 2.64V$ when the stylus tip nears the last sections of the sound groove.

6. End control

Whithin the END detection range of 5 (above), (E5 \geq 2.64V), the arm will be returned by the END control when E6 \geq 0.23V.

 $\rm E5 \ge 0.23V$ when the stylus tip moves into the lead-out groove and the arm moves fast.

7. Matching input

 $\rm E7 \le |\pm 0.6 V|$ will be recognized as the match range for lead-in.

8. Drive output

Connect to GND.

9. UP control output

When the lifter is in the UP position during automatic arm operations or when the UP signal is sent by pressing the arm lifter button, pin 9 will be at H level.

E9H ≒ 4V

E9L≒0V

10. DOWN time constant

To ensure that the arm is lowered completely before proceeding to the next movement, a resistor between pins 9 and 10 and a capacitor on pin 10 has a preset discharge time constant which is somewhat longer than the time required for the arm to be lowered. Thus, when pin 9 becomes L (E9L = 0V), and the fixed amount of time elapses, the arm will be recognized to be DOWN as soon as E10 < 2V.

11. ANT (Anti-skating) control

When E10 \leq 2V, then E11 = -4V will be the control output needed for the anti-skating to be engaged.

When E10 \geq 2V, then E11 = +4V will be the control output needed for the anti-skating to be disengaged.

12. Negative power source

Supplies -5V.

14. SUB (substratum)

To prevent any interference from the inner elements of the LSI, the substratum terminal is connected to the unregulated side of the negative power source, since it has the lowest electric potential.

15. GND

Standard zero electric potential is the GND.

17. Return control

When the stop command is given, or when the repeat is disengaged and the END is detected (E6 \geq 0.23V), a control signal output (E17H > 4V) is made to return the arm to rest.

E17H > 4V

E17L: release

18. Horizontal drive control

When the arm is in resting position, or when the arn reaches the lead-in position during automatic play, and comes into the matching range (E7 \leq | \pm 0.6V |), a control signal output (E18H \doteq 4V) is made to stop the horizontal motion of the arm.

19. Initial set

This is the preparation time setting terminal when the power source is turned on. The resistor in the LSI and the outer capacitor will set the charge time constant and carry out the initial set.

20. LCTD (Located) time constant

The LSI and its outer circuits will set the LCTD time constant to improve the detection accuracy of the lead-in position and the arm rest position.

E20H = 1.2V A few moments after the arm reaches

the range of detection, in other words, after the set LCTD time constant elapses, it will become H level, where it is memorized immediately and then

reset to the L level.

E20L = 0V Before and after detection, it will

become L level.

21. Turntable (T/T) Drive Control

E21L = 0V the turntable stops

E21H release the turntable rotates

(refer to the operational explanations for pin 22)

22. Turntable (T/T) Start Position

This terminal establishes the turntable start position. The turntable will start when the arm separates from the arm rest and pin 22 is released, under manual and auto modes.

23. Start

Will start automatically at the GND level.

24. Auto stop

Will stop automatically at the GND level.

25. Lifter

Will raise the lifter automatically at the GND level.

26. Repeat

Will engage the repeat automatically at the GND level.

27. UP SW

An UP time constant circuit is used so that when the lifter is in the UP condition, this terminal is released and becomes H level; and at other times, it becomes GND level. With this unit, the arm will start to move approximately two seconds after the UP command.

28. Positive power supply

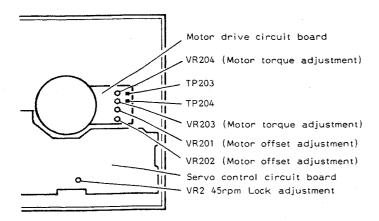
Supplies +5V.

ADJUSTMENT METHOD

* Prepare a two-channel oscilloscope for the measuring instrument.

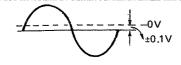
Adjusting the Phonomotor Section

* Measure, using the wrapping terminal number 8 of the motor drive circuit board as the ground reference point when adjusting the motor OP amp. voltage offset and the motor torque.



1. Adjusting the motor amp. offset voltage

- 1) Fix the tonearm to the arm rest and connect the oscilloscope to TP 203 and 204.
- 2) Rotating the turntable by hand, adjust the center of amplitude at TP 203 to 0 \pm 0.1V by turning VR 201.
- 3) Following the preceding directions adjust to 0 \pm 0.1V by turning VR 202 for TP 204 .



2. Adjusting the motor torque

- 1) Leave the oscilloscope connections as they were for the motor OP amp. voltage offset adjustments.
- Take the turntable off the main body; move the tonearm close to the speed detection head and rotate the phonomotor at a fast speed.

(Note) Be very cautious as not to damage the cartridge during this procedure.

- 3) For T.P. 203, rotate VR 203 and adjust to 15VP-P±0.5V.
- 4) For T.P. 204 , rotate VR 204 and adjust to $15VP-P\pm0.5V$.



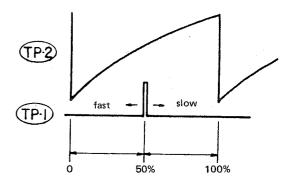
3. Adjusting the head gap

Adjust, so that the gap between the turntable magnetic coating surface and the detection head is 0.18 mm.

4. Lock adjustments for 45 rpm

From hereafter, the earth reference point of the measuring instrument should be connected to wrapping terminal 35 of the servo control circuit board.

- Connect the two-channel oscilloscope to T.P. 1 and T.P. 2.
- 2) Set the speed selector to 45 rpm.
- 3) Take the arm off the arm rest and move it toward the turntable to rotate the phonomotor.
- 4) Adjust VR2 so that the pulse form T.P. 1 is positioned to 50% of the triangular wave length from T.P. 2.

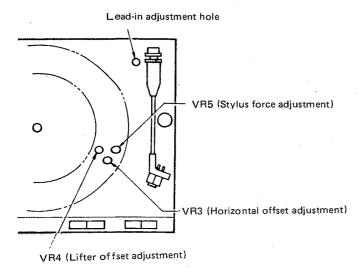


5. Lock adjustments for 33 rpm

- 1) Connect the oscilloscope in the same manner as the 45 rpm lock adjustments. Set the speed selector to 33 rpm.
- 2) Make sure that the sampling pulse positions between 40% and 80% of the triangular wave length.

Note: Phase lock position for 33rpm is fixed (relative to 45rpm) by R113 (metal film resistor).

Adjusting the Arm Control Section



1. Adjusting the horizontal OP amp. offset voltage

- 1) Fix the tonearm to the armrest and connect the oscilloscope to T.P. 3.
- 2) Set the lifter switch to the UP condition.
- 3) Turn VR3 and adjust to 0V±0.01V.

2. Adjusting the lifter OP amp. offset voltage

- Fix the tonearm to the armrest and connect the oscilloscope to T.P. 4.
- 2) Set the lifter switch to the DOWN condition.
- 3) Turn VR4 and adjust to -1V±0.1V.

3. Adjusting the stylus force

- 1) Turn the power supply switch OFF.
- Take the arm off the armrest. Rotate the balance weight so that the tonearm becomes parallel to the turntable surface when let go.
- 3) Return the arm to the armrest and turn the power supply switch ON.
- 4) Wait five seconds after the arm has lowered. Place the cartridge stylus tip onto a stylus force guage and set the stylus force adjustment knob to 1.5 g.
 - (Note) At this time, the stylus tip height should be adjusted so that it is about the same height as during play.
- 5) Turn VR5 and adjust, so that the stylus force guage reads 1.5 g.

4. Adjusting the 30 cm lead-in position

Place a 30 cm record on the turntable and set the record size selector switch to "30".
 (Note) Keep the bottom cover closed.

- 2) Move the arm so that the stylus tip is at approximately the 30 cm lead-in position. Insert a small flat-headed screwdriver into the lead-in adjustment hole; move the arm back and forth and fit the screw driver into the groove of the cam inside gently.
- After turning the screwdriver, pull it out. Press the start switch and adjust so that the stylus position stops at the 30 cm lead-in position.

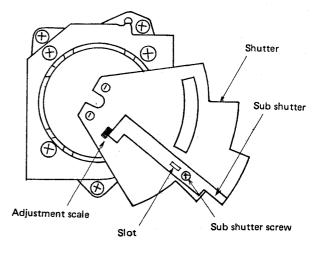
(Note) The 30 cm lead-in adjustments cannot be performed unless the stylus tip position is approximately in the 30 cm lead-in position. In addition, if the screwdriver is left inserted, the arm will not move.

5. Adjusting the 17 cm lead-in position

Adjust as necessary, such as when parts of the sensor section have been replaced.

However, the following procedures should only be used when a discrepancy is found for the 17 cm lead-in position, after the 30 cm lead-in position has been adjusted.

- 1) Set the record size selector to 17 cm.
- 2) By continuously pressing the start switch, the arm will move over and stop. At this time, check now many millimeters, toward the inside or outside, the stylus tip deviates from the required 17 cm lead-in position.
- 3) Take off the bottom cover of the cabinet and check the adjustment scale position of the shutter. (One adjustment scale corresponds to a stylus tip movement of 5 mm.)
- 4) Untighten the screw holding the sub shutter and place a small screwdriver into the slot of the shutter. When the stylus position is toward the inside, compared to the required position, move the sub shutter toward the right of the scale; when the stylus position is toward the outside, move the sub shutter toward the left. When completed, tentatively tighten the screw holding the sub shutter.
- After the adjustments are made, press the start switch and check whether or not the stylus stops at the 17 cm lead-in position.
- If the stylus stops at the required position, then tighten the sub shutter screw.



PARTS LIST OF EXPLODED VIEW

-				
	Ref. No.	Part No.	Part Name	Remarks
ı	1	4730356017	3×12 CBRŢS	
	2	4751106042	WASHER	
-	3	1048066018	INSULATOR ASS'Y	
l	4	4730306038	3×12 CBRTS (1)	
	5	1058085005	BOTTOM COVER ASS'Y	
١	6	4370306012	3×12 CBRTS (1)	
l	7	KU-440	SERVO CONTROL UNIT	81A, 81B, 81C,
ı			•	81 D, 81 E, 81 F
	8	1138136104	SIZE KNOB	
	9.	1138135105	SPEED KNOB	
	10	1138137103	REPEAT KNOB	
	11	1138138102	LIFTER KNOB	
	12	1138139101	START KNOB	·
	13	1138140103	STOP KNOB	
	14	4618113000	SPRING PLATE	
	15	4713808003	3×25 CBS	
	16	4731806003	3×20 CPTS (1)	
	17	FG-286	MOTOR ASS'Y	
	18	4730304014	3×8 CBRTS (1)	
	19	4418846001	WASHER	
	20	4418814305	HEAD SUPPORT	
	21	3918423006	MAGNETIC HEAD	
	22	4700009019	3x6 CPS W	
	23	2118024002	V16V15KB502	
	24	1128088000	VOLUME KNOB	İ
	25	1038206503	CABINET	
	25	1038206505	CABINET	E1 only
	26	4418863000	FRICTION SHEET	
	27	4730205016	2.6×10 CPTS (1)	
A	28	2129180003	PUSH SWITCH	
‹ـــــــــــــــــــــــــــــــــــــ	29	1138146000	KNOB	
	30	2033642103	OUTPUT CORD ASS'Y	
A	31	2062002031	AC CORD	
		2062024006	ACCORD WITH LABEL	EKonly
	32	4730309019	3×16 CBRTS (1)	
	33	4620027003	RUBBER BUSH	
Λ	34	2030150009	WIRE CONNECTOR	E2, EK
$\overline{\Lambda}$	35	2339059005	POWER TRANS	E2, EK
<u></u>		2339060007	POWER TRANS	E1.only
	36	4711810019	2×3 CPS	
	37	4338172004	SUB SHUTTER	
	38	4712303017	3×6 CFS	
	39	4711303018	3x6 CPS	
	40	4751003006	3 W	
	41	4438545201	COLLAR	
	42	4338177300	SHUTTER	
	43	4638225004	SPRING	
	44	3418025205	MAGNET ASS'Y	
	45	4761003009	3 E-RING	
	46	4751005004	4 W	
	47	3158451003	FRICTION WASHER	
	48	4248019202	ADJUST CAM	
	49	2398013118	COIL ASS'Y	
	50	4338181008	YOKE (A) GENE ASS'Y	
	51	4744102037	3x3 SS	
	52	4418815100	ARM PLATE	
	53	3158744105	BALANCE WEIGHT	
	54	3158742000	MAIN BODY ASS'Y	
	55	3158545113	ARM REST	
	56	FSC00903	SHELL SCREW	
	57	DL-60	CARTRIDGE UNIT	
	58	FPU0379J	SHELL WASHER	
	59	FSC0089	SHELL NUT	
	60	4628023009	BUSHING	
	61	1468139208	DUST COVER	
	62	4018041015	HINGE	
			<u> </u>	

	Ref. No.	Part No.	Part Name	Remarks
	63	4218288005	RUBBER SHEET	
	64	4218217209	RECORDED TURNTABLE	
	65	3158751004	SHELL SCREW	
⚠	66	2129185008	SLIDE SWITCH	E1 only
	67	4730205016	2.6×10 CPTS (1)	E1 only
\triangle	68	2033667007	PLUG ADAPTOR	E1 only

CARTON CASE GROUP

Ref. No.	Part No.	Part Name	Remarks
	5018252104	CARTON CASE ASS'Y	
	5028074000	PACKING ASS'Y	'
	5058092010	LAMINATE ENVELOPE	
ļ	5058017011	ENVELOPE	60x260x0.03t
	5058006006	ENVELOPE	60x100x0.03t
	5058023018	ENVELOPE	350×640×0.05t

ACCESSORIES GROUP

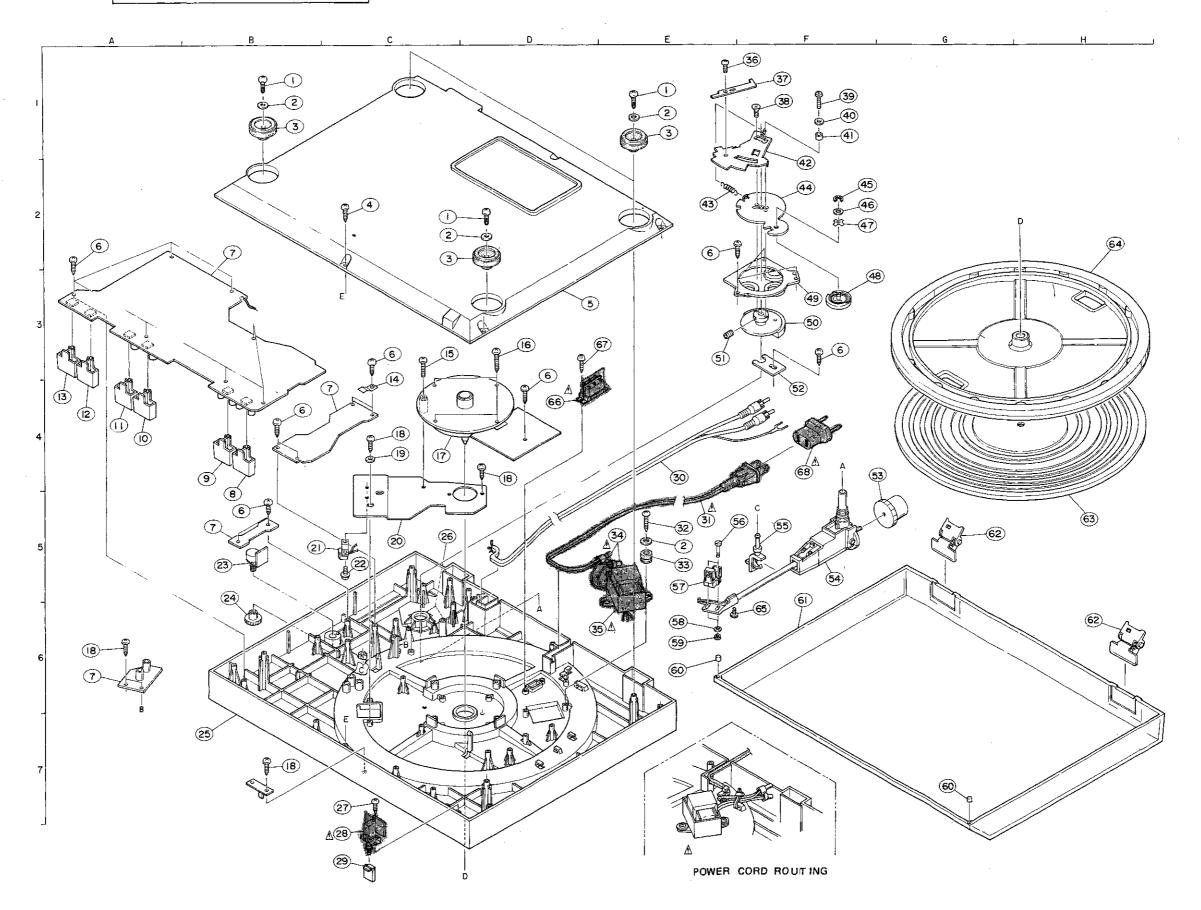
Ref. No.	Part No.	Part Name	Remarks
63	5298006002 4218288005 5118215106	45 ADAPTOR RUBBER SHEET INSTRUCTION MANUAL	
68	3158752003 2033667007	ALIGNMENT PLATE PLUG ADAPTOR	E1 only

WARNING:

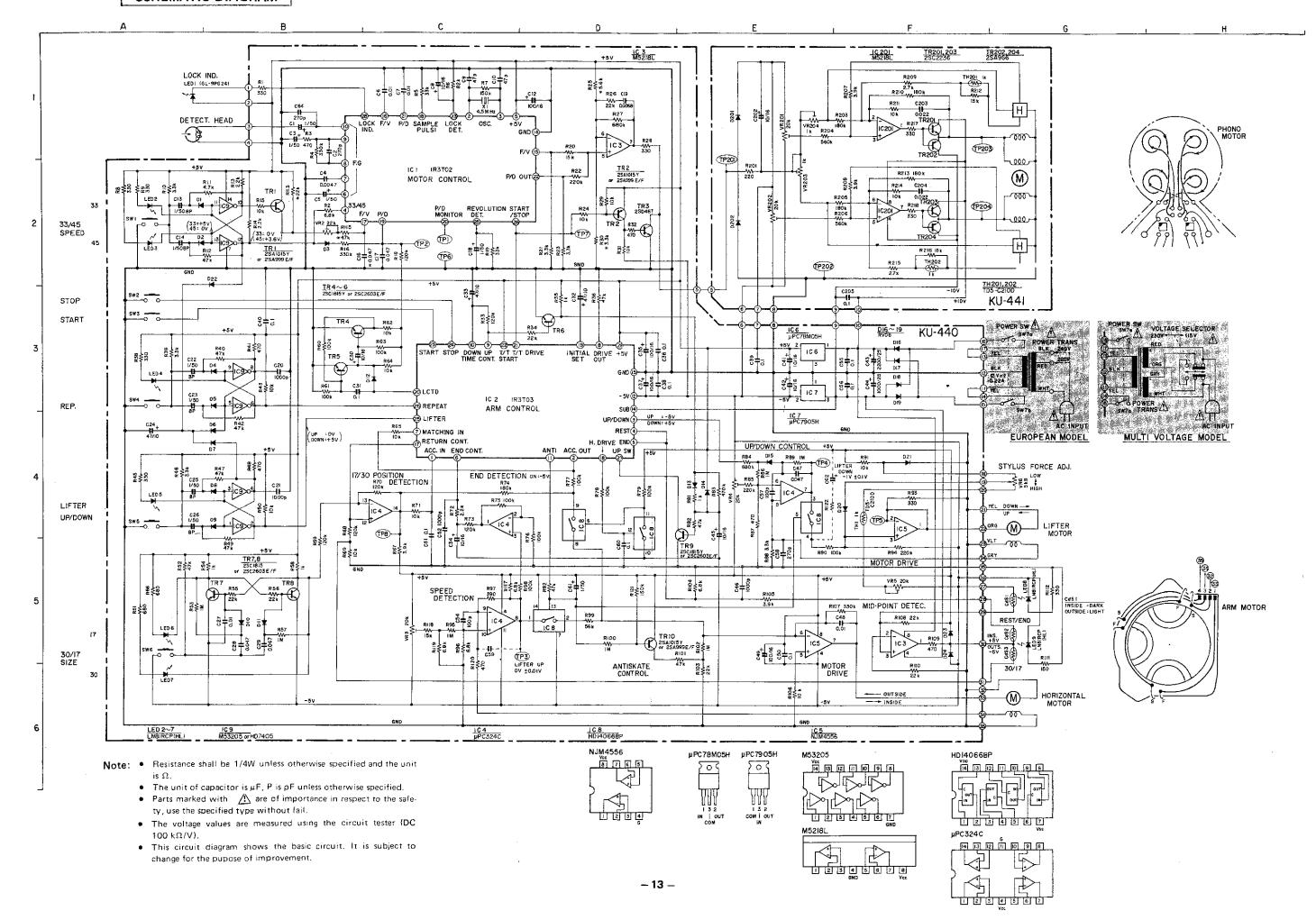
Parts marked with \triangle and/or shading have special characteristics important to safety. Be sure to use the specified parts for replacement.

Remark symbols in the parts list refer to the following countries and areas.

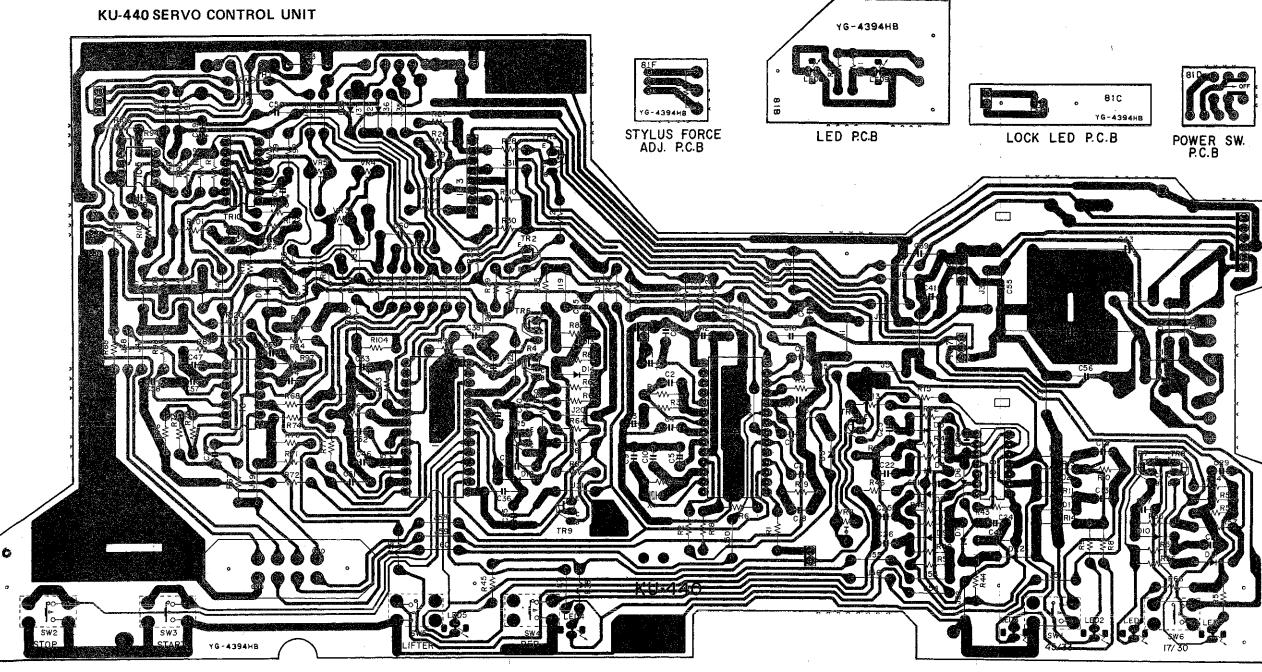
EK: United KingdomE1: Multiple voltage modelE2: European continent

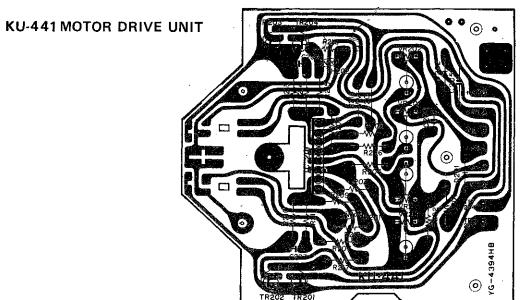


SCHEMATIC DIAGRAM

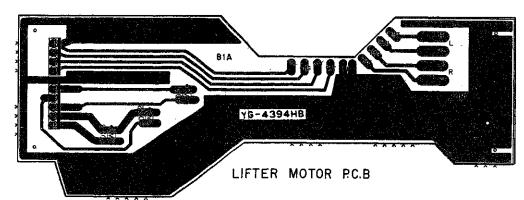


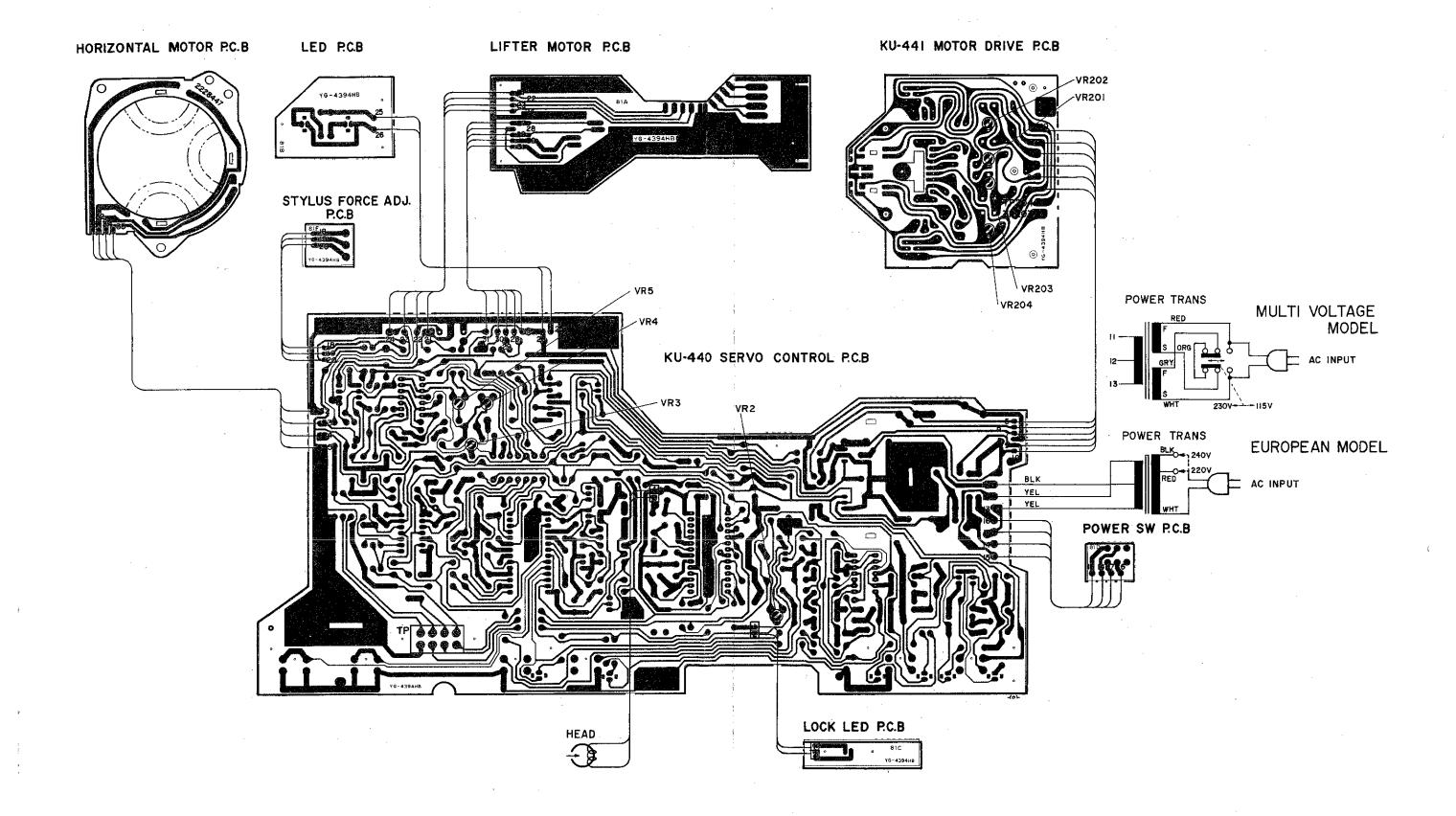
PRINTED CIRCUIT BOARD





MOTOR DRIVE P.C.B





PARTS LIST OF P. C. BOARD

KU-440 SERVO CONTROL UNIT

38~40 50,51,55, 56,60 C27	
ICS	
IC1	
IC2	
IC2	n
IC3	
IC4	
IC5	
IC6	
IC7	
TR1,2,10 2710102005 2SA1015(Y) TR4~9 2730198002 2SC1815(Y) TR3 2740038000 2SD467(C) D1~15	
TRA~9	
TR3	
D1~15	
D1~15 20~24 D16~19 2760237001 RV06 RV06 THERMISTER LED1 3939140009 LED (GL-9PG24) LED LED2~9 3939041001 LED (LN81RCP(HL)) LED (GS 2, 3 3939053002 CDS	
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CAPACITOR GROUP C31, 36	1/4
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C12, 35, 37 2544136001 CE04W1C101= 100µF	
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18,61	
Film	35\
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C6,7,48 2551072006 CQ93M1H103K 0.01μF 5	35\ 50\
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22, 23, 25	35\ 50\ 50\ 50\
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	35\ 50\ 50\ 50\ 50\
26,28,29 47	35\ 50\ 50\ 50\ 50\

Ref. No.	Part No.	Part Name	Remarks	
OTHER PARTS GROUP				
X1 '	4178028101 3998025000	HEAT SINK CRYSTAL (4.5M)	For IC6, 7	
SW1~6 SW7	2129130008 2129180003	PUSH SWITCH PUSH SWITCH	FUNCTION POWER	
	4438568107	LED HOLDER	For LED2~9	

KU-441 MOTOR DRIVE UNIT

Ref. No.	Part No.	Part Name	Remarks			
SEMICONDU	SEMICONDUCTOR GROUP					
IC201	2630189001	M5218L	IC			
TR202, 204	2710105002	2SA966(Y)				
TR 201, 203	2730201009	2SC2236(Y)				
D201, 202	2760049901	IS2076				
	2760303016	HL-300C	Hall detector			
TH201,202	2760311008	THERMISTOR	TD5-C210D			
RESISTOR G	RESISTOR GROUP					
		·	Variable resistor			
VR203, 204	2116000031	V08PB102	1ΚΩ			
VR201,202	2116000072	V08PB203	20ΚΩ			
CAPACITOR	CAPACITOR GROUP					
			Electrolitic			
C202	2544132005	CE04W1C100=	10µF 16V Film			
C203, 204	2551076002	CQ93M1H223K	0.022µF 50V			

• The carbon resistors rated at 1/4W are not listed herein.